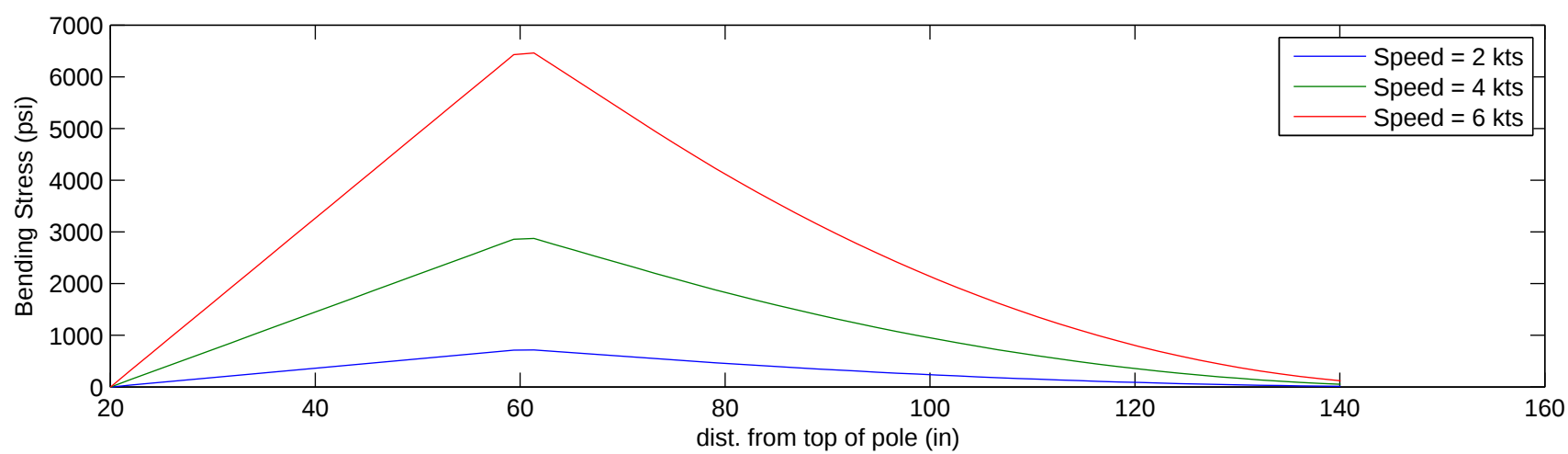
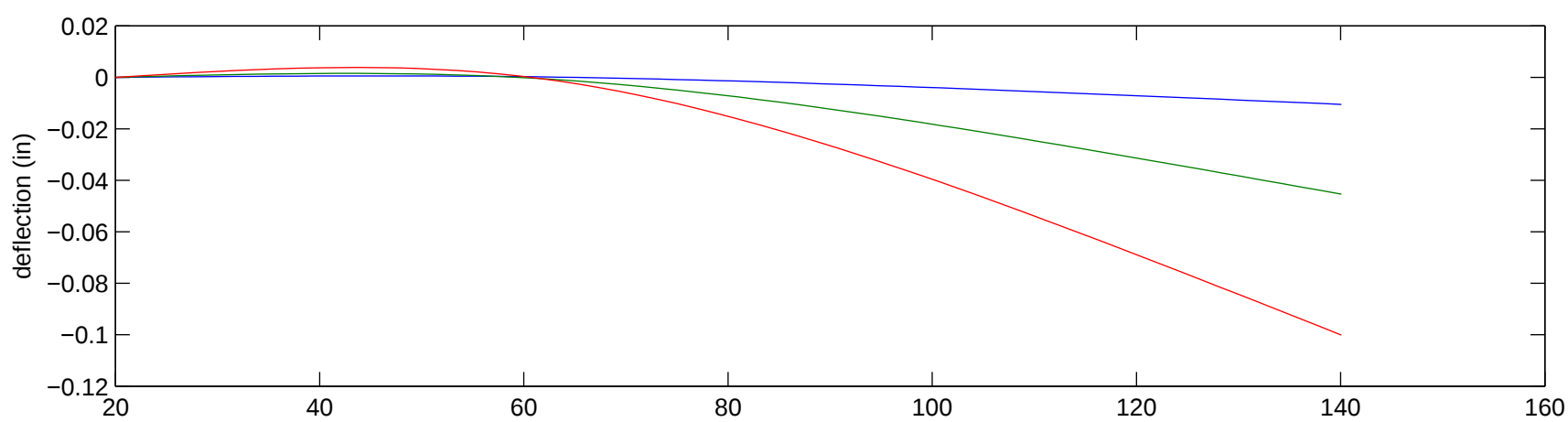
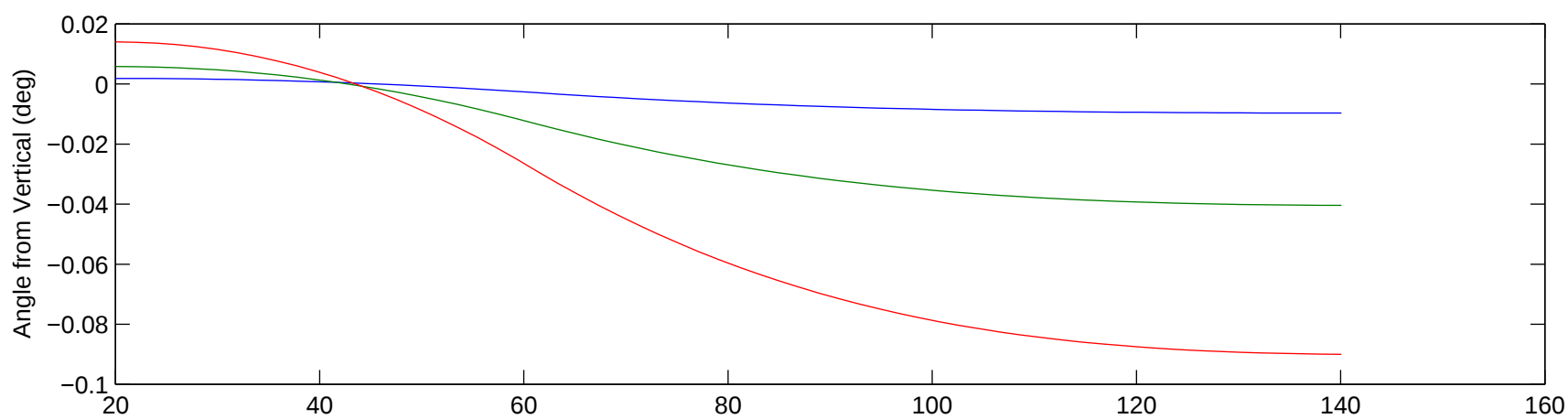
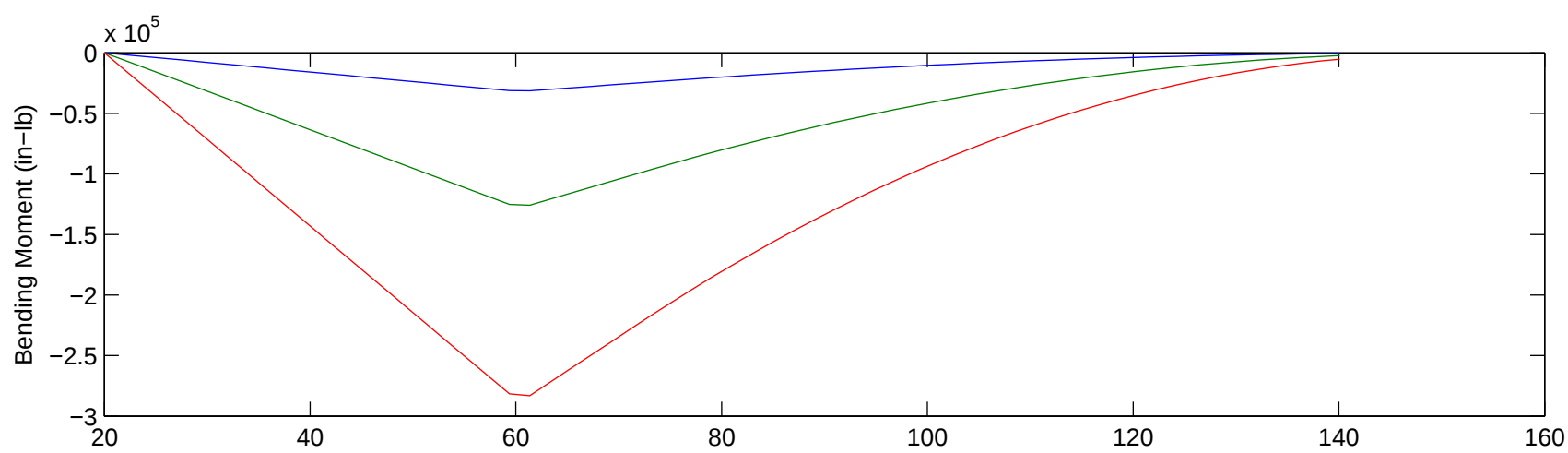
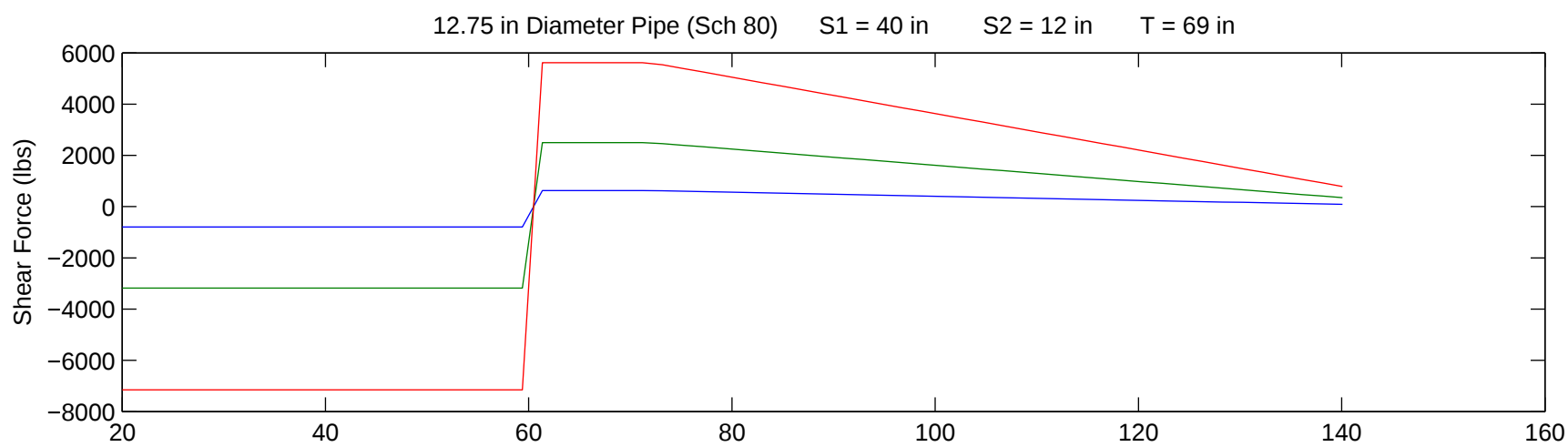
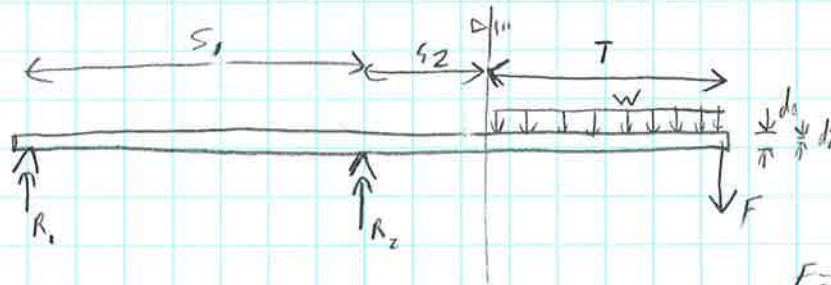




HYDRO PNEUMATIC

$$S_c = \frac{S \cdot d}{L}$$



$$F = C_{p,ph} \cdot \frac{1}{8} \rho u^2 \pi d_t^2 \left\{ \begin{array}{l} \text{TRANSDUCER} \\ \text{MODULUS} \\ \text{AS} \\ \text{SPRING} \end{array} \right.$$

$$w = C_{p,ph} \cdot \frac{1}{2} \rho u^2 d_t^2 \left\{ \frac{F}{L} \right.$$

$$\sum F = 0$$

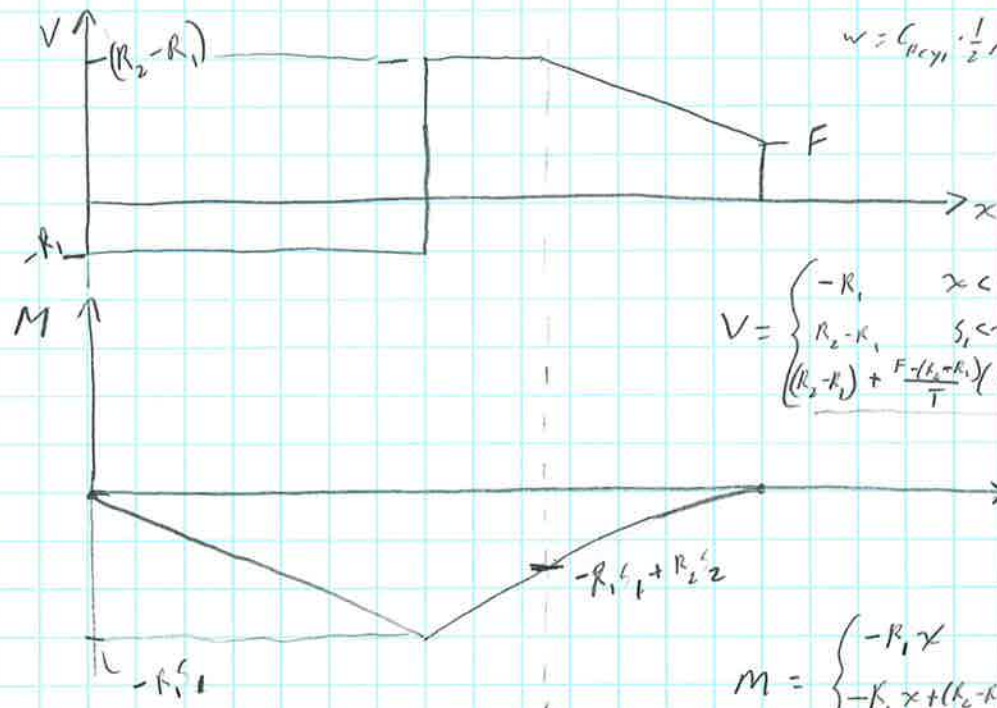
$$R_1 + R_2 - F - wT = 0$$

$$R_1 + R_2 = F + wT$$

$$\sum M = 0$$

$$C_1 R_2 - wT \left[s_1 + s_2 + \frac{T}{2} \right] - F[s_1 + s_2 + T] = 0$$

$$\left\{ \begin{array}{l} R_2 = \frac{1}{s_1} \left[wT \left[s_1 + s_2 + \frac{T}{2} \right] + F[s_1 + s_2 + T] \right] \\ R_1 = F + wT - R_2 \end{array} \right.$$



$$V = \begin{cases} -R_1 & x < s_1 \\ R_2 - R_1 & s_1 < x < (s_1 + s_2) \\ (R_2 - R_1) + \frac{F - (R_2 - R_1)}{T} (x - (s_1 + s_2)) & x > s_1 + s_2 \end{cases}$$

$$M = \begin{cases} -R_1 x & x < s_1 \\ -R_1 x + (R_2 - R_1)(x - s_1) & s_1 < x < s_1 + s_2 \\ -R_1 s_1 + R_2 s_1 + \frac{F - (R_2 - R_1)}{2T} x^2 & x > s_1 + s_2 \end{cases}$$

$$w = C_{p,ph} \cdot \frac{1}{2} \rho u^2 \cdot d_0$$

$$F = C_{p,ph} \cdot \frac{1}{2} \rho u^2 (\pi d_t^2) / 4$$