



LMR16006 SIMPLE SWITCHER® 60 V 0.6 A Buck Regulators With High Efficiency ECO Mode

1 Features

- Ultra Low 28 μ A Standby Current in ECO Mode
- Input Voltage Range 4 V to 60 V
- 1 μ A Shutdown Current
- High Duty Cycle Operation Supported
- Output Current up to 600 mA
- 0.7 MHz and 2.1 MHz Switching Frequency
- Internal Compensation
- High Voltage Enable Input
- Internal Soft Start
- Over Current Protection
- Over Temperature Protection
- Small Overall Solution Size (SOT-6L Package)

2 Applications

- Industrial Distributed Power Systems
- Automotive
- Battery Powered Equipment
- Portable Handheld Instruments
- Portable Media Players

3 Description

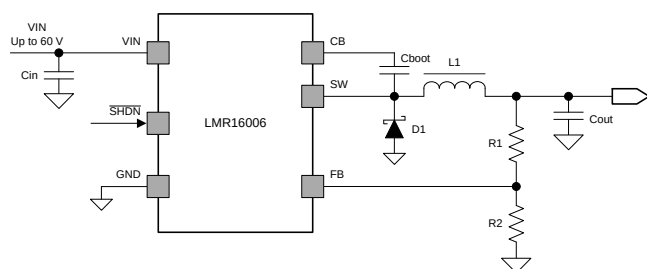
The LMR16006 is a PWM DC/DC buck (step-down) regulator. With a wide input range of 4 V to 60 V, it is suitable for a wide range of application from industrial to automotive for power conditioning from an unregulated source. The regulator's standby current is 28 μ A in ECO mode, which is suitable for battery operating systems. An ultra low 1 μ A shutdown current can further prolong battery life. Operating frequency is fixed at 0.7 MHz (X version) and 2.1 MHz (Y version) allowing the use of small external components while still being able to have low output ripple voltage. Soft-start and compensation circuits are implemented internally, which allows the device to be used with minimized external components. The LMR16006 is optimized for up to 600 mA load currents. It has a 0.765 V typical feedback voltage. The device has built-in protection features such as pulse by pulse current limit, thermal sensing and shutdown due to excessive power dissipation. The LMR16006 is available in a low profile SOT-6L package.

Device Information⁽¹⁾

PART NUMBER	PACKAGE	BODY SIZE
LMR16006	SOT (6)	2.90 mm × 1.60 mm

(1) For all available packages, see the orderable addendum at the end of the datasheet.

4 Simplified Schematic



Efficiency vs Output Current
(f_{SW} = 0.7 MHz, V_{OUT} = 3.3 V)

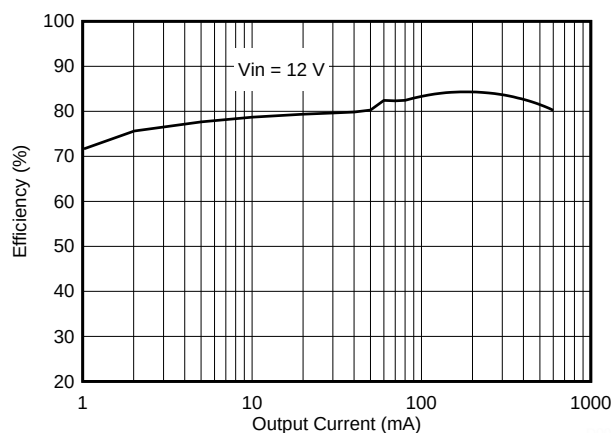


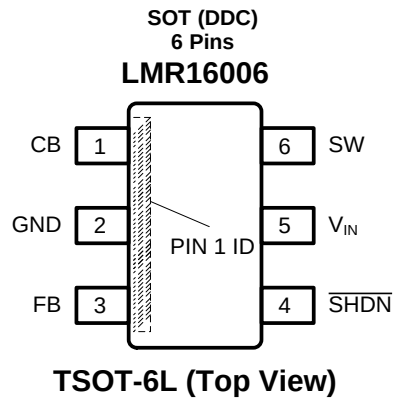
Table of Contents

1 Features	1	8.2 Functional Block Diagram	8
2 Applications	1	8.3 Feature Description	9
3 Description	1	8.4 Device Functional Modes	10
4 Simplified Schematic	1	9 Application and Implementation	11
5 Revision History	2	9.1 Application Information	11
6 Pin Configuration and Functions	3	9.2 Typical Application	11
7 Specifications	4	10 Power Supply Recommendations	16
7.1 Absolute Maximum Ratings	4	11 Layout	16
7.2 Handling Ratings	4	11.1 Layout Guidelines	16
7.3 Recommended Operating Conditions	4	11.2 Layout Example	16
7.4 Thermal Information	4	12 Device and Documentation Support	17
7.5 Electrical Characteristics	5	12.1 Related Documentation	17
7.6 Switching Characteristics	5	12.2 Trademarks	17
7.7 Typical Characteristics	6	12.3 Electrostatic Discharge Caution	17
8 Detailed Description	8	12.4 Glossary	17
8.1 Overview	8	13 Mechanical, Packaging, and Orderable Information	17

5 Revision History

DATE	REVISION	NOTES
October 2014	*	Initial release.

6 Pin Configuration and Functions



Pin Functions

PIN		I/O	DESCRIPTION
NAME	NUMBER		
CB	1	I	Switch FET gate bias voltage. Connect C_{boot} cap between CB and SW.
GND	2	G	Ground connection.
FB	3	I	Feedback Input. Set feedback voltage divider ratio with $V_{OUT} = V_{FB} (1 + (R1/R2))$.
$\overline{SHDN}$	4	I	Enable and disable input (high voltage tolerant). Internal pull-up current source. Pull below 1.25 V to disable. Float to enable. Establish input undervoltage lockout with two resistor divider.
V_{IN}	5	I	Power input voltage pin. Input for internal supply and drain node input for internal high-side MOSFET.
SW	6	O	Switch node. Connect to inductor, diode, and C_{boot} cap.

7 Specifications

7.1 Absolute Maximum Ratings ⁽¹⁾

		MIN	MAX	UNIT
Input Voltages	V _{IN} to GND	-0.3	65	V
	$\overline{\text{SHDN}}$ to GND	-0.3	65	
	FB to GND	-0.3	7	
	CB to SW	-0.3	7	
Output Voltages	SW to GND	-0.3	65	V
	SW to GND less than 30 ns transients	-2	65	
T _J Operation Junction temperature		-40	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

7.2 Handling Ratings

			MIN	MAX	UNIT
T _{stg}	Storage temperature range		-55	165	°C
V _(ESD)	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins ⁽¹⁾		2000	V
		Charged device model (CDM), per JEDEC specification JESD22-C101, all pins ⁽²⁾		500	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted) ⁽¹⁾

		MIN	MAX	UNIT
Buck Regulator	V _{IN}	4	60	V
	CB	4	66	
	CB to SW	-0.3	6	
	SW	-0.3	60	
	FB	0	5.5	
Control	$\overline{\text{SHDN}}$	0	60	
Temperature	Operating junction temperature range, T _J	-40	125	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

7.4 Thermal Information

over operating free-air temperature range (unless otherwise noted)

THERMAL METRIC ⁽¹⁾		SOT (6 PINS)	UNIT
R θ_{JA}	Junction-to-ambient thermal resistance	102	°C/W
R θ_{JCTop}	Junction-to-case (top) thermal resistance	36.9	
R θ_{JB}	Junction-to board characterization parameter	28.4	

- (1) All numbers apply for packages soldered directly onto a 3" x 3" PC board with 2 oz. copper on 4 layers in still air in accordance to JEDEC standards. Thermal resistance varies greatly with layout, copper thickness, number of layers in PCB, power distribution, number of thermal vias, board size, ambient temperature, and air flow.

7.5 Electrical Characteristics

Limits apply over the recommended operating junction temperature (T_J) range of -40°C to $+125^{\circ}\text{C}$, unless otherwise stated. Minimum and Maximum limits are specified through test, design or statistical correlation. Typical values represent the most likely parametric norm at $T_J = 25^{\circ}\text{C}$, and are provided for reference purposes only. Unless otherwise specified, the following conditions apply: $V_{IN} = \overline{\text{SHDN}} = 12\text{V}$

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V _{IN} (Input Power Supply)						
V _{IN}	Operating input voltage		4		60	V
I _{SHDN}	Shutdown supply current	V _{EN} = 0 V		1	3	μA
I _Q	Operating quiescent current (non-switching)	no load, V _{IN} = 12 V		28		μA
UVLO	Undervoltage lockout thresholds	Rising threshold			4	V
		Falling threshold	3			
SHDN						
V _{SHDN_Thre}	Rising $\overline{\text{SHDN}}$ Threshold Voltage		1.05	1.25	1.38	V
I _{SHDN}	Input current	$\overline{\text{SHDN}}$ = 2.3 V		-4.2		μA
		$\overline{\text{SHDN}}$ = 0.9 V		-1		
I _{SHDN_HYS}	Hysteresis current			-3		μA
HIGH-SIDE MOSFET						
R _{DS_ON}	On-resistance	V _{IN} = 12 V, CB to SW = 5.8 V		900		mΩ
VOLTAGE REFERENCE (FB PIN)						
V _{FB}	Feedback voltage		0.747	0.765	0.782	V
CURRENT LIMIT						
I _{LIMIT}	Peak Current limit	V _{IN} = 12 V, T _J = 25°C		1200		mA
				1700		
THERMAL PERFORMANCE						
T _{SHDN} ⁽¹⁾	Thermal shutdown threshold			170		°C
T _{HYS} ⁽¹⁾	Hysteresis			10		°C

(1) Ensured by design

7.6 Switching Characteristics

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
SW (SW PIN)						
f_{SW}	Switching frequency	LMR16006X	595	700	805	kHz
		LMR16006Y	1785	2100	2415	
$T_{\text{ON_MIN}}^{(1)}$	Minimum turn-on time	$f_{\text{SW}} = 2.1\text{ MHz}$		80		ns
D_{MAX}	Maximum duty cycle	LMR16006X		96%		
		LMR16006Y		97%		

(1) Ensured by design.

7.7 Typical Characteristics

Unless otherwise specified the following conditions apply: $V_{IN} = 12\text{ V}$, $f_{SW} = 700\text{ kHz}$, $L1 = 22\text{ }\mu\text{H}$, $C_{out} = 10\text{ }\mu\text{F}$, $T_A = 25^\circ\text{C}$.

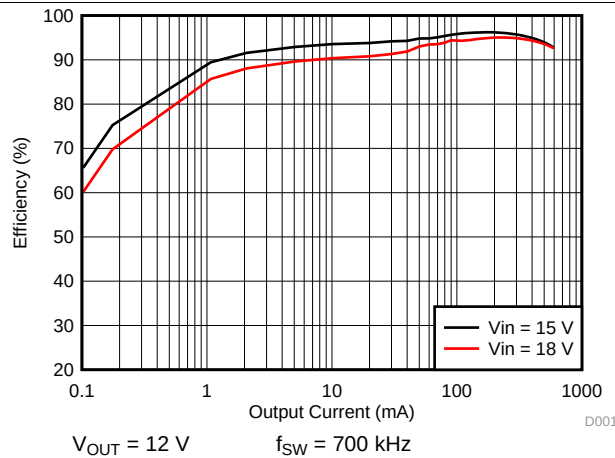


Figure 1. Efficiency vs. Load Current

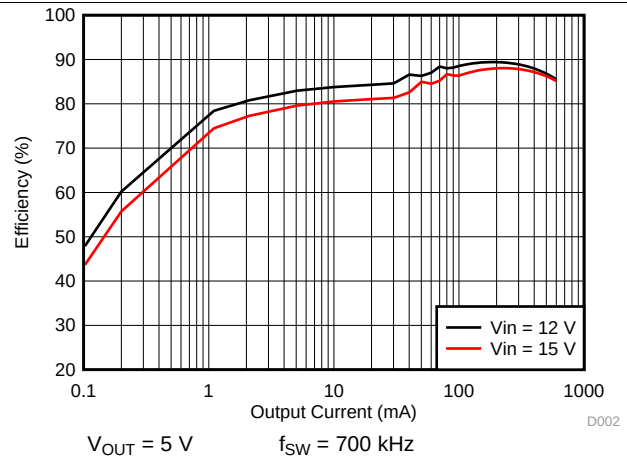


Figure 2. Efficiency vs. Load Current

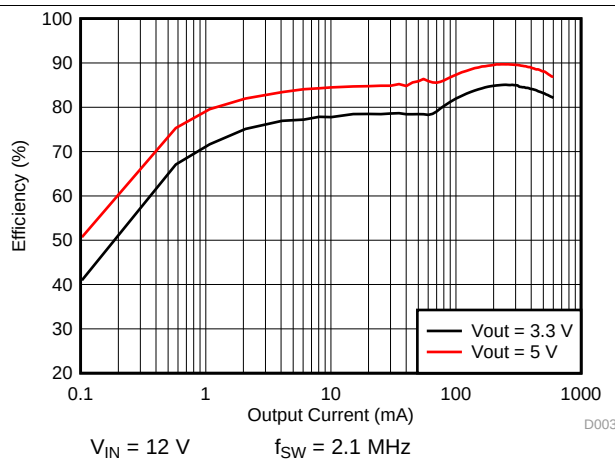


Figure 3. Efficiency vs. Load Current

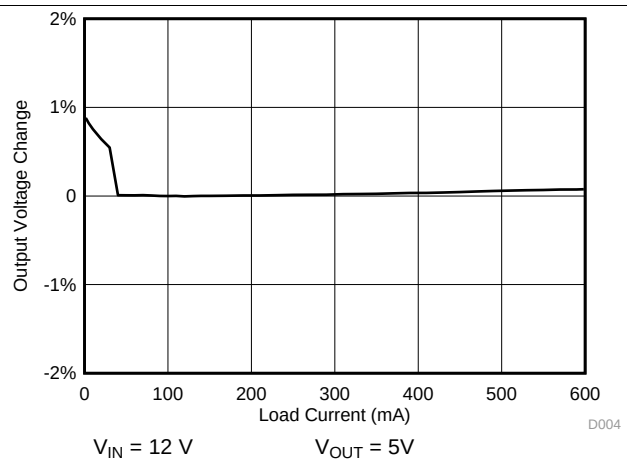


Figure 4. Load Regulation

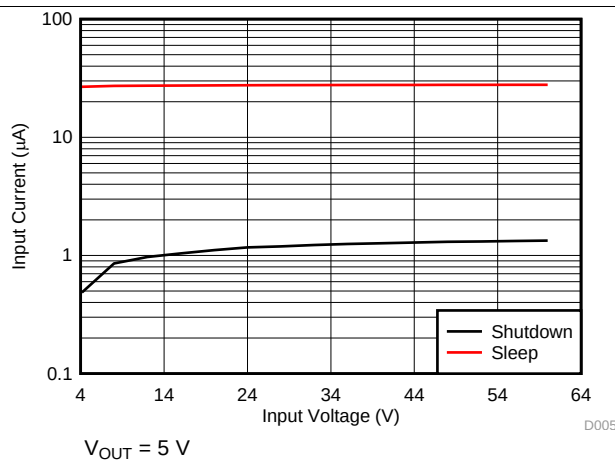


Figure 5. Shut-Down Current and Quiescent Current

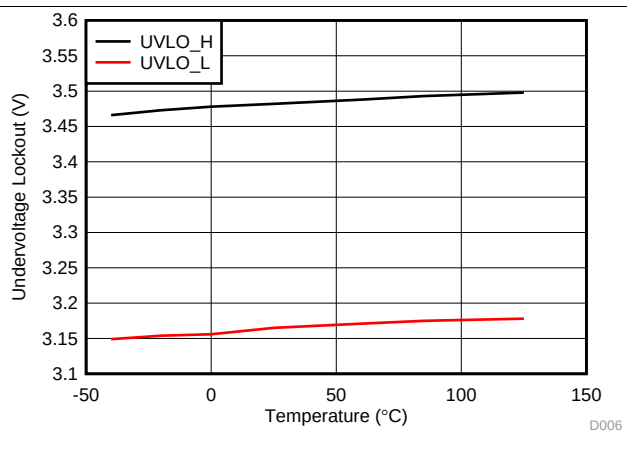


Figure 6. UVLO Threshold

Typical Characteristics (continued)

Unless otherwise specified the following conditions apply: $V_{IN} = 12\text{ V}$, $f_{SW} = 700\text{ kHz}$, $L1 = 22\text{ }\mu\text{H}$, $C_{out} = 10\text{ }\mu\text{F}$, $T_A = 25^\circ\text{C}$.

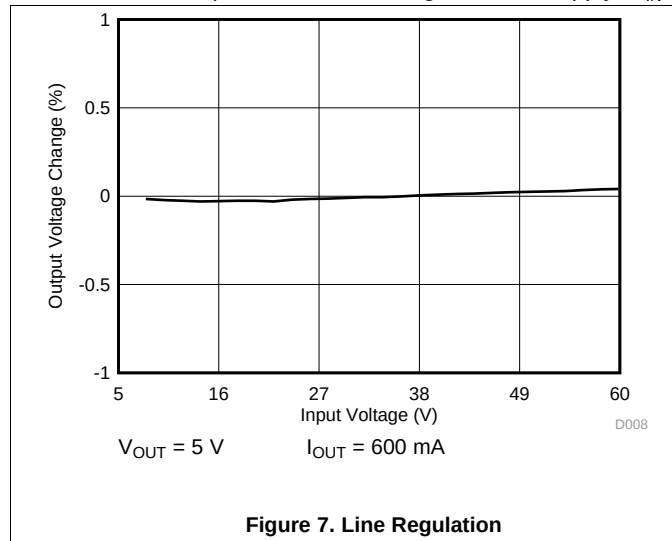


Figure 7. Line Regulation

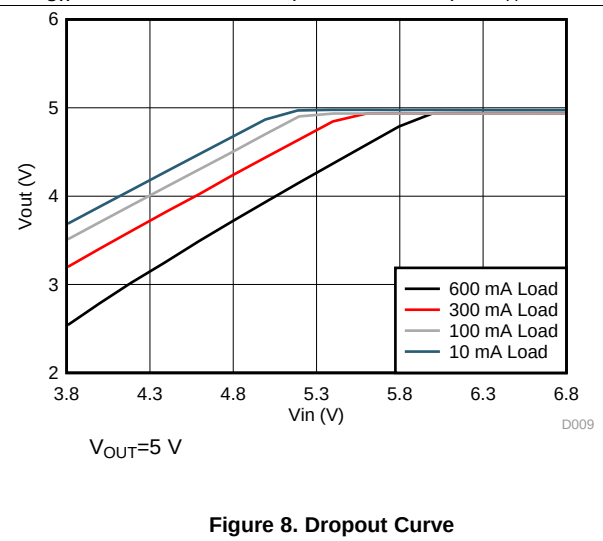


Figure 8. Dropout Curve

8.3 Feature Description

8.3.1 Fixed Frequency PWM Control

The LMR16006 has two fixed frequency options, and it implements peak current mode control. The output voltage is compared through external resistors on the V_{FB} pin to an internal voltage reference by an error amplifier which drives the internal COMP node. An internal oscillator initiates the turn on of the high side power switch. The error amplifier output is compared to the high side power switch current. When the power switch current reaches the level set by the internal COMP voltage, the power switch is turned off. The internal COMP node voltage will increase and decrease as the output current increases and decreases. The device implements a current limit by clamping the COMP node voltage to a maximum level.

8.3.2 Bootstrap Voltage (CB)

The LMR16006 has an integrated boot regulator, and requires a small ceramic capacitor between the CB and SW pins to provide the gate drive voltage for the high side MOSFET. The CB capacitor is refreshed when the high side MOSFET is off and the low side diode conducts. To improve drop out, the LMR16006 is designed to operate at 100% duty cycle as long as the CB to SW pin voltage is greater than 3 V. When the voltage from CB to SW drops below 3 V, the high side MOSFET is turned off using an UVLO circuit which allows the low side diode to conduct and refresh the charge on the CB capacitor. Since the supply current sourced from the CB capacitor is low, the high side MOSFET can remain on for more switching cycles than are required to refresh the capacitor, thus the effective duty cycle of the switching regulator is high. Attention must be taken in maximum duty cycle applications with light load. To ensure SW can be pulled to ground to refresh the CB capacitor, an internal circuit will charge the CB capacitor when the load is light or the device is working in dropout condition.

8.3.3 Output Voltage Setting

The output voltage is set using the feedback pin and a resistor divider connected to the output as shown on the front page schematic. The feedback pin voltage 0.765 V, so the ratio of the feedback resistors sets the output voltage according to the following equation: $V_{OUT} = 0.765 \text{ V} (1 + (R1/R2))$. Typically R2 will be given as 1k Ω - 100 k Ω for a starting value. To solve for R1 given R2 and Vout uses $R1 = R2 ((V_{OUT}/0.765 \text{ V}) - 1)$.

8.3.4 Enable $\overline{\text{SHDN}}$ and VIN Undervoltage Lockout

LMR16006 $\overline{\text{SHDN}}$ pin is a high voltage tolerant input with an internal pull up circuit. The device can be enabled even if the $\overline{\text{SHDN}}$ pin is floating. The regulator can also be turned on using 1.23 V or higher logic signals. If the use of a higher voltage is desired due to system or other constraints, a 100 k Ω or larger resistor is recommended between the applied voltage and the $\overline{\text{SHDN}}$ pin to protect the device. When $\overline{\text{SHDN}}$ is pulled down to 0 V, the chip is turned off and enters the lowest shutdown current mode. In shutdown mode the supply current will be decreased to approximately 1 μA . If the shutdown function is not to be used the $\overline{\text{SHDN}}$ pin may be tied to V_{IN} via 100k Ω resistor. The maximum voltage to the $\overline{\text{SHDN}}$ pin should not exceed 60 V. LMR16006 has an internal UVLO circuit to shutdown the output if the input voltage falls below an internally fixed UVLO threshold level. This ensures that the regulator is not latched into an unknown state during low input voltage conditions. The regulator will power up when the input voltage exceeds the voltage level. If there is a requirement for a higher UVLO voltage, the SHDN can be used to adjust the system UVLO by using external resistors.

8.3.5 Current Limit

The LMR16006 implements current mode control which uses the internal COMP voltage to turn off the high side MOSFET on a cycle-by-cycle basis. Each cycle the switch current and internal COMP voltage are compared, when the peak switch current intersects the COMP voltage, the high side switch is turned off. During overcurrent conditions that pull the output voltage low, the error amplifier will respond by driving the COMP node high, increasing the switch current. The error amplifier output is clamped internally, which functions as a switch current limit.

8.3.6 Overvoltage Transient Protection

The LMR16006 incorporates an overvoltage transient protection (OVTP) circuit to minimize voltage overshoot when recovering from output fault conditions or strong unload transients on power supply designs with low value output capacitance. For example, when the power supply output is overloaded the error amplifier compares the actual output voltage to the internal reference voltage. If the FB pin voltage is lower than the internal reference voltage for a considerable time, the output of the error amplifier will respond by clamping the error amplifier

Feature Description (continued)

output to a high voltage. Thus, requesting the maximum output current. Once the condition is removed, the regulator output rises and the error amplifier output transitions to the steady state duty cycle. In some applications, the power supply output voltage can respond faster than the error amplifier output can respond, this actuality leads to the possibility of an output overshoot. The OVTP feature minimizes the output overshoot, when using a low value output capacitor, by implementing a circuit to compare the FB pin voltage to OVTP threshold which is 108% of the internal voltage reference. If the FB pin voltage is greater than the OVTP threshold, the high side MOSFET is disabled preventing current from flowing to the output and minimizing output overshoot. When the FB voltage drops lower than the OVTP threshold, the high side MOSFET is allowed to turn on at the next clock cycle.

8.3.7 Thermal Shutdown

The device implements an internal thermal shutdown to protect itself if the junction temperature exceeds 170°C(typ). The thermal shutdown forces the device to stop switching when the junction temperature exceeds the thermal trip threshold. Once the junction temperature decreases below 160°C(typ), the device reinitiates the power up sequence.

8.4 Device Functional Modes

8.4.1 Continuous Conduction Mode

The LMR16006 steps the input voltage down to a lower output voltage. In continuous conduction mode (when the inductor current never reaches zero at CCM), the buck regulator operates in two cycles. The power switch is connected between V_{IN} and SW. In the first cycle of operation the transistor is closed and the diode is reverse biased. Energy is collected in the inductor and the load current is supplied by C_{out} and the rising current through the inductor. During the second cycle the transistor is open and the diode is forward biased due to the fact that the inductor current cannot instantaneously change direction. The energy stored in the inductor is transferred to the load and output capacitor. The ratio of these two cycles determines the output voltage. The output voltage is defined approximately as: $D = V_{OUT}/V_{IN}$ and $D' = (1-D)$ where D is the duty cycle of the switch, D and D' will be required for design calculations.

8.4.2 ECO Mode

The LMR16006 operates in ECO mode at light load currents to improve efficiency by reducing switching and gate drive losses. The LMR16006 is designed so that if the output voltage is within regulation and the peak switch current at the end of any switching cycle is below the sleep current threshold, $I_{INDUCTOR} \leq 80$ mA, the device enters ECO mode. For ECO mode operation, the LMR16006 senses peak current, not average or load current, so the load current where the device enters ECO mode is dependent on V_{IN} , V_{OUT} and the output inductor value. When the load current is low and the output voltage is within regulation, the device enters an ECO mode and draws only 28 μ A input quiescent current.

9 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

The LMR16006 is a step down DC-to-DC regulator. It is typically used to convert a higher DC voltage to a lower DC voltage with a maximum output current of 600 mA. The following design procedure can be used to select components for the LMR16006. This section presents a simplified discussion of the design process.

9.2 Typical Application

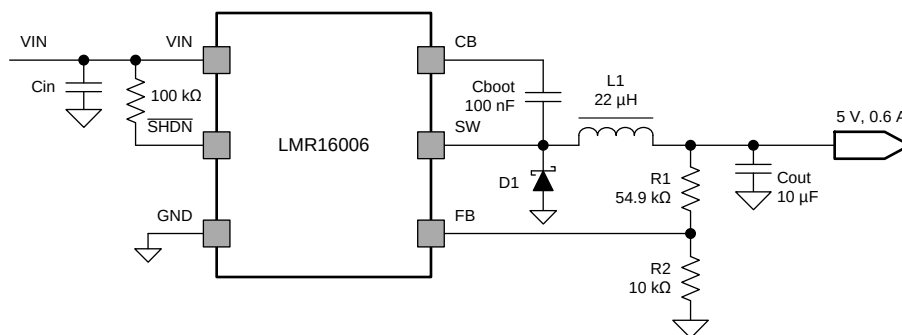


Figure 9. Application Circuit, 5 V Output

9.2.1 Design Requirements

Table 1. Design Example Parameters

Input Voltage, V_{IN}		9 V to 16 V, Typical 12 V
Output Voltage, V_{OUT}		5.0 V $\pm$ 3%
Maximum Output Current I_{O_max}		0.6 A
Minimum Output Current I_{O_min}		0.03 A
Transient Response 0.03 A to 0.6 A		5%
Output Voltage Ripple		1%
Switching Frequency F_{sw}		0.7 MHz
Target during Load Transient	Over Voltage Peak Value	106% of Output Voltage
	Under Voltage Value	91% of Output Voltage

9.2.2 Detailed Design Procedure

This example details the design of a high frequency switching regulator using ceramic output capacitors. A few parameters must be known in order to start the design process. These parameters are typically determined at the system level:

9.2.2.1 Output Inductor Selection

The most critical parameters for the inductor are the inductance, peak current and the DC resistance. The inductance is related to the peak-to-peak inductor ripple current, the input and the output voltages. Since the ripple current increases with the input voltage, the maximum input voltage is always used to determine the inductance. To calculate the minimum value of the output inductor, use [Equation 1](#). K_{IND} is a coefficient that represents the amount of inductor ripple current relative to the maximum output current. A reasonable value is setting the ripple current to be 30%-40% of the DC output current. For this design example, the minimum

inductor value is calculated to be 20.4 μH , and a nearest standard value was chosen: 22 μH . For the output filter inductor, it is important that the RMS current and saturation current ratings not be exceeded. The RMS and peak inductor current can be found from [Equation 3](#) and [Equation 4](#). The inductor ripple current is 0.22 A, and the RMS current is 0.602 A. As the equation set demonstrates, lower ripple currents will reduce the output voltage ripple of the regulator but will require a larger value of inductance. A good starting point for most applications is 22 μH with a 1.6 A current rating. Using a rating near 1.6 A will enable the LMR16006 to current limit without saturating the inductor. This is preferable to the LMR16006 going into thermal shutdown mode and the possibility of damaging the inductor if the output is shorted to ground or other long-term overload.

$$L_{o\min} = \frac{V_{in\max} - V_{out}}{I_o \times K_{IND}} \times \frac{V_{out}}{V_{in\max} \times f_{sw}} \quad (1)$$

$$I_{ripple} = \frac{V_{out} \times (V_{in\max} - V_{out})}{V_{in\max} \times L_o \times f_{sw}} \quad (2)$$

$$I_{L-RMS} = \sqrt{I_o^2 + \frac{1}{12} I_{ripple}^2} \quad (3)$$

$$I_{L-peak} = I_o + \frac{I_{ripple}}{2} \quad (4)$$

9.2.2.2 Output Capacitor Selection

The selection of C_{out} is mainly driven by three primary considerations. The output capacitor will determine the modulator pole, the output voltage ripple, and how the regulator responds to a large change in load current. The output capacitance needs to be selected based on the most stringent of these three criteria.

The desired response to a large change in the load current is the first criteria. The regulator usually needs two or more clock cycles for the control loop to see the change in load current and output voltage and adjust the duty cycle to react to the change. The output capacitance must be large enough to supply the difference in current for 2 clock cycles while only allowing a tolerable amount of droop in the output voltage. Equation 5 shows the minimum output capacitance necessary to accomplish this. The transient load response is specified as a 3% change in V_{OUT} for a load step from 0.03 A to 0.6 A (full load), $\Delta I_{OUT} = 0.6 - 0.03 = 0.57$ A and $\Delta V_{OUT} = 0.03 \times 5 = 0.15$ V. Using these numbers gives a minimum capacitance of 10.8 μF . For ceramic capacitors, the ESR is usually small enough to ignore in this calculation. Aluminum electrolytic and tantalum capacitors have higher ESR that should be taken into account.

The stored energy in the inductor will produce an output voltage overshoot when the load current rapidly decreases. The output capacitor must also be sized to absorb energy stored in the inductor when transitioning from a high load current to a lower load current. [Equation 6](#) is used to calculate the minimum capacitance to keep the output voltage overshoot to a desired value. Where L is the value of the inductor, I_{OH} is the output current under heavy load, I_{OL} is the output under light load, V_f is the final peak output voltage, and V_i is the initial capacitor voltage. For this example, the worst case load step will be from 0.6 A to 0.03 A. The output voltage will increase during this load transition and the stated maximum in our specification is 3% of the output voltage. This will make $V_{o_overshoot} = 1.03 \times 5 = 5.15$ V. V_i is the initial capacitor voltage which is the nominal output voltage of 5 V. Using these numbers in [Equation 6](#) yields a minimum capacitance of 5.2 μF .

[Equation 7](#) calculates the minimum output capacitance needed to meet the output voltage ripple specification. Where f_{sw} is the switching frequency, V_{o_ripple} is the maximum allowable output voltage ripple, and I_{L_ripple} is the inductor ripple current. [Equation 7](#) yields 0.26 μF .

[Equation 8](#) calculates the maximum ESR an output capacitor can have to meet the output voltage ripple specification. Equation 8 indicates the ESR should be less than 680 m Ω .

Additional capacitance de-ratings for aging, temperature and dc bias should be factored in which will increase this minimum value. For this example, 10 μF ceramic capacitors will be used. Capacitors in the range of 4.7 μF -100 μF are a good starting point with an ESR of 0.7 Ω or less.

$$C_{out} > \frac{2 \times \Delta I_{out}}{f_{sw} \times \Delta V_{out}} \quad (5)$$

$$C_{out} > L_o \times \frac{(I_{oh}^2 - I_{ol}^2)}{(V_f^2 - V_i^2)} \quad (6)$$

$$C_{out} > \frac{1}{8 \times f_{sw}} \times \frac{1}{\frac{V_{o_ripple}}{I_{L_ripple}}} \quad (7)$$

$$R_{ESR} < \frac{V_{o_ripple}}{I_{L_ripple}} \quad (8)$$

9.2.2.3 Schottky Diode Selection

The breakdown voltage rating of the diode is preferred to be 25% higher than the maximum input voltage. In the target application, the current rating for the diode should be equal or greater to the maximum output current for best reliability in most applications. In cases where the input voltage is not much greater than the output voltage the average diode current is lower. In this case it is possible to use a diode with a lower average current rating, approximately $(1-D) \times I_{OUT}$. However the peak current rating should be higher than the maximum load current. A 0.5 A to 1 A rated diode is a good starting point.

9.2.2.4 Input Capacitor Selection

A low ESR ceramic capacitor is needed between the V_{IN} pin and ground pin. This capacitor prevents large switching voltage transients from appearing at the input. Use a 1 μ F-10 μ F value with X5R or X7R dielectric. Depending on construction, a ceramic capacitor's value can decrease up to 50% of its nominal value when rated voltage is applied. Consult with the capacitor manufactures data sheet for information on capacitor derating over voltage and temperature. The capacitor must also have a ripple current rating greater than the maximum input current ripple of the LMR16006. The input ripple current can be calculated using below Equation 9.

For this example design, one 2.2 μ F, 50 V capacitor is selected. The input capacitance value determines the input ripple voltage of the regulator. The input voltage ripple can be calculated using Equation 10. Using the design example values, $I_{OUT_max} = 0.6$ A, $C_{in} = 2.2$ μ F, $f_{sw} = 700$ kHz, yields an input voltage ripple of 97 mV and a rms input ripple current of 0.3 A.

$$I_{cirms} = I_{out} \times \sqrt{\frac{V_{out}}{V_{in\ min}} \times \frac{(V_{in\ min} - V_{out})}{V_{in\ min}}} \quad (9)$$

$$\Delta V_{in} = \frac{I_{out\ max} \times 0.25}{C_{in} \times f_{sw}} \quad (10)$$

9.2.2.5 Bootstrap Capacitor Selection

A 0.1 μ F ceramic capacitor or larger is recommended for the bootstrap capacitor (C_{BOOT}). For applications where the input voltage is close to output voltage a larger capacitor is recommended, generally 0.1 μ F to 1 μ F to ensure plenty of gate drive for the internal switches and a consistently low $R_{DS(on)}$. A ceramic capacitor with an X7R or X5R grade dielectric with a voltage rating of 10 V or higher is recommended because of the stable characteristics over temperature and voltage.

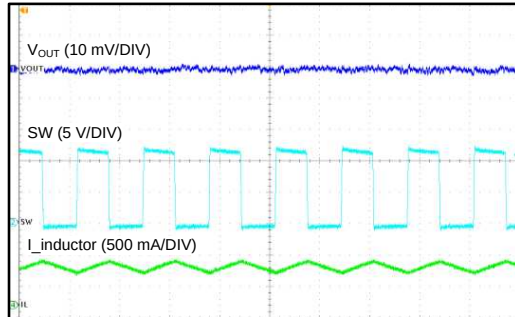
Table 2 represents the recommended typical output voltage inductor/capacitor combinations for optimized total solution size.

Table 2. Recommended Typical Output Voltage

P/N	Vout (V)	R1 (k Ω)	R2 (k Ω)	L (μ H)	Cout (μ F)
LMR16006 Y	5	54.9 (1%)	10 (1%)	6.8	10
LMR16006 Y	12	147 (1%)	10 (1%)	10	10

9.2.3 Application Curves

Unless otherwise specified the following conditions apply: $V_{IN} = 12\text{ V}$, $f_{SW} = 700\text{ kHz}$, $L1 = 22\text{ }\mu\text{H}$, $C_{out} = 10\text{ }\mu\text{F}$, $T_A = 25^\circ\text{C}$

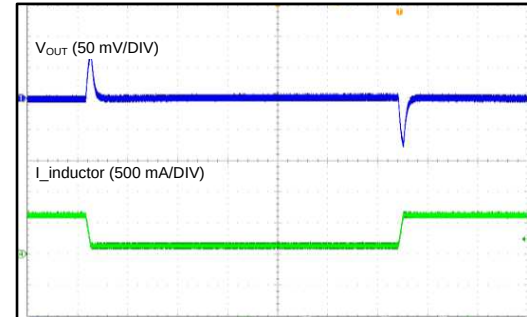


Time (1 $\mu\text{s/DIV}$)

$V_{OUT} = 5\text{ V}$

$I_{OUT} = 600\text{ mA}$

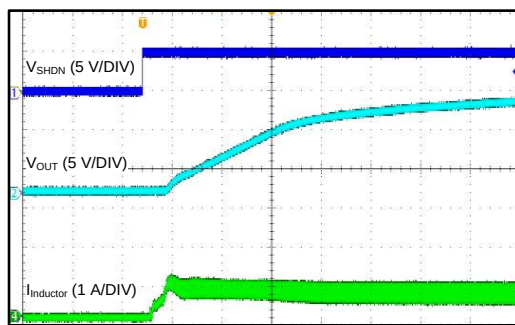
Figure 10. Output Voltage Ripple



Time (800 $\mu\text{s/DIV}$)

$V_{OUT} = 5\text{ V}$

Figure 11. Load Transient from 0.1 A to 0.6 A



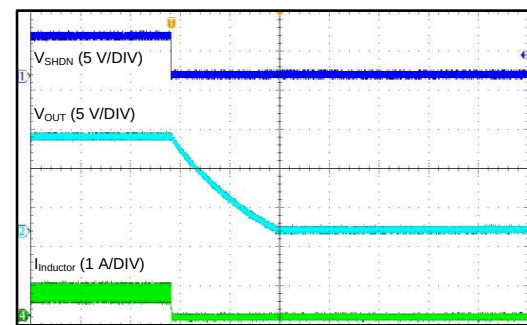
Time (800 $\mu\text{s/DIV}$)

$V_{IN} = 24\text{ V}$

$V_{OUT} = 12\text{ V}$

$I_{OUT} = 600\text{ mA}$

Figure 12. Start-Up



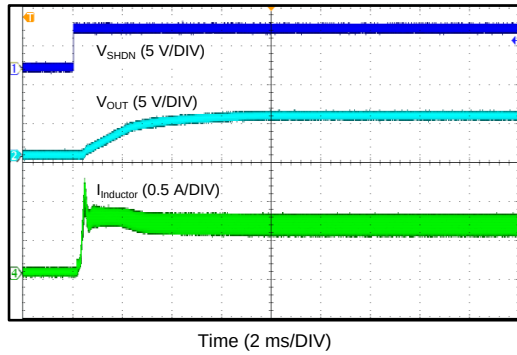
Time (200 $\mu\text{s/DIV}$)

$V_{IN} = 24\text{ V}$

$V_{OUT} = 12\text{ V}$

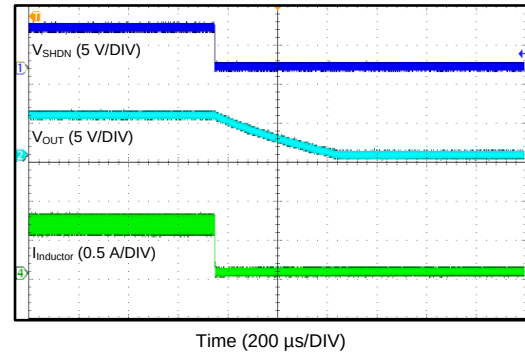
$I_{OUT} = 600\text{ mA}$

Figure 13. Shut-Down



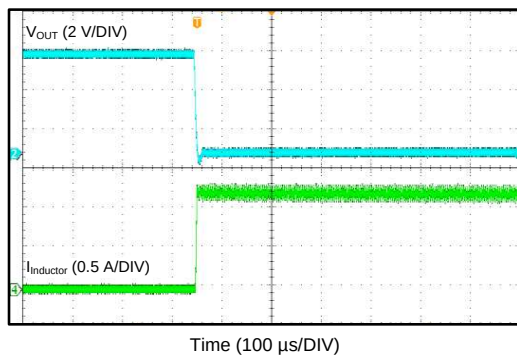
$V_{IN} = 12\text{ V}$ $V_{OUT} = 5\text{ V}$ $I_{OUT} = 600\text{ mA}$

Figure 14. Start-Up



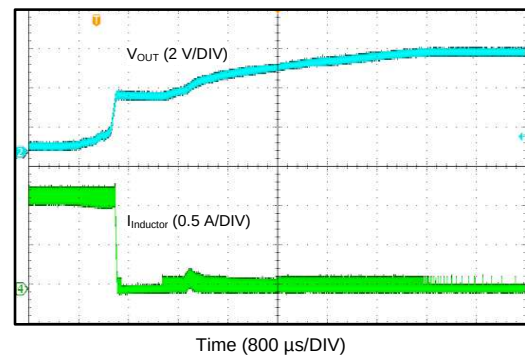
$V_{IN} = 12\text{ V}$ $V_{OUT} = 5\text{ V}$ $I_{OUT} = 600\text{ mA}$

Figure 15. Shut-Down



$V_{IN} = 12\text{ V}$ $V_{OUT} = 5\text{ V}$

Figure 16. Short Circuit Entry



$V_{IN} = 12\text{ V}$ $V_{OUT} = 5\text{ V}$

Figure 17. Short Circuit Recovery

10 Power Supply Recommendations

The LMR16006 is designed to operate from an input voltage supply range between 4 V and 60 V. This input supply should be able to withstand the maximum input current and maintain a voltage above 4 V. The resistance of the input supply rail should be low enough that an input current transient does not cause a high enough drop at the LMR16006 supply voltage that can cause a false UVLO fault triggering and system reset. If the input supply is located more than a few inches from the LMR16006, additional bulk capacitance may be required in addition to the ceramic input capacitors.

11 Layout

11.1 Layout Guidelines

Layout is a critical portion of good power supply design. The following guidelines will help users design a PCB with the best power conversion performance, thermal performance, and minimized generation of unwanted EMI.

1. The feedback network, resistors R1 and R2, should be kept close to the FB pin, and away from the inductor to minimize coupling noise into the feedback pin.
2. The input bypass capacitor Cin must be placed close to the V_{IN} pin. This will reduce copper trace resistance which effects input voltage ripple of the IC.
3. The inductor L1 should be placed close to the SW pin to reduce magnetic and electrostatic noise.
4. The output capacitor, Cout should be placed close to the junction of L1 and the diode D1. The L1, D1, and Cout trace should be as short as possible to reduce conducted and radiated noise and increase overall efficiency.
5. The ground connection for the diode, Cin, and Cout should be as small as possible and tied to the system ground plane in only one spot (preferably at the Cout ground point) to minimize conducted noise in the system ground plane.
6. For more detail on switching power supply layout considerations see AN-1149 Layout Guidelines for Switching Power Supplies [SNVA021](#)

11.2 Layout Example

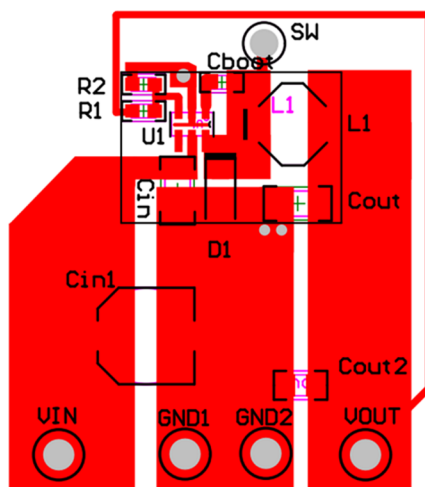


Figure 18. Layout

12 Device and Documentation Support

12.1 Related Documentation

AN-1149 Layout Guidelines for Switching Power Supplies [SNVA021](#)

12.2 Trademarks

SIMPLE SWITCHER is a registered trademark of TI .
All other trademarks are the property of their respective owners.

12.3 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

12.4 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
LMR16006XDDCR	ACTIVE	SOT	DDC	6	3000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 125	D02X	Samples
LMR16006XDDCT	ACTIVE	SOT	DDC	6	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 125	D02X	Samples
LMR16006YDDCR	ACTIVE	SOT	DDC	6	3000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 125	D02Y	Samples
LMR16006YDDCT	ACTIVE	SOT	DDC	6	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 125	D02Y	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBsolete: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

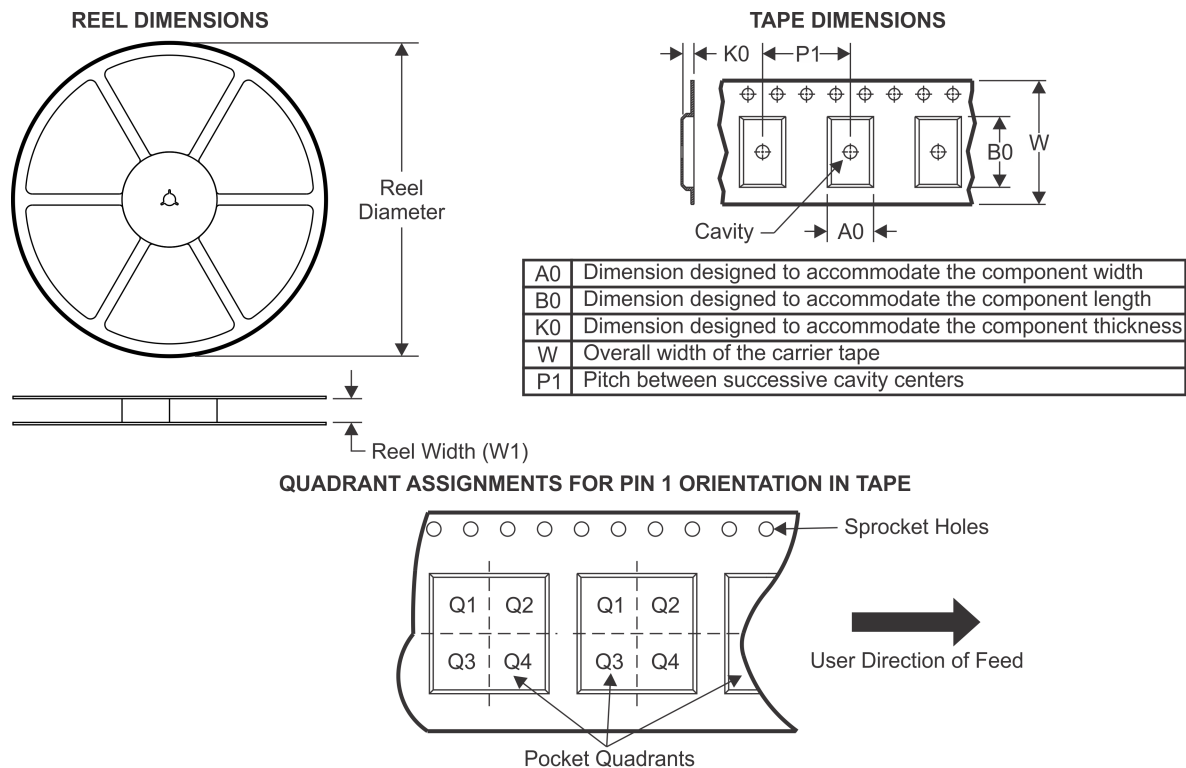
(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

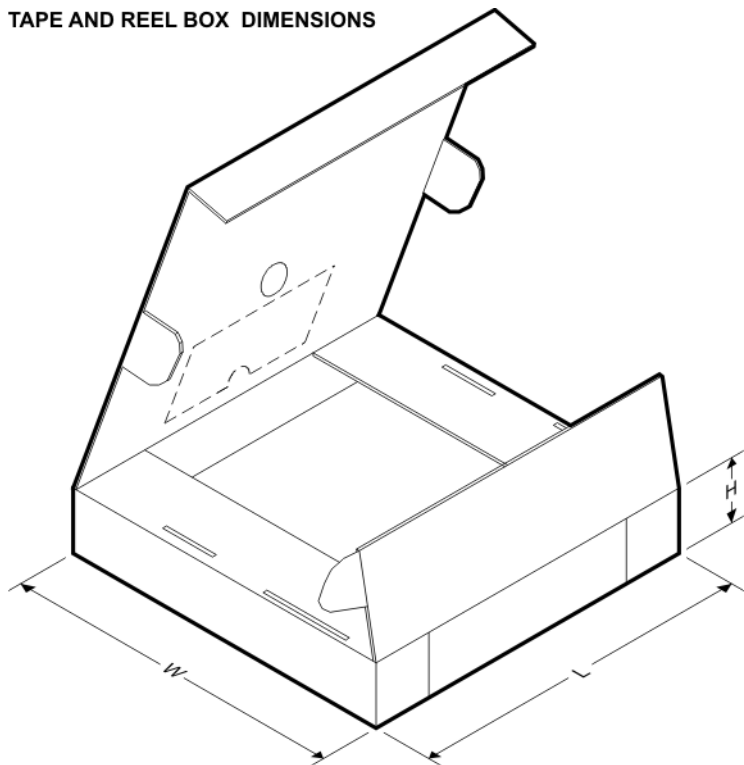
In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

TAPE AND REEL INFORMATION


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMR16006XDDCR	SOT	DDC	6	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMR16006XDDCT	SOT	DDC	6	250	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMR16006YDDCR	SOT	DDC	6	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMR16006YDDCT	SOT	DDC	6	250	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3

TAPE AND REEL BOX DIMENSIONS

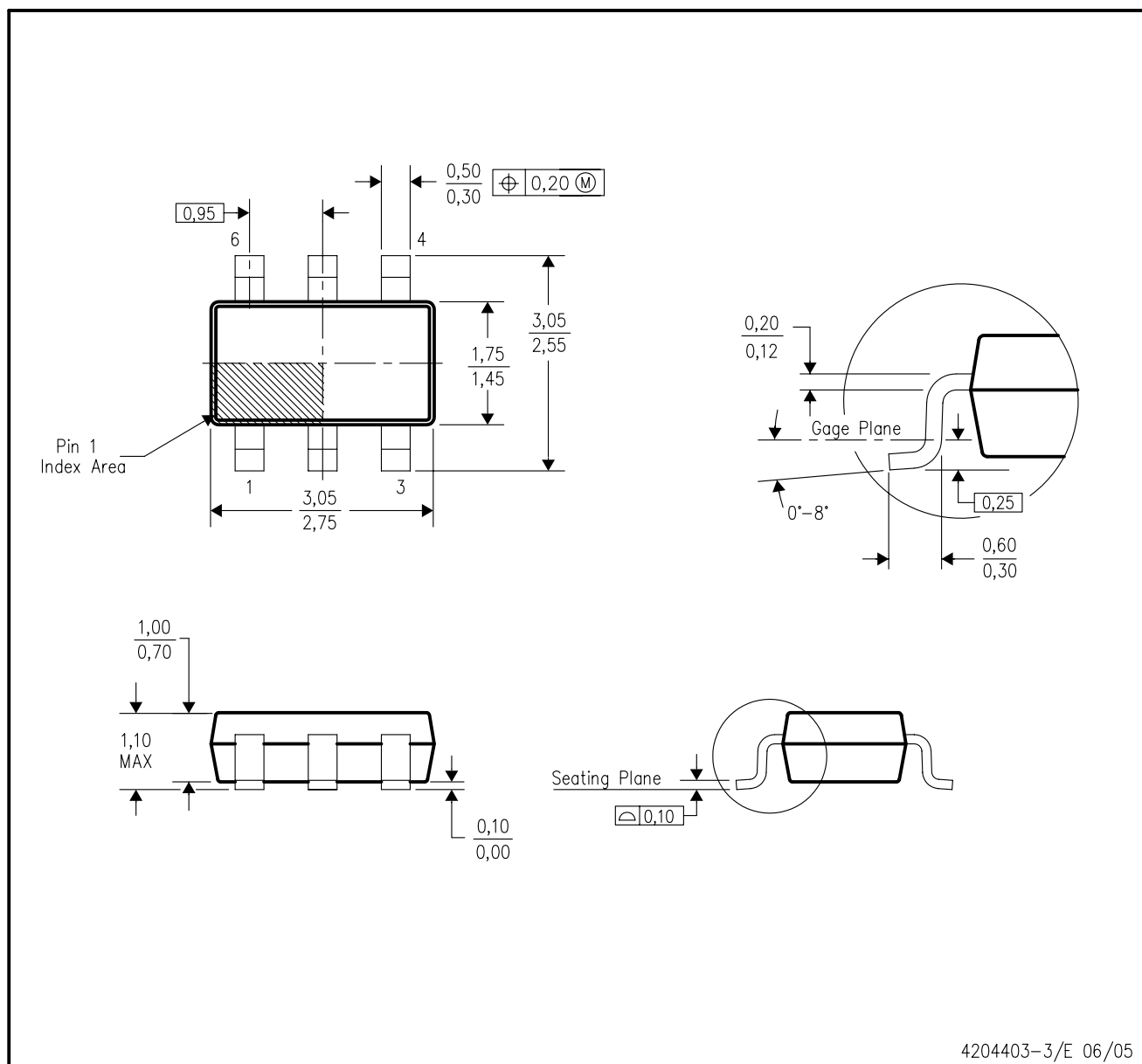


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LMR16006XDDCR	SOT	DDC	6	3000	210.0	185.0	35.0
LMR16006XDDCT	SOT	DDC	6	250	210.0	185.0	35.0
LMR16006YDDCR	SOT	DDC	6	3000	210.0	185.0	35.0
LMR16006YDDCT	SOT	DDC	6	250	210.0	185.0	35.0

DDC (R-PDSO-G6)

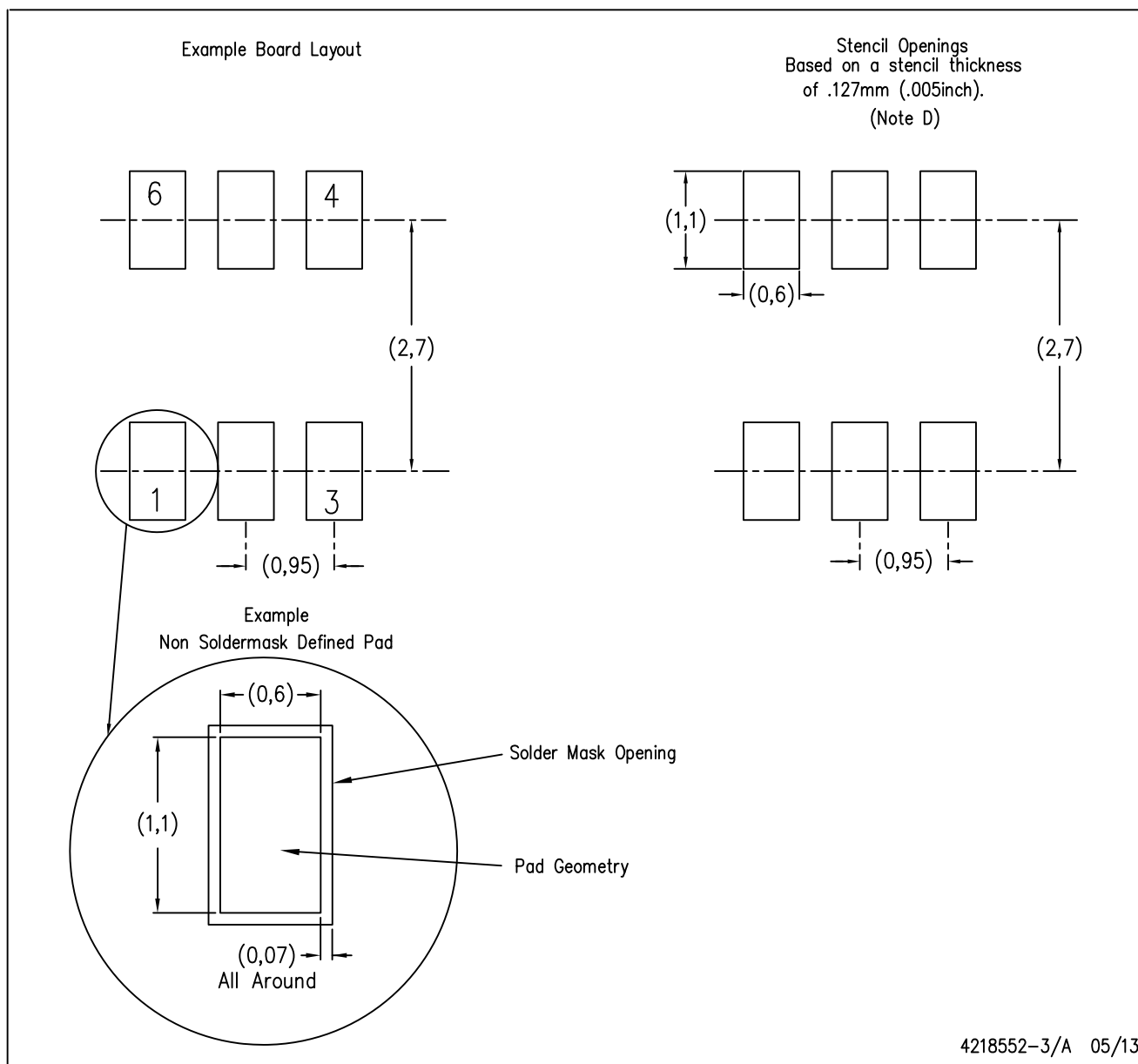
PLASTIC SMALL-OUTLINE



- NOTES:
- All linear dimensions are in millimeters.
 - This drawing is subject to change without notice.
 - Body dimensions do not include mold flash or protrusion.
 - Falls within JEDEC MO-193 variation AA (6 pin).

DDC (R-PDSO-G6)

PLASTIC SMALL OUTLINE



- NOTES:
- A. All linear dimensions are in millimeters.
 - B. This drawing is subject to change without notice.
 - C. Publication IPC-7351 is recommended for alternate designs.
 - D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.

IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, enhancements, improvements and other changes to its semiconductor products and services per JESD46, latest issue, and to discontinue any product or service per JESD48, latest issue. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All semiconductor products (also referred to herein as "components") are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its components to the specifications applicable at the time of sale, in accordance with the warranty in TI's terms and conditions of sale of semiconductor products. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by applicable law, testing of all parameters of each component is not necessarily performed.

TI assumes no liability for applications assistance or the design of Buyers' products. Buyers are responsible for their products and applications using TI components. To minimize the risks associated with Buyers' products and applications, Buyers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right relating to any combination, machine, or process in which TI components or services are used. Information published by TI regarding third-party products or services does not constitute a license to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of significant portions of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI components or services with statements different from or beyond the parameters stated by TI for that component or service voids all express and any implied warranties for the associated TI component or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Buyer acknowledges and agrees that it is solely responsible for compliance with all legal, regulatory and safety-related requirements concerning its products, and any use of TI components in its applications, notwithstanding any applications-related information or support that may be provided by TI. Buyer represents and agrees that it has all the necessary expertise to create and implement safeguards which anticipate dangerous consequences of failures, monitor failures and their consequences, lessen the likelihood of failures that might cause harm and take appropriate remedial actions. Buyer will fully indemnify TI and its representatives against any damages arising out of the use of any TI components in safety-critical applications.

In some cases, TI components may be promoted specifically to facilitate safety-related applications. With such components, TI's goal is to help enable customers to design and create their own end-product solutions that meet applicable functional safety standards and requirements. Nonetheless, such components are subject to these terms.

No TI components are authorized for use in FDA Class III (or similar life-critical medical equipment) unless authorized officers of the parties have executed a special agreement specifically governing such use.

Only those TI components which TI has specifically designated as military grade or "enhanced plastic" are designed and intended for use in military/aerospace applications or environments. Buyer acknowledges and agrees that any military or aerospace use of TI components which have **not** been so designated is solely at the Buyer's risk, and that Buyer is solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI has specifically designated certain components as meeting ISO/TS16949 requirements, mainly for automotive use. In any case of use of non-designated products, TI will not be responsible for any failure to meet ISO/TS16949.

Products

Audio	www.ti.com/audio
Amplifiers	amplifier.ti.com
Data Converters	dataconverter.ti.com
DLP® Products	www.dlp.com
DSP	dsp.ti.com
Clocks and Timers	www.ti.com/clocks
Interface	interface.ti.com
Logic	logic.ti.com
Power Mgmt	power.ti.com
Microcontrollers	microcontroller.ti.com
RFID	www.ti-rfid.com
OMAP Applications Processors	www.ti.com/omap
Wireless Connectivity	www.ti.com/wirelessconnectivity

Applications

Automotive and Transportation	www.ti.com/automotive
Communications and Telecom	www.ti.com/communications
Computers and Peripherals	www.ti.com/computers
Consumer Electronics	www.ti.com/consumer-apps
Energy and Lighting	www.ti.com/energy
Industrial	www.ti.com/industrial
Medical	www.ti.com/medical
Security	www.ti.com/security
Space, Avionics and Defense	www.ti.com/space-avionics-defense
Video and Imaging	www.ti.com/video

TI E2E Community

e2e.ti.com