

3DM-GX5-25

Attitude and Heading Reference System (AHRS)



3DM-GX5-25 - miniature industrial-grade attitude and heading reference system (AHRS) with integrated magnetometers, high noise immunity, and exceptional performance

The LORD Sensing 3DM-GX5 family of industrial grade inertial sensors provides a wide range of triaxial inertial measurements and computed attitude and navigation solutions.

The 3DM-GX5-25 is the smallest and lightest industrial AHRS with an Adaptive Kalman Filter available. It features a triaxial accelerometer, gyroscope, magnetometer, and temperature sensors to achieve the optimum combination of measurement qualities. Additionally, the dual on-board processors run a new Auto-Adaptive Extended Kalman Filter (EKF) for outstanding dynamic attitude estimates, making it ideal for a wide range of applications, including platform stabilization and vehicle health and usage monitoring.

The LORD Sensing **MIP Monitor** software can be used for device configuration, live data monitoring, and recording. Alternatively, the **MIP Data Communications Protocol** is available for development of custom interfaces and easy OEM integration.

Product Highlights

- Triaxial accelerometer, gyroscope, magnetometer, temperature sensors achieve the optimal combination of measurement qualities
- Dual on-board processors run a new Auto-Adaptive Extended Kalman Filter (EKF) for outstanding dynamic attitude estimates

Features and Benefits

Best in Class Performance

- Bias tracking, error estimation, threshold flags, and adaptive noise modeling allow for fine tuning to conditions in each application
- Accelerometer noise as low as 25 $\mu g/\sqrt{Hz}$
- Smallest and lightest industrial AHRS with Adaptive Kalman Filter available

Ease of Use

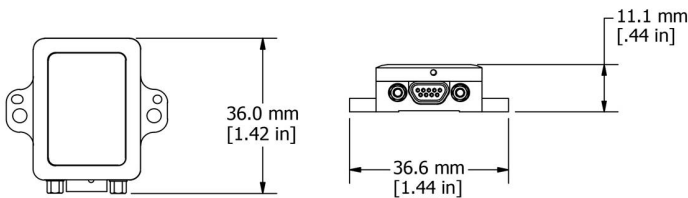
- Automatic magnetometer calibration and anomaly rejection eliminates the need for field calibration
- Automatically compensates for vehicle noise and vibration
- Easy integration via comprehensive and fully backwards-compatible communication protocol
- Common protocol between 3DM-GX3, GX4, RQ1, GQ4, and GX5 inertial sensor families for easy migration

Cost Effective

- Out-of-the box solution reduces development time
- Volume discounts

Applications

- Unmanned vehicle navigation
- Platform stabilization, artificial horizon
- Health and usage monitoring of vehicles



3DM-GX5-25 Attitude and Heading Reference System (AHRS)

Specifications

General			
Integrated sensors	Triaxial accelerometer, triaxial gyroscope, triaxial magnetometer, pressure altimeter, and temperature sensors		
Data outputs	Inertial Measurement Unit (IMU) outputs: acceleration, angular rate, magnetic field , ambient pressure, deltaTheta, deltaVelocity Computed outputs: Extended Kalman Filter (EKF): filter status, timestamp, attitude estimates (in Euler angles, quaternion, orientation matrix), linear and compensated acceleration, bias compensated angular rate, pressure altitude, gravity-free linear acceleration, gyroscope and accelerometer bias, scale factors and uncertainties, gravity and magnetic models, and more.		
Inertial Measurement Unit (IMU) Sensor Outputs			
	Accelerometer	Gyroscope	Magnetometer
Measurement range	±8 g (standard) ±2 g, ±4 g, ±20 g, ±40 g (optional)	300°/sec (standard) ±75, ±150, ±900 °/sec (optional)	±2.5 Gauss
Non-linearity	±0.02 % fs	±0.02 % fs	±0.3 % fs
Resolution	<0.1 mg	<0.003°/sec	--
Bias instability	±0.04 mg	8°/hr	--
Initial bias error	±0.002 g	±0.04°/sec	±0.003 Gauss
Scale factor stability	±0.03%	±0.05%	±0.1%
Noise density	25 µg/√Hz (2 g)	0.005°/sec/√Hz (300 dps)	100 µGauss/√Hz
Alignment error	±0.05°	±0.05°	±0.05°
Adjustable bandwidth	225 Hz (max)	250 Hz (max)	-
Offset error over temperature	0.06% (typ)	0.04% (typ)	--
Gain error over temperature	0.03% (typ)	0.03% (typ)	--
Scale factor non-linearity (@ 25° C)	0.02% (typ) 0.06% (max)	0.02% (typ) 0.06% (max)	±0.0015 Gauss
Vibration induced noise	--	0.072°/s RMS/g RMS	--
Vibration rectification error (VRE)	--	0.001°/s/g ² RMS	--
IMU filtering	Digital sigma-delta wide band anti-aliasing filter to digital averaging filter (user adjustable) scaled into physical units; coning and sculling integrals computed at 1 kHz		
Sampling rate	1 kHz	4 kHz	50 Hz
IMU data output rate	1 Hz to 1 kHz		
Pressure Altimeter			
Range	-1800 m to 10,000 m		
Resolution	< 0.1 m		
Noise density	0.01 hPa RMS		
Sampling rate	25 Hz		

Computed Outputs	
Attitude accuracy	EKF outputs: ±0.25° RMS roll and pitch, ±0.8° RMS heading (typ) CF outputs: ±0.5° RMS roll and pitch, ±1.5° RMS heading (typ)
Attitude heading range	360° about all axes
Attitude resolution	< 0.01°
Attitude repeatability	0.2° (typ)
Calculation update rate	500 Hz
Computed data output rate	EKF outputs: 1 Hz to 500 Hz CF outputs: 1 Hz to 500 Hz
Operating Parameters	
Communication	USB 2.0 (full speed) RS232 (9,600 bps to 921,600 bps, default 115,200)
Power source	+4 to +36 V dc
Power consumption	500 mW (typ)
Operating temperature	-40 °C to +85 °C
Mechanical shock limit	500 g (calibration unaffected) 1000 g (bias may change), 5000 g (survivability)
MTBF	(TBD)
Physical Specifications	
Dimensions	36.0 mm x 36.6 mm x 11.1 mm
Weight	16.5 grams
Enclosure material	Aluminum
Regulatory compliance	ROHS, CE
Integration	
Connectors	Data/power output: micro-DB9
Software	MIP Monitor, Windows XP/Vista/7/8/10 compatible
Compatibility	Protocol compatibility across 3DM-GX3, GX4, RQ1, GQ1, and GX5 product families
Software development kit (SDK)	MIP data communications protocol with sample code available (OS and platform independent)

LORD

SENSING

MicroStrain

LORD Corporation

LORD SENSING
MicroStrain

LORD Corporation
MicroStrain® Sensing Systems
459 Hurricane Lane, Suite 102
Williston, VT 05495 USA

ph: 802-862-6629
sensing_sales@LORD.com
sensing_support@LORD.com