



JUMPtec[®]

JIDA32 Library API

Technical Manual

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JUMPtec[®]

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User Information

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General

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Warranty

Each board is tested carefully and thoroughly before being shipped. If, however, problems should occur during the operation, please check your user specific settings of all boards included in your system. This is often the source of the fault. If a board is defective, it can be sent to your supplier for repair. Please take care of the following steps:

1. The board returned should have the factory default settings since a test is only possible with these settings.
2. In order to repair your board as fast as possible we require some additional information from you. Please fill out the attached Repair Form and include it with the defective board.
3. If possible the board will be upgraded to the latest version without additional cost.
4. Upon receipt of the board please be aware that your user specific settings were changed during the test.

Within the warranty period the repair is free of charge as long as the warranty conditions are observed. Because of the high test expenditure you will be charged with the test cost if no fault is found. Repair after the warranty period will be charged.

This **JUMPtec[®]** product is warranted against defects in material and workmanship for the warranty period from the date of shipment. During the warranty period **JUMPtec[®]** will at its option either repair or replace defective products.

For warranty service or repair the product must be returned to a service facility designated by **JUMPtec[®]**.

The foregoing warranty shall not apply to defects resulting from improper or inadequate maintenance or handling by buyer, unauthorized modification or misuse, operation outside of the product's environmental specifications or improper installation or maintenance.

JUMPtec[®] will not be responsible for any defects or damages to other products not supplied by **JUMPtec[®]** that are caused by a faulty **JUMPtec[®]** product.

Introduction

Most **JUMPtec[®]** PC boards are equipped with unique hardware features that cannot be accessed with standard API. The JIDA interface allows you to access these features in a hardware independent manner under popular 32-bit operating systems.

The library interface works under any flavor of Win32, as well as Linux and VxWorks. The library communicates with a platform dependent driver. At the present time drivers are available for Windows 9x, Windows NT, Windows 2000, Windows XP, Windows CE, Linux, and VxWorks.

The API was renamed from "JIDA Win32 API" to "JIDA32 Library API" as it is now available for a variety of operating systems. There are no changes for using the API under Windows.

The Watchdog functionality has been integrated into the JIDA API. The use of the obsolete JWDOG.DLL is strongly discouraged.

Requirements

- PC with any number of **JUMPtec[®]** boards that have BIOS support
- Any of these operating system:
 - Windows 9x
 - Windows NT 4.0
 - Windows 2000
 - Windows XP
 - Windows CE 2.x/3.0
 - Linux 2.2/2.4
 - Wind River Tornado 2.0 (VxWorks 5.4) with Pentium or 486 BSP

Installation

The drivers are dynamically installed upon running the sample application JIDATST.EXE. You can do that in your own application as well.

Under Windows NT/2000/XP you need Administrator rights to install the drivers, i.e. running JIDATST.EXE for the first time.

The JIDA API includes a function `JidaDllInstall` that allows you to perform the necessary steps to set up the required drivers in an operating system independent manner. Please note that it still your responsibility to copy the required files into the Windows directory before calling `JidaDllInstall`. The files are listed below for each operating system along with installation instructions if you do not want to use the JIDA install function.

Please note that the JIDA.DLL is binary compatible between Windows 9x and NT/2000/XP. A different version with the same name is supplied for Windows CE.

The `Jida.h` header file is the same on all operating system versions. For Linux and VxWorks you need to include the file `JWinDefs.h` before including `Jida.h`. to pull in missing type declarations. You also need to include any OS specific header file before that like `windows.h` or `vxWorks.h`.

Note that for individual operating systems or boards **JUMPtec[®]** may occasionally release separate packages of the JIDA32 Library or drivers that will eventually be incorporated into this complete package. So always check for individual updates first.

Windows 9x

The following files must be copied to the Windows 9x system directory:

```
JIDA.DLL
JIDAV.VXD
JWDOGV.VXD
JWDOGR.EXE
```

To set up the drivers manually the following line must be added to [386Enh] section of the SYSTEM.INI file located in the Windows directory:

```
device=JIDAV.VXD
device=JWDOGV.VXD
```

Note that if you do not intend to use the watchdog functionality then you do not need to load the JWDOG.VXD which sets up an NMI handler.

Note that the JWDOG.VXD is never installed automatically. You must add this line manually.

Using JUMPtéc boards with a Winbond controller (like the ETX-MGX) under Windows 98:

This information does not apply to other operating systems.

Open REGEDIT.EXE and delete this tree node:

```
HKEY_LOCAL_MACHINE\System\CurrentControlSet\Services\VxD\VFBACKUP
```

This prevents the floppy backup VxD from loading and allows the BIOS to access the Winbond controller.

The floppy drive still works but unpredictable results MAY occur if multiple DOS boxes access the floppy drive at the same time. Certain DOS based Backup or Copy programs that access the floppy drive directly will most likely fail or show unpredictable results including floppy disk data loss.

It is OK if multiple Windows applications access the drive at the same time.

The BIOS implementation of the JIDA interface on that board has the following restrictions:

- The watchdog delay MUST be set to zero otherwise the watchdog is not activated.
- The watchdog mode MUST be set to RESET otherwise the watchdog will never work until the board is reset.

A better solution will be implemented at a later time.

This condition exists because programming the Winbond controller requires access to port 3f0h and 3f1h.

On Windows 98 the VFBACKUP VxD for the floppy disk drives traps these port accesses even though these ports are only used on PS/2 machines for floppy drives. This VxD does NOT to emulate these port accesses by default but instead ignores them. So the Winbond controller cannot be accessed and the Watchdog and I2C functionality does not work.

Windows NT/2000/XP

The following files must be copied to the Windows NT System32 directory:

JIDA.DLL
JIDAN.SYS

To set up the drivers manually the following entries must be made to the system registry:

```
[HKEY_LOCAL_MACHINE\SYSTEM\CurrentControlSet\Services\Jidan]
"Type"=dword:00000001
"Start"=dword:00000002
"ErrorControl"=dword:00000001
"Group"="Extended Base"
```

Please note that the Restart option is not implemented under Windows NT/2000/XP. The Restart option of the watch dog API issues an NMI when the watch dog expires. If desired you can add your own NMI Handler. By default NT will produce a **blue screen**. This behavior is by design.

Windows CE

The following files must be copied to the Windows directory:

JIDA.DLL
JIDAC.DLL

To do that add these line to the MODULES section of any *.BIB file:

jida.dll	\$(_FLATRELEASEDIR)\jida.dll	NK	SH
jidac.dll	\$(_FLATRELEASEDIR)\jidac.dll	NK	SH

If you want to run the demo also add:

jidatst.exe	\$(_FLATRELEASEDIR)\jidatst.exe	NK	S
-------------	---------------------------------	----	---

Place the three files into any files directory.

To set up the drivers manually add these line in any *.REG file:

```
[HKEY_LOCAL_MACHINE\Drivers\BuiltIn\JidaC]
"Dll"="jidac.dll"
"Prefix"="JDA"
"Index"=dword:1
"Order"=dword:9
```

Build your new Windows CE operating system.

Linux

This package includes pre-compiled JIDA modules for the following kernels:

- 2.2.x
- 2.4.x

The Linux JIDA package contains the following files/directories:

JidaDrv	Contains partially linked versions of the JIDA kernel driver for 2.2.x and 2.4.x kernels
JidaLib	Contains a partially linked version of the JIDA interface library
JidaTst	Contains the source code for the general JIDA test application
JWDogTst	Contains the source code for the JIDA watchdog test application
Makefile	Main makefile

Prerequisites

In order to build and install the Linux JIDA driver and interface library you need to have ROOT privileges.

Please make sure, that /usr/src/linux contains or points to the sources (or at least the header files) of the kernel for which you want to build the JIDA package.

Build and Installation

Type '**make all**' to build the JIDA kernel driver matching the kernel version located in /usr/src/linux, the JIDA interface library for your installed libc version, and the corresponding test utilities.

The make utility will automatically chose the appropriate partially linked driver library for the kernel located in /usr/src/linux and build the kernel driver module jida.o.

If the build is successful, the following JIDA files can be found in the respective directories:

Directory	Files(s)	Description
JidaDrv	jida.o	The JIDA kernel driver module for the respective kernel.
JidaLib	Jida.h and JWinDefs.h <u>or</u> jidakiss.h	Header files to be included by the user's application accessing the JIDA interface.
	libjida.a, libjida.so	Static and shared JIDA interface libraries to be linked to the user's application.
JidaTst	jidatst	General JIDA test application.
JWDogTst	jwdogtst	JIDA watchdog test application.

Running '**make install**' will copy the JIDA modules to the appropriate directories:

jida.o	/lib/modules/'KERNEL_VERSION'/misc
libjida.so, libjida.a	/usr/lib
Jida.h, JWinDefs.h, jidakiss.h	/usr/include
jidatst, jwdogtst	/usr/bin

Now you should run the sample application `jidatst`, which will display the following message:

```
JIDA system driver is incompatible or not installed.  
Would you like to install it? (yes or no)
```

If you answer this question with 'yes' or 'y', the device node `/dev/jida` is created and the driver module `jida.o` is loaded.

Afterwards some basic JIDA test calls will be performed which display their results on the screen. If you see these results, the JIDA interface is operational.

In order to be able to access the JIDA interface from your own (non-root) application, you have to make sure, that the JIDA driver module is loaded.

There are two recommended ways to do this:

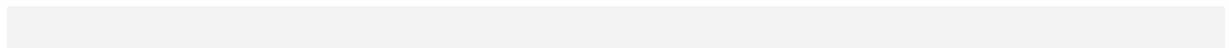
1. Add an `insmod jida` instruction to one of the Linux initialization scripts.
2. Add the following entry to your `/etc/conf.modules` file:

```
alias char-major-99 jida
```

This way `jida.o` will be loaded dynamically on calling `JidaDllInitialize`. However, this method only works if either `KERNELD` or `KMOD` are active and you are using a `jida.o` compiled for your kernel version.

Please make sure to include the files `Jida.h` and `JWinDefs.h` in your JIDA application.

As an alternate method you can include the `jidakiss.h` **instead** of the previous two header files. This header file uses only simple ANSI C data types and does not rely on any other typedefs made in other header files. It is however untested and solely provided for the convenience of users who have had limited exposure to other operating systems or who find the use of too many abstract typedefs difficult to understand. There is no support for 16 bit characters.



VxWorks

You must install the following products first:

- Wind River Tornado 2.0 (VxWorks 5.4, UGL 1.2)
- BSP Pentium or 486

VxWork issues

- Since VxWorks uses 8 bit character there is no support for UNICODE.
- The Restart option of the watch dog API issues an NMI when the watch dog expires. If desired you can add your own NMI Handler.
- You need to include the `JWinDefs.h` header file before including the `Jida.h`.

As an alternate method you can include the `jidakiss.h` **instead** of the previous two header files. This header file uses only simple ANSI C data types and does not rely on any other typedefs made in other header files. It is however untested and solely provided for the convenience of users who have had limited exposure to other operating systems or who find the use of too many abstract typedefs difficult to understand.

Installation

Please make sure that Tornado has been installed properly.

All paths are relative to the Tornado root that is `C:\Tornado` by default.

Board Support Package BSP

First of all it is recommended that you create a new BSP based on the PENTIUM or 486 BSP. The location of the new BSP will be referred to as `target\config<BSP>` in this documentation.

Driver Files

Copy these files to your Tornado directory

```
target\lib\objPENTIUMgnuvx\JIDA.a
target\lib\objI80486gnuvx\JIDA.a
target\lib\objPENTIUMgnuvx\JIDA.o
target\lib\objI80486gnuvx\JIDA.o
target\h\jida.h
target\h\win2unix.h
```

Using the Driver

After that you are ready to create a new Tornado project based on the new BSP.

There are a number of ways to include the `jida.a` library to your project. One way of doing that is to add the name `jida.a` to the `EXTRA_MODULES` or `LIB` macro in the projects settings.

As an alternative the JIDA Interface is also provided as a single object file `jida.o`. Please note that can either use `jida.a` or `jida.o` but not both at the same time.

The library also contains two demo functions that correspond to the `JIDATST` and `JWDOGTST` in the documentation.

You can call them with `jidaTest()` and `jidaTestWD()` respectively. Please note that need to run `jidaTest()` before running `jidaTestWD()`. The functions will only be pulled in if they are referenced.

Answer the questions with y for yes, n for no, o for ok, and c for cancel. You need to press return after the letter.

The Restart option of the watch dog API issues an NMI when the watch dog expires. If desired you can add your own NMI Handler.



Additional Programs

LCD Hot Key Support

This tool enables hot keys to change the contrast and back light voltage for LCD panels under Windows 9x/NT/2000/XP.

You need these files in addition to the JIDA binaries:

JLcdKeyX.exe
JLcdKeyD.dll

Run JLcdKeyX.exe from your StartUp group or registry Run key.

The hot key assignment is as follows:

Key	Action
Ctrl+Alt+1	Decrease contrast
Ctrl+Alt+2	Increase contrast
Ctrl+Alt+3	Set contrast to 50%
Ctrl+Alt+F1	Decrease backlight
Ctrl+Alt+F2	Increase backlight
Ctrl+Alt+F3	Set backlight to 66%

IMPORTANT NOTE: The JIDA.DLL MUST be located in the Windows or Windows System directory for this to work. It is NOT sufficient that the JIDA.DLL is in the same directory as JLcdKeyX.exe. There is no error message to indicate this faulty configuration. The hot keys simply have no effect.

Sample Programs

The sample programs JIDATST and JWDOGTST are just that: sample programs. They are not intended to serve any useful purpose. To learn how they work please look at the provided source code. Please note that JIDATST dynamically loads the driver while JWDOGTST does not.

THESE PROGRAMS ARE INTENDED FOR SOFTWARE DEVELOPERS AND ARE OF NO INTEREST TO END USERS!

YOU SHOULD NEVER SHIP THESE PROGRAMS (AS THEY ARE) TO END USERS!

PLEASE NOTE THAT AFTER RUNNING JWDOGTST THE BOARD MIGHT BE *RESET*** OR PRODUCE A ***BLUE SCREEN*** WITHOUT PRIOR NOTICE. DATA MIGHT BE LOST! THIS BEHAVIOR IS BY DESIGN. SEE THE SOURCE CODE FOR DETAILS!**

Programming Overview

All API functions are exported from the JIDA.DLL dynamic link library. UNICODE is supported. JIDA.DLL is binary compatible between Windows 9x and NT/2000/XP. A different version with the same name is supplied for Windows CE.

A header file Jida.h and import library JIDA.LIB for C/C++ are provided in the INC and LIB directories. The header file is the same on all Windows versions.

The file JIDATST.CPP contains an example that demonstrates the JIDA functionality under Microsoft Visual C++.

The file JWD0GTST.CPP contains an example that demonstrates the basic watchdog functionality under Microsoft Visual C++.

Initializing the DLL

Before any other API is to be used you must initialize the DLL using JidaDllInitialize. Before your application terminates you must call JidaDllUninitialize to allow proper resource clean up.

- JidaDllGetVersion
- JidaDllInitialize
- JidaDllUninitialize
- JidaDllIsAvailable
- JidaDllInstall

Establishing a connection to a board

The JIDA API is based on the board concept. A board is a physical hardware component. At the moment each board must have a BIOS or DOS TSR that either provides a 16 bit real mode or 32 bit protected mode entry point that contains support functions for the underlying hardware.

Each board has a unique seven letter name that corresponds directly with the physical type of board. Examples are "P388", "P488", "LEU1" or "SPRINT5". Boards are also divided into classes. The currently defined classes are "CPU", "VGA", and "IO". Each board has one primary class but it can also have any number of secondary classes.

This allows you to talk to a class of boards that has a particular functionality without knowing the exact name of the board.

The function JidaBoardCount can be used to query the number of available boards either in total or for a given class. Note that since one board can belong to any number of classes the total number of boards is not necessarily the sum of all of the number of boards for each class. For example "LEU1" is primarily a CPU class board but it also has an on board VGA, so it has that class as its secondary class.

The maximum possible configuration at the moment would be a CPU board with onboard VGA, a second VGA and an IO card plugged into a slot.

So you would have a total of three physical boards. One for CPU class, two boards for VGA, and one for IO.

Most JIDA API calls take a board handle as a first parameter. You can obtain such a handle thru one of two functions: `JidaBoardOpen` which takes a class name or board index as a parameter and `JidaBoardOpenByName` which takes a unique board name.

You can keep the handle open for as long as you like. The handle must be closed with `JidaBoardClose`.

- `JidaBoardCount`
- `JidaBoardOpen`
- `JidaBoardOpenByName`
- `JidaBoardClose`

Generic board functions

A number of JidaBoard* functions allow you to retrieve general board class independent information about the board.

- JidaBoardGetName
- JidaBoardGetInfo
- JidaBoardGetBootCounter
- JidaBoardGetRunningTimeMeter

VGA functions

JidaVga* functions are implemented by boards that belong to the VGA class. They primarily control LCD backlight brightness and contrast.

- JidaVgaGetContrast
- JidaVgaSetContrast
- JidaVgaGetBacklight
- JidaVgaSetBacklight
- JidaVgaEndDarkBoot

Storage areas

Each board can have a number of storage areas. A storage area is piece of physical memory that usually provides persistent storage for the user's application. All of the JidaStorageArea* functions take a type as a second parameter. This type is a combination of one of the predefined type constants for EEPROM, FLASH, CMOS, or RAM and a zero-based index of the area if there are more areas of a particular type.

- JidaStorageAreaCount
- JidaStorageAreaType
- JidaStorageAreaSize
- JidaStorageAreaRead
- JidaStorageAreaWrite

I2C buses

JidaI2C* functions provide access to the onboard I2C bus. Note that since I2C addresses may change you should not use these functions to access any JUMPtec[®] onboard devices. You should use these functions only if you have your own devices connected to the onboard bus. Although the functions take a type as a second parameter, only one I2C per board is implemented at the moment.

- JidaI2CCount
- JidaI2CIsAvailable
- JidaI2CReadRegister
- JidaI2CWriteRegister

Watchdog

Some JUMPtec[®] PC boards are equipped with a watchdog component that allows the system to be reset when the running application has stopped responding.

This works by setting up a time interval either in the BIOS setup or thru API functions like `JidaWDogSetConfig` that are called directly by the application. After that the application must continuously call another API function named `JidaWDogTrigger` that triggers the watchdog. If it fails to call that function within the set up time period the PC is reset.

The JUMPtec[®] Watchdog Win32 API is obsolete and has been incorporated into the JIDA API.

- `JidaWDogCount`
- `JidaWDogIsAvailable`
- `JidaWDogTrigger`
- `JidaWDogGetConfigStruct`
- `JidaWDogSetConfigStruct`
- `JidaWDogSetConfig`
- `JidaWDogDisable`

Porting from JWDOG API to JIDA:

All watchdog functions have been moved to JIDA. All functions have been renamed from `JWDog*` to `JidaWDog*` and now have a JIDA handle and a type as the first two parameters. See `JWDogTst.cpp` and `Jida.h` for details.

Easy steps to convert your application to the new JIDA watchdog API:

- Replace `JWDogInitialize` with `JidaDllInitialize`
- Replace `JWDogUninitialize` with `JidaDllUninitialize`
- Declare a variable `HJIDA hJida;`
- Call `JidaBoardOpen(JIDA_BOARD_CLASS_CPU,0,0,&hJida)` to obtain a JIDA board handle
- Call `JidaBoardClose(hJida)` to free the JIDA handle at the end
- Replace all function prefixes from `JWDog` to `JidaWDog`
- Prefix these two arguments to all watchdog calls: `hJida, 0,`
- Replace the header include from `jwdog.h` to `Jida.h`
- Link with `jida.lib` instead of `jwdog.lib`

JIDA32 Library API Programmer's Reference

JidaDllGetVersion

Declaration

```
DWORD WINAPI JidaDllGetVersion(void);  
Declare Function JidaDllGetVersion Lib "JIDA" () As Long
```

Returns:

The major version number of the API is located in the upper 16 bits and the minor version number of the API in the lower 16 bits of the return value.

Description:

This function returns the version number of the JIDA API. This is the only function that can be called before `JidaDllInitialize()`. To check for version compliance you can compare the major number to the constant `JidaDllVersionMajor` as defined in your version of the header file.

JidaDllInitialize

Declaration

```
BOOL WINAPI JidaDllInitialize(void);  
Declare Function JidaDllInitialize Lib "JIDA" () As Integer
```

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

This initializes the JIDA API for use by the application. A failure indicates that the driver is not properly installed or outdated. Calls to `JidaDllInitialize` and `JidaDllUninitialize` can be nested but must be balanced.

JidaDllUninitialize

Declaration

```
BOOL WINAPI JidaDllUninitialize(void);  
Declare Function JidaDllUninitialize Lib "JIDA" () As Integer
```

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

This function must be called before the application terminates after it has successfully called `JidaDllInitialize`. Calls to `JidaDllInitialize` and `JidaDllUninitialize` can be nested but must be balanced.

JidaDllIsAvailable

Declaration

```
BOOL WINAPI JidaDllIsAvailable(void);  
Declare Function JidaDllIsAvailable Lib "JIDA" () As Integer
```

Returns:

TRUE (1) if a previous call to JidaDllInitialize was successful and the JIDA functionality is available. FALSE (0) on failure.

Description:

This function allows you to determine if the JIDA functionality is available.

JidaDllInstall

Declaration

```
BOOL WINAPI JidaDllInstall(BOOL install);
```

Parameters:

install
TRUE (1) on for install. FALSE (0) for uninstall.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

This function installs or uninstalls the underlying JIDA driver. You can call this function from your setup program or if JidaDllInitialize fails. Note that the system may need to be rebooted for the changes to become effective. Under NT you need administrative rights to use this function successfully. After this function succeeds you can call JidaDllInitialize a second time. If this function fails again then a reboot is required to load the drivers (under Windows 9x). If it succeeds then the drivers have been loaded dynamically and JIDA is ready to be used (under Windows NT and Windows CE). The driver will also load every time you start Windows in the future. Please note that under Windows CE the drivers will only be loaded again if the registry is retained on reboots.

Note that under Windows 9x the JWD0G.VXD which is required by the JidaWDog* functions is never installed automatically by this function. You must add this driver manually. See the Windows 9x installation section.

JidaBoardCount

Declaration

```
DWORD WINAPI JidaBoardCount(LPCTSTR pszClass, DWORD dwFlags);
```

Parameters:

pszClass

The class name of the board. So far the following classes have been defined:

JIDA_BOARD_CLASS_CPU

Basic CPU boards with BIOS

JIDA_BOARD_CLASS_VGA

VGA (LCD) boards with video BIOS

JIDA_BOARD_CLASS_IO

IO cards

This value can be NULL in which case the total number of boards will be returned

dwFlags

Can be any combination of the following flags:

JIDA_BOARD_OPEN_FLAGS_PRIMARYONLY

Count only boards that do have the given class name as a primary class.

Otherwise any boards that fit the given class in any way will be returned.

Returns:

Number of available boards.

Description:

JIDA_BOARD_OPEN_FLAGS_PRIMARYONLY

JidaBoardOpen

Declaration

```
BOOL WINAPI JidaBoardOpen(LPCTSTR pszClass, DWORD dwNum, DWORD dwFlags,  
PHJIDA phJida);
```

Parameters:

pszClass

See JidaBoardCount.

dwNum

Zero based number of the board within the given class.

dwFlags

See JidaBoardCount.

phJida

Pointer to a location that will receive the handle to the board.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

Opens a board that fits the given class.

JidaBoardOpenByName

Declaration

```
BOOL WINAPI JidaBoardOpenByName(LPCTSTR pszName, PHJIDA phJida);
```

Parameters:

pszName

Name of the board. Currently defined names are:

"D101", "D201", "D401", "D501", "P386", "P388", "P488", "P586", "P588", "P489",
"ROI1", "PISB", "LEU1", "LEV1", "LEU2", "LEU3", "LEU6", "MOD1", "MOD2", "MOD5",
"MOD6", "A586", "SIEB", "SIM1", "MODI", "WOB1", "MULTI4", "SPRINT5",
"SPRINT6", "APG1", "MIO2".

phJida

Pointer to a location the will receive the handle to the board.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

JidaBoardClose

Declaration

```
BOOL WINAPI JidaBoardClose(HJIDA hJida);
```

Parameters:

hJida

Board handle.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

Closes the connection to a board.

JidaBoardGetName

Declaration

```
BOOL WINAPI JidaBoardGetName(HJIDA hJida, LPTSTR pszName, DWORD dwSize);
```

Parameters:

hJida

Board handle.

pszName

Location that will receive the name of the board.

dwSize

Size of the buffer location. Should be at least JIDA_BOARD_MAX_SIZE_ID_STRING characters.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

Retrieves the unique name of the board.

JidaBoardGetInfo

Declaration

```
BOOL WINAPI JidaBoardGetInfo(HJIDA hJida, PJIDABOARDINFO pBoardInfo);
```

Parameters:

hJida

Board handle.

pBoardInfo

Location of a JIDABOARDINFO structure that will receive the static information of the board. The structure contains the following information:

DWORD dwSize

Must be initialized by the caller with sizeof(JIDABOARDINFO).

DWORD dwFlags

Reserved. Always 0.

TCHAR szPrimaryClass[JIDA_BOARD_MAX_SIZE_ID_STRING]

Primary class name. See JidaBoardCount for possible values.

TCHAR szBoard[JIDA_BOARD_MAX_SIZE_ID_STRING]

Name of the board. See JidaBoardOpenByName for possible values.

TCHAR szBoardSub[JIDA_BOARD_MAX_SIZE_ID_STRING]

Subname of the board or empty. Usually the same as the board name and of no particular use.

TCHAR szManufacturer[JIDA_BOARD_MAX_SIZE_ID_STRING]

Manufacturer name. Usually "JUMP".

SYSTEMTIME stManufacturingDate

Manufacturing date.

SYSTEMTIME stLastRepairDate

Date that the system was last repaired or refurbished. Valid only if later then the manufacturing date.

TCHAR szSerialNumber[JIDA_BOARD_MAX_SIZE_SERIAL_STRING]

10 character unique serial number of the board

WORD wHardwareRevision

Hardware revision number. Major number in upper byte. Minor number in lower byte.

WORD wFirmwareRevision
Firmware revision number. Major number in upper byte. Minor number in lower byte.

WORD wJidaRevision
BIOS Jida interface revision number. Major number in upper byte. Minor number in lower byte. Only valid if driver has the option of querying the BIOS.

WORD wFeatureNumber
Feature Number of the BIOS or the driver. Usually 0 or 1.

TCHAR szClasses[JIDA_BOARD_MAX_SIZE_CLASSES_STRING]
Comma separated list of all class names that are applicable for the board. See JidaBoardCount for possible values.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

Retrieves a structure that contains information about the board that does not change.

JidaBoardGetBootCounter

Declaration

```
BOOL WINAPI JidaBoardGetBootCounter(HJIDA hJida, LPDWORD pdwCount);
```

Parameters:

hJida
Board handle.

pdwCount
Pointer to location that will receive the value.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

Retrieve the watchdog boot counter.

JidaBoardGetRunningTimeMeter

Declaration

```
BOOL WINAPI JidaBoardGetRunningTimeMeter(HJIDA hJida, LPDWORD pdwCount);
```

Parameters:

hJida
Board handle.

pdwCount
Pointer to location that will receive the value.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

The time period in hours that the system has been running.

JidaBoardGetOption

Declaration

```
BOOL WINAPI JidaBoardGetOption(HJIDA hJida, DWORD dwOption,  
LPDWORD pdwSetting);
```

Parameters:

hJida
Board handle.
dwOption
pdwSetting
Pointer to location that will receive the value.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

No functionality in the current version of JIDA.

JidaBoardSetOption

Declaration

```
BOOL WINAPI JidaBoardSetOption(HJIDA hJida, DWORD dwOption, DWORD  
dwSetting);
```

Parameters:

hJida
Board handle.
dwOption
dwSetting
New value.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

No functionality in the current version of JIDA.

JidaVgaGetContrast

Declaration

```
BOOL WINAPI JidaVgaGetContrast(HJIDA hJida, LPDWORD pdwSetting);
```

Parameters:

hJida
Board handle.
pdwSetting
Pointer to location that will receive the value.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

Retrieves the contrast setting for the LCD of any VGA class board. The value ranges from 0 to JIDA_VGA_CONTRAST_MAX (255).

JidaVgaSetContrast

Declaration

```
BOOL WINAPI JidaVgaSetContrast(HJIDA hJida, DWORD dwSetting);
```

Parameters:

hJida
Board handle.
dwSetting
New value.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

Sets the contrast setting for the LCD of any VGA class board. The value ranges from 0 to JIDA_VGA_CONTRAST_MAX (255).

JidaVgaGetBacklight

Declaration

```
BOOL WINAPI JidaVgaGetBacklight(HJIDA hJida, LPDWORD pdwSetting);
```

Parameters:

hJida
Board handle.
pdwSetting
Pointer to location that will receive the value.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

Retrieves the backlight brightness setting for the LCD of any VGA class board. The value ranges from 0 to JIDA_VGA_BACKLIGHT_MAX (255).

JidaVgaSetBacklight

Declaration

```
BOOL WINAPI JidaVgaSetBacklight(HJIDA hJida, DWORD dwSetting);
```

Parameters:

hJida
Board handle.
dwSetting
New value.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

Sets the backlight brightness setting for the LCD of any VGA class board. The value ranges from 0 to JIDA_VGA_BACKLIGHT_MAX (255).

JidaVgaEndDarkBoot

Declaration

```
BOOL WINAPI JidaVgaEndDarkBoot(DWORD dwReserved);
```

Parameters:

dwReserved
Must be 0.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

This ends the dark boot if that option has been enabled in the BIOS. The screen will be no longer be black and the current Windows screen will be visible.

JidaStorageAreaCount

Declaration

```
DWORD WINAPI JidaStorageAreaCount(HJIDA hJida, DWORD dwType);
```

Parameters:

hJida

Board handle.

dwType

Possible values are:

```
JIDA_STORAGE_AREA_UNKNOWN  
JIDA_STORAGE_AREA_EEPROM  
JIDA_STORAGE_AREA_FLASH  
JIDA_STORAGE_AREA_CMOS  
JIDA_STORAGE_AREA_RAM
```

The only type currently supported is JIDA_STORAGE_AREA_EEPROM and 0.
Use 0 to get the total number of storage areas.

Returns:

Number of available storage areas.

Description:

Retrieves the number of persistent user storage areas of the specified type that are on the given board.

JidaStorageAreaType

Declaration

```
DWORD WINAPI JidaStorageAreaType(HJIDA hJida, DWORD dwType);
```

Parameters:

hJida

Board handle.

dwType

Zero based storage area index.

Returns:

Type of storage area.

Description:

Retrieves the type of storage area.

JidaStorageAreaSize

Declaration

```
DWORD WINAPI JidaStorageAreaSize(HJIDA hJida, DWORD dwType);
```

Parameters:

hJida

Board handle.

dwType

Possible values are a zero based index ORed with one of the following flags:

JIDA_STORAGE_AREA_UNKNOWN

JIDA_STORAGE_AREA_EEPROM

JIDA_STORAGE_AREA_FLASH

JIDA_STORAGE_AREA_CMOS

JIDA_STORAGE_AREA_RAM

The only type currently supported is JIDA_STORAGE_AREA_EEPROM and a index of 0.

Returns:

Size of storage area in bytes.

Description:

Retrives the size of the given storage area.

JidaStorageAreaBlockSize

Declaration

```
DWORD WINAPI JidaStorageAreaBlockSize(HJIDA hJida, DWORD dwType);
```

Parameters:

hJida

Board handle.

dwType

See JidaStorageAreaSize for possible values.

Returns:

Block size of storage area or 0 in not split into blocks.

Description:

No functionality in the current version of JIDA.

JidaStorageAreaRead

Declaration

```
BOOL WINAPI JidaStorageAreaRead(HJIDA hJida, DWORD dwType, DWORD dwOffset, LPBYTE pBytes, DWORD dwLen);
```

Parameters:

hJida
Board handle.

dwType
See JidaStorageAreaSize for possible values.

dwOffset
Zero based offset into the storage area.

pBytes
Pointer to location that will receive the bytes.

dwLen
Number of bytes to read.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

Read bytes from a storage area.

JidaStorageAreaWrite

Declaration

```
BOOL WINAPI JidaStorageAreaWrite(HJIDA hJida, DWORD dwType, DWORD dwOffset, LPBYTE pBytes, DWORD dwLen);
```

Parameters:

hJida
Board handle.

dwType
See JidaStorageAreaSize for possible values.

dwOffset
Zero based offset into the storage area.

pBytes
Pointer to location that contains the bytes.

dwLen
Number of bytes to write.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

Write bytes to the storage area.

JidaStorageAreaErase

Declaration

```
BOOL WINAPI JidaStorageAreaErase(HJIDA hJida, DWORD dwType, DWORD dwOffset, DWORD dwLen);
```

Parameters:

hJida
Board handle.

dwType
See JidaStorageAreaSize for possible values.

dwOffset
Zero based offset into the storage area.

dwLen
Number of bytes to erase.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

No functionality in the current version of JIDA.

JidaStorageAreaEraseStatus

Declaration

```
BOOL WINAPI JidaStorageAreaEraseStatus(HJIDA hJida, DWORD dwType, DWORD dwOffset, DWORD dwLen, LPDWORD lpStatus);
```

Parameters:

hJida
Board handle.

dwType
See JidaStorageAreaSize for possible values.

dwOffset
Zero based offset into the storage area.

dwLen

lpStatus

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

No functionality in the current version of JIDA.

Jidal2CCount

Declaration

```
DWORD WINAPI JidaI2CCount(HJIDA hJida);
```

Parameters:

hJida
Board handle.

Returns:

Number of available I2C buses.

Description:

Retrieves the number of I2C buses on the board.

Jidal2CIsAvailable

Declaration

```
BOOL WINAPI JidaI2CIsAvailable(HJIDA hJida, DWORD dwType);
```

Parameters:

hJida
Board handle.
dwType
Must be 0.

Returns:

TRUE (1) if the give type of I2C bus is present. FALSE (0) otherwise.

Description:

Queries whether the I2C bus of the given type is available. Currently only type 0 is implemented.

Jidal2CRead

Declaration

```
BOOL WINAPI JidaI2CRead(HJIDA hJida, DWORD dwType, BYTE bAddr,  
LPBYTE pBytes, DWORD dwLen);
```

Parameters:

hJida
Board handle.

dwType
Must be 0.

bAddr
Address of the device on the I2C bus.

pBytes
Pointer to location that will receive the bytes.

dwLen
Number of bytes to read.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

No functionality in the current version of JIDA.

Jidal2CWrite

Declaration

```
BOOL WINAPI JidaI2CWrite(HJIDA hJida, DWORD dwType, BYTE bAddr,  
LPBYTE pBytes, DWORD dwLen);
```

Parameters:

hJida
Board handle.

dwType
Must be 0.

bAddr
Address of the device on the I2C bus.

pBytes
Pointer to location that contains the bytes.

dwLen
Number of bytes to write.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

No functionality in the current version of JIDA.

Jidal2CReadRegister

Declaration

```
BOOL WINAPI JidaI2CReadRegister(HJIDA hJida, DWORD dwType, BYTE  
bAddr, WORD wReg, LPBYTE pDataByte);
```

Parameters:

hJida
Board handle.

dwType
Must be 0.

bAddr
Address of the device on the I2C bus.

wReg
Register index of the device.

pDataByte
Pointer to location that will receive the byte.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

Reads a register from a device on the I2C bus.

Jidal2CWriteRegister

Declaration

```
BOOL WINAPI JidaI2CWriteRegister(HJIDA hJida, DWORD dwType, BYTE  
bAddr, WORD wReg, BYTE bData);
```

Parameters:

hJida
Board handle.

dwType
Must be 0.

bAddr
Address of the device on the I2C bus.

wReg
Register index of the device.

bData
Data byte.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

Writes a register from a device on the I2C bus.

JidaIOCount

Declaration

```
DWORD WINAPI JidaIOCount(HJIDA hJida);
```

Parameters:

hJida
Board handle.

Returns:

Number of available IO Ports.

Description:

Always returns 0 in the current version of JIDA.

JidaIOIsAvailable

Declaration

```
BOOL WINAPI JidaIOIsAvailable(HJIDA hJida, DWORD dwType);
```

Parameters:

hJida
Board handle.
dwType

Returns:

TRUE (1) if the give type of IO is present. FALSE (0) otherwise.

Description:

Always returns FALSE in the current version of JIDA.

JidaIORead

Declaration

```
BOOL WINAPI JidaIORead(HJIDA hJida, DWORD dwType, LPDWORD pdwData);
```

Parameters:

hJida
Board handle.
dwType
pdwData

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

No functionality in the current version of JIDA.

JidaIOWrite

Declaration

```
BOOL WINAPI JidaIOWrite(HJIDA hJida, DWORD dwType, DWORD dwData);
```

Parameters:

hJida
Board handle.
dwType
dwData

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

No functionality in the current version of JIDA.

JidaIOXorAndXor

Declaration

```
BOOL WINAPI JidaIOXorAndXor(HJIDA hJida, DWORD dwType, DWORD dwXorMask1, DWORD dwAndMask, DWORD dwXorMask2);
```

Parameters:

hJida
Board handle.
dwType
dwXorMask1
dwAndMask
dwXorMask2

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

No functionality in the current version of JIDA.

JidaWDogCount

Declaration

```
DWORD WINAPI JidaWDogCount(HJIDA hJida);
```

Parameters:

hJida
Board handle.

Returns:

Number of available watchdogs on this board.

Description:

Always returns 0 or 1 in the current version of JIDA.

JidaWDogsAvailable

Declaration

```
BOOL WINAPI JidaWDogIsAvailable(HJIDA hJida, DWORD dwType);
```

Parameters:

hJida
Board handle.
dwType
Must be 0.

Returns:

TRUE (1) if the give type of I2C bus is present. FALSE (0) otherwise.

Description:

Queries whether the watchdog of the given type is available. Currently only type 0 is implemented.

JidaWDogTrigger

Declaration

```
BOOL WINAPI JidaWDogTrigger(HJIDA hJida, DWORD dwType);
```

Parameters:

hJida
Board handle.
dwType
Must be 0.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

This function indicates that the application is still working properly and must be called on a continues basis by the application to ensure that the system will not be restarted. This applies only after that watchdog has been activated.

JidaWDogDisable

Declaration

```
BOOL WINAPI JidaWDogDisable(HJIDA hJida, DWORD dwType);
```

Parameters:

hJida
Board handle.
dwType
Must be 0.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

This disables the watchdog. The application is not longer required to call JidaWDogTrigger.

This function is not implemented in any of the current watchdog versions. Once a watchdog is turned on it can never be turned off again until the next hard reset. This behavior may change in future versions.

JidaWDogSetConfig

Declaration

```
BOOL WINAPI JidaWDogSetConfig(HJIDA hJida, DWORD dwType, DWORD timeout,  
DWORD delay, DWORD mode);
```

Parameters:

hJida
Board handle.
dwType
Must be 0.
timeout
This is the watchdog timeout in milliseconds. The application must continuously call JidaWDogTrigger within that interval to prevent a reboot.
delay
This is an initial delay in milliseconds that will be added to the first timeout period. This allows the application to have a longer initialization phase without calling JidaWDogTrigger and still be protected by the watchdog.
mode
This value can either be:
JWDMoDeRebootPC (0)
This will cause a hard reset without shutting down Windows when the watchdog engages.
JWDMoDeRestartWindows (1)
This will shut down Windows in a proper manner when the watchdog engages. **This behavior is only implemented under Windows 9x.** Other OS call the NMI handler which should be implemented by the Embedded System Designer.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

This function activates the watchdog with the given parameters. After that the application must continuously call JidaWDogTrigger within the specified interval. The timeout value can be changed at any time. The transition from JWDMoDeRebootPC to JWDMoDeRestartWindows can only be made once. After that you cannot revert to JWDMoDeRebootPC. This behavior may change in future versions.

JidaWDogSetConfigStruct

Declaration

```
BOOL WINAPI JidaWDogSetConfigStruct(HJIDA hJida, DWORD dwType,
PJWDCONFIG pConfig);
```

Parameters:

hJida
Board handle.
dwType
Must be 0.
pConfig
Pointer to a PJWDCONFIG structure.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

This function activates the watchdog with the given parameters. After that the application must continuously call JidaWDogTrigger within the specified interval.

JidaWDogGetConfigStruct

Declaration

```
BOOL WINAPI JidaWDogGetConfigStruct(HJIDA hJida, DWORD dwType,
PJWDCONFIG pConfig);
```

Parameters:

hJida
Board handle.
dwType
Must be 0.
pConfig
Pointer to a PJWDCONFIG structure.

Returns:

TRUE (1) on success. FALSE (0) on failure.

Description:

This function is available but will always fail in the current implementation.

JWDCONFIG Data Structure

Declaration

```
typedef struct {  
    DWORD dwSize;  
    DWORD dwTimeout;  
    DWORD dwDelay;  
    DWORD dwMode;  
} JWDCONFIG, * PJWDCONFIG;
```

Parameters:

dwSize

This must be initialized to `sizeof(JWDCONFIG)` before calling any of that functions that deal with this structure.

dwTimeout

This is the watchdog timeout in milliseconds. The application must continuously call `JidawDogTrigger` within that interval to prevent a reboot.

dwDelay

This is an initial delay in milliseconds that will be added to the first timeout period. This allows the application to have a longer initialization phase without calling `JidawDogTrigger` and still be protected by the watchdog.

dwMode

This value can either be:

`JWDMODERebootPC (0)`

This will cause a hard reset without shutting down Windows when the watchdog engages.

`JWDMODERestartWindows (1)`

This will shut down Windows in a proper manner when the watchdog engages.

Description:

This structure is used with `JidawDogSetConfigStruct` and `JidawDogGetConfigStruct`.

Document Revision History

Filename	Date	Edited by	Rev	Alteration to preceding revision
JIDA32.DOC	01.11.98	DP		Initial version!
JIDA32.DOC	11.11.98	C.Riesinger	1.0	Reformatted
JIDA32.DOC	07.06.99	DP	1.1	Updated for JIDA Win32 1.1 Moved Watchdog API to JIDA Driver available for Win NT and Win CE
JIDA32.DOC	21.06.99	DP	1.1	CHAR to TCHAR
JIDA32.DOC	04.04.00	DP	1.2	Windows 2000
JIDA32.DOC	07.03.01	DP	1.3	Changed "JIDA Win32 API" to "JIDA32 Library API" Added Linux and VxWorks platform Added new boards Added hot key LCD support
JIDA32.DOC	04.12.01	DP	1.4	Added new boards Added Windows XP Added VxWorks jida.o Added jidakiss.h Updated Linux section