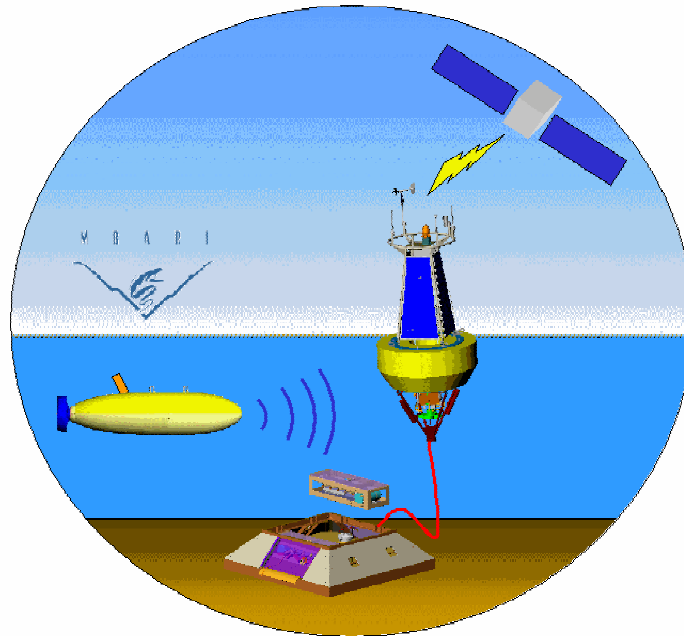


Power Management



Mike Risi

Primary requirement sources

- *MOOS Deployed Subsystem Software Requirements Specification:*
 - 3.2.3, 3.2.13, 3.2.13.1, 3.2.13.2
- *Power Management Software for MOOS Functional Requirements*

Power Management

- Requirements
 - definitions
 - mechanism and policy
 - system and application
- Implementation
 - Phase 1, *Static Power Management*
 - Phase 2, *Power Prediction and Adaptive Power Management*

Power Management Requirements

- Requirements definitions
 - Mechanism - What needs to be done
 - Policy - How that capability is used
 - System - what needs to be done at the Linux kernel/driver level
 - Application - what needs to be done by the SIAM application

Power Management Mechanism

- System
 - running
 - idle
 - sleeping
- Application
 - switching between running and sleeping mode
 - enable and disable instrument power

Power Management Policy

- System
 - How does Linux handle services (e.g. telnetd, ftpd, etc.)

Power Management Policy

- Application - Static Power Management
 - support instrument POWER_ALWAYS, POWER_WHEN_SAMPLING, POWER_NEVER policies
 - enter and exit sleep mode at appropriate time

Power Management Policy

- Application - Power Predication and Adaptive Management
 - interfaces to power subsystems
 - prioritization of energy usage
 - event response power allocation

Power Management - Phase 1

- Implementation of *Static Power Management*
 - System policies
 - SleepManager
 - RMI protection mechanisms
 - InstrumentService
 - PowerManager
 - CommsLeaseListener

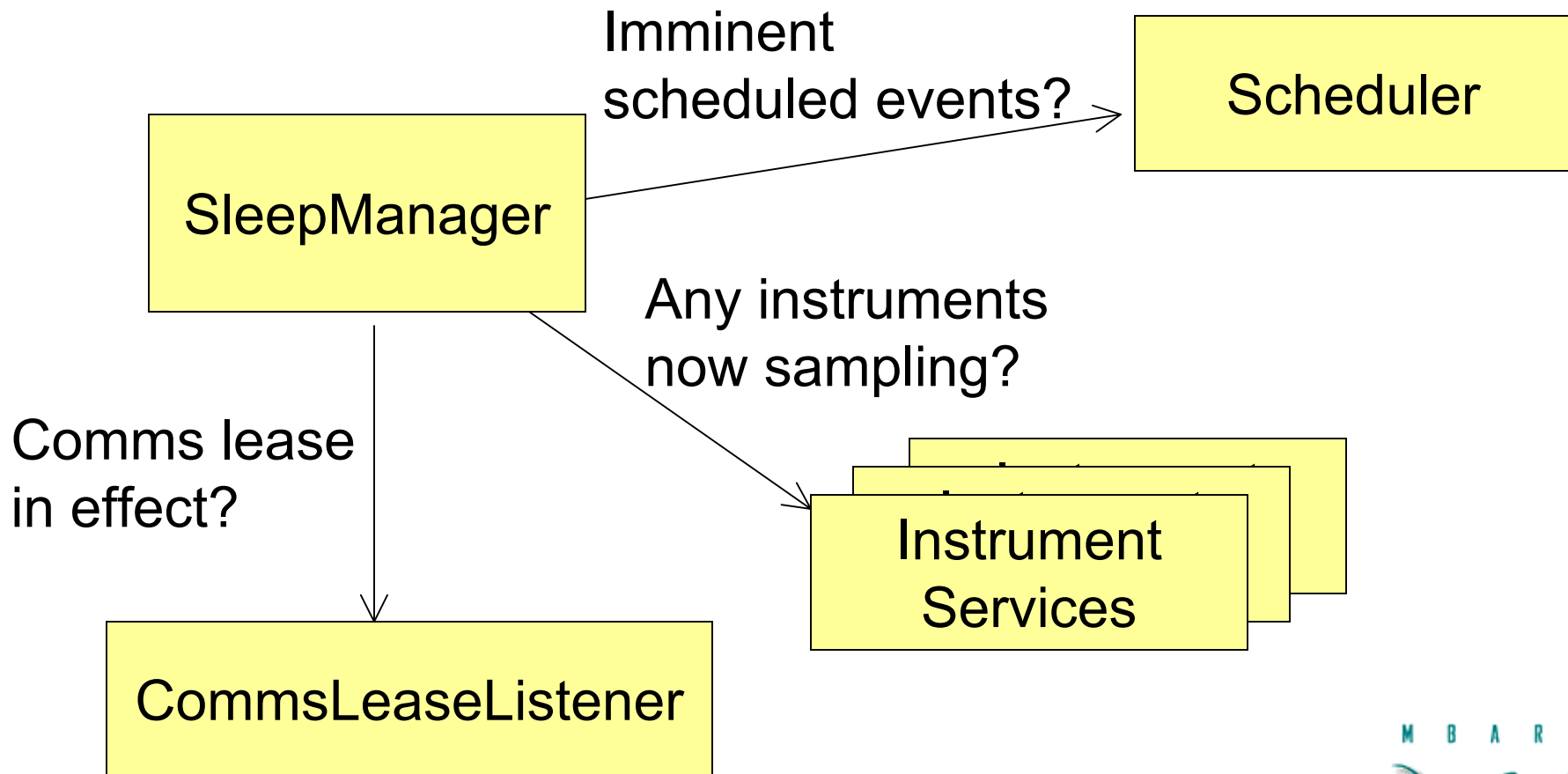
Power Management - Phase 1

- System Policies
 - All normal operations use RMI
 - Linux facilities ftp, ssh, telnet, etc. are not used during normal operation

Power Management - Phase 1

- SleepManager queries subsystems to determine if it is appropriate to go to sleep
 - Scheduler
 - CommsLeaseListener
 - InstrumentService
 - PowerManagedSockets

Power Management - Phase 1



Power Management - Phase 1

- RMI protection mechanisms
 - PowerManagedRMISocketFactory
 - Leasing

Power Management - Phase 1

- InstrumentService
 - instrument power modes
 - POWER_ALWAYS
 - POWER_WHEN_SAMPLING
 - POWER_NEVER
 - InstrumentService status indicates whether it's safe to sleep

Power Management - Phase 1

- **PowerManager**
 - monitors node power usage
 - grants request to InstrumentService for power
- **CommsLeaseListener**
 - power manages communication resources

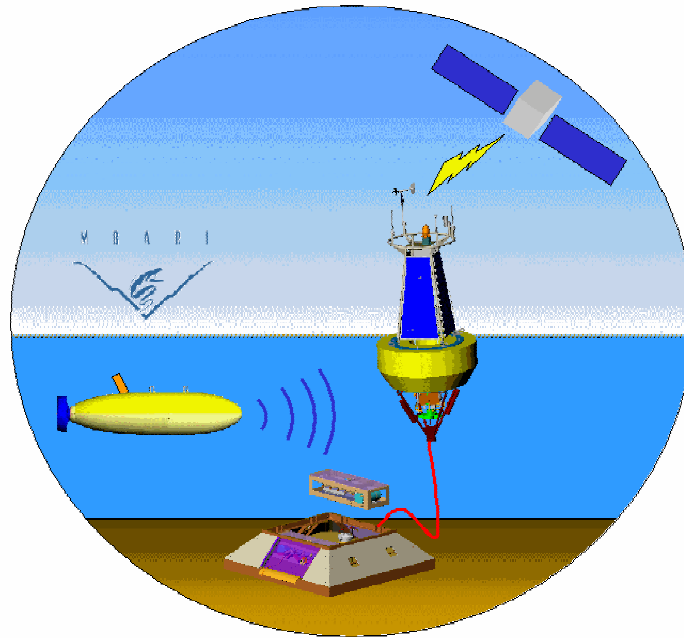
Power Management - Phase 1

- Issues
 - httpd is necessary for RMI codebase
 - Power managed RMI sockets versus leasing
 - MSP430 sleep/wakeup interface
 - ethernet interface
 - spi driver

Power Management - Phase 2

- Implementation of power predication and adaptive management
 - power subsystems
 - prioritization of energy usage
 - event response power allocation

Event Propagation and Response



Mike Risi

Primary requirement sources

- *MOOS Deployed Subsystem Software Requirements Specification:*
 - 3.2.5.4, 3.2.10, 3.2.11, 3.2.12.2, 3.2.17.1, 3.3.5
- *SIAM User Story:*
 - 8

Event propagation

- Definition of events
- Distributed events versus local events
- Events embedded in device data streams
- RMI callbacks
- Jini distributed events

What is an event?

- Event is notification of state change
- Types of events
 - asynchronous events
 - autonomous event response
 - event logs

Distributed versus local events

- Distributed events timely delivery not guaranteed
- Distributed events may arrive out of order
- Distributed events may be lost due network failure

Events embedded in device data streams

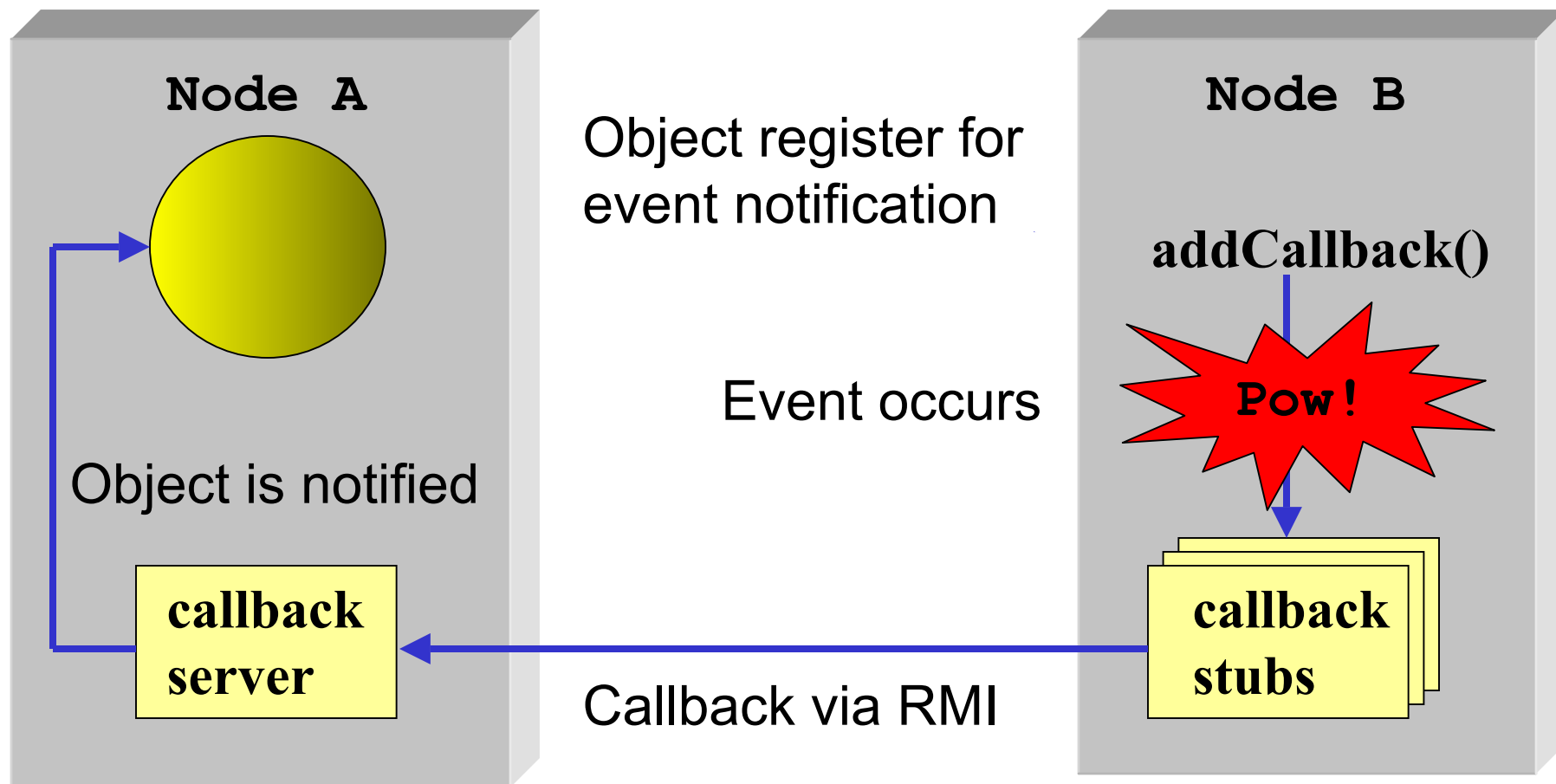
- Metadata packets
 - instruments service starting
 - user changes service property
 - service may autonomously generate metadata
- Message packets
 - port annotation
 - certain types of errors

RMI Callbacks

- RMI callbacks can be used for distributed events
- Nodes already use RMI as standard interface
- Prototyped for GUI notification of instrument state change



RMI Callbacks



RMI Callback Issues

- Subscribed node is sleeping during event
- Network failure occurs during event propagation
- May consume large amounts of bandwidth

Jini Distributed Event Model

- RemoteEventListener uses RMI
- RemoteEvent is small
 - event ID
 - sequence number
 - hand-back object, supplied by consumer may be null
 - reference to event producer



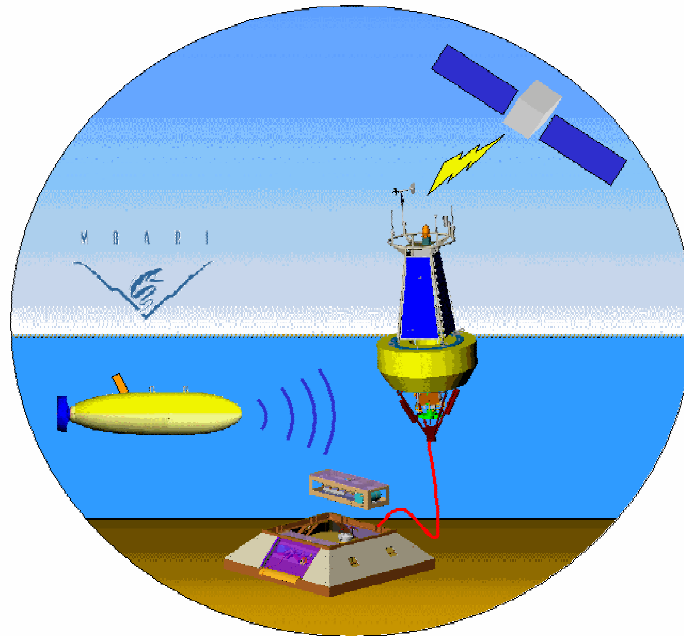
Jini Distributed Event Model

- Third party *registrant*
 - may reside on event consumer, producer, or some other node
 - filters events
 - stores events and forward events
 - addresses network failures
 - addresses sleeping nodes

Jini Distributed Event Model

- While all of Jini may not be appropriate some concepts may be useful
- May be able to use `net.jini.core.event.*` package unmodified

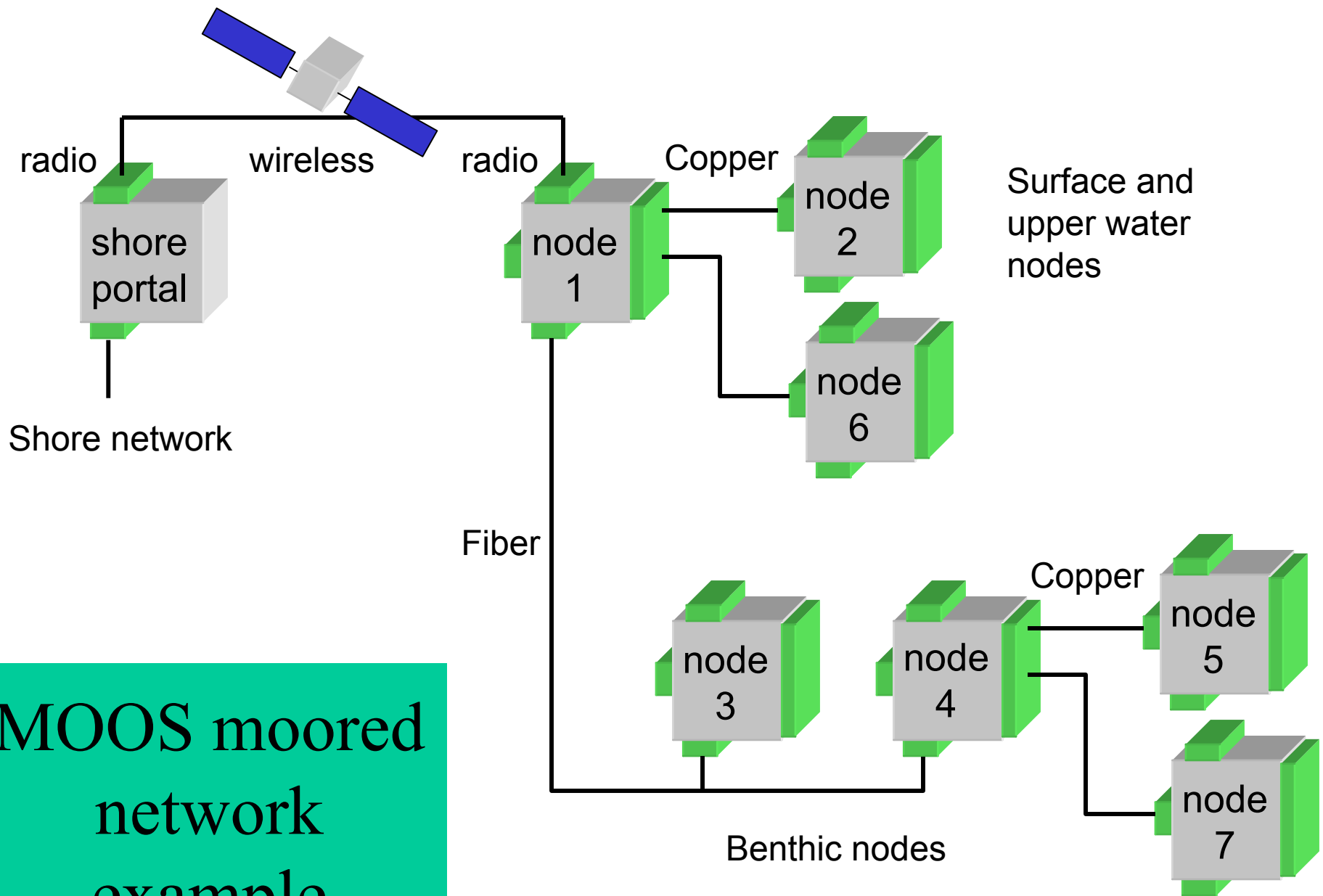
Multi-node Moored Networks



Tom O'Reilly

Primary requirement sources

- *MOOS Deployed Subsystem Software Requirements Specification*
 - 3.2.14, 3.2.19

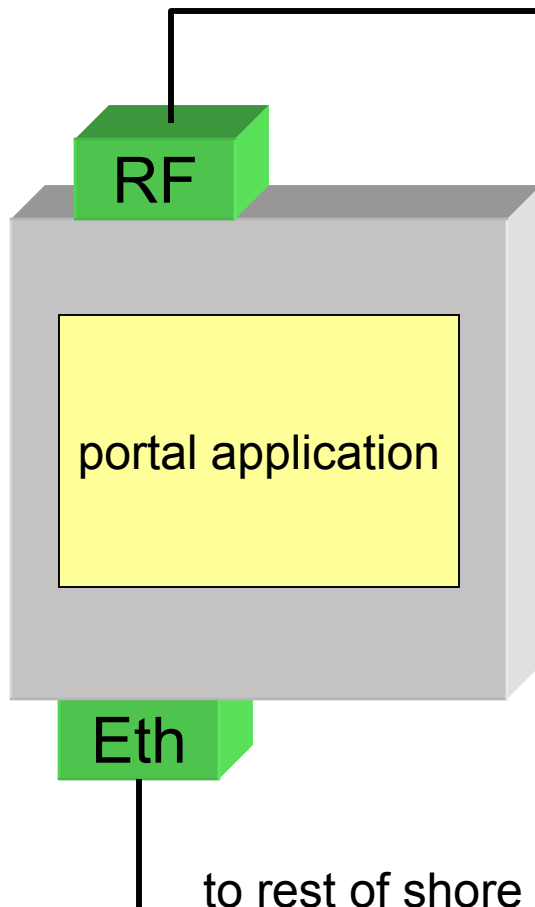


MOOS moored network example

MOOS portal

- Shore-based store-and-forward service over low-bandwidth wireless link
- When RF link is up, forwards commands to moored network, and retrieves data from network
- In general, all traffic between mooring and shore goes through portal

Portal node

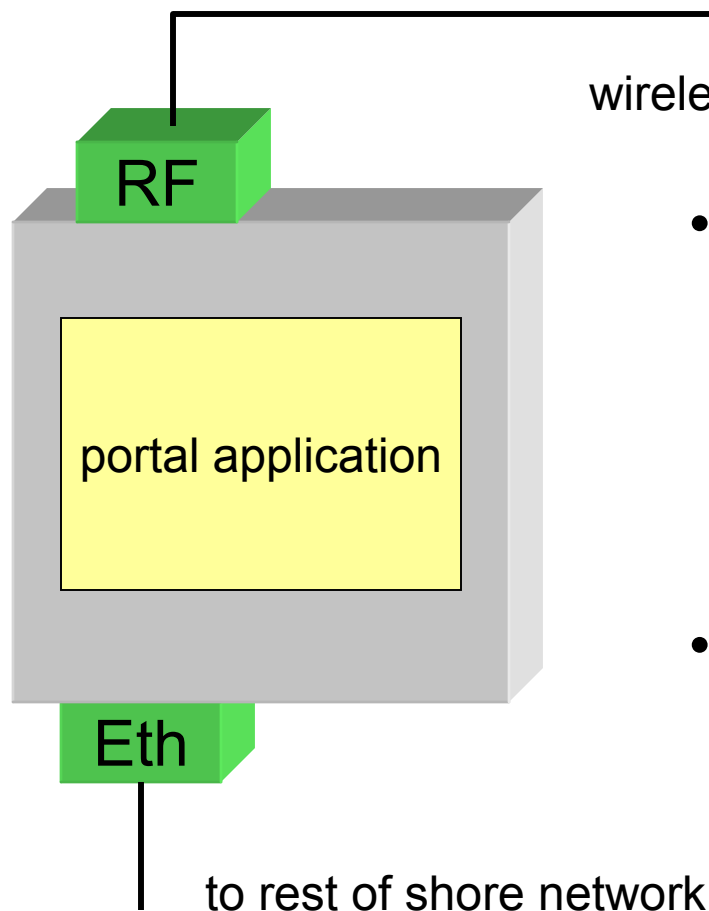


wireless to moored network

- Located on shore (e.g. in MBARI cupola)
- Has two IP interfaces; RF/ppp and ethernet
- Node does NOT route between shore network and moored network
- Hosts portal application

to rest of shore network

Portal application

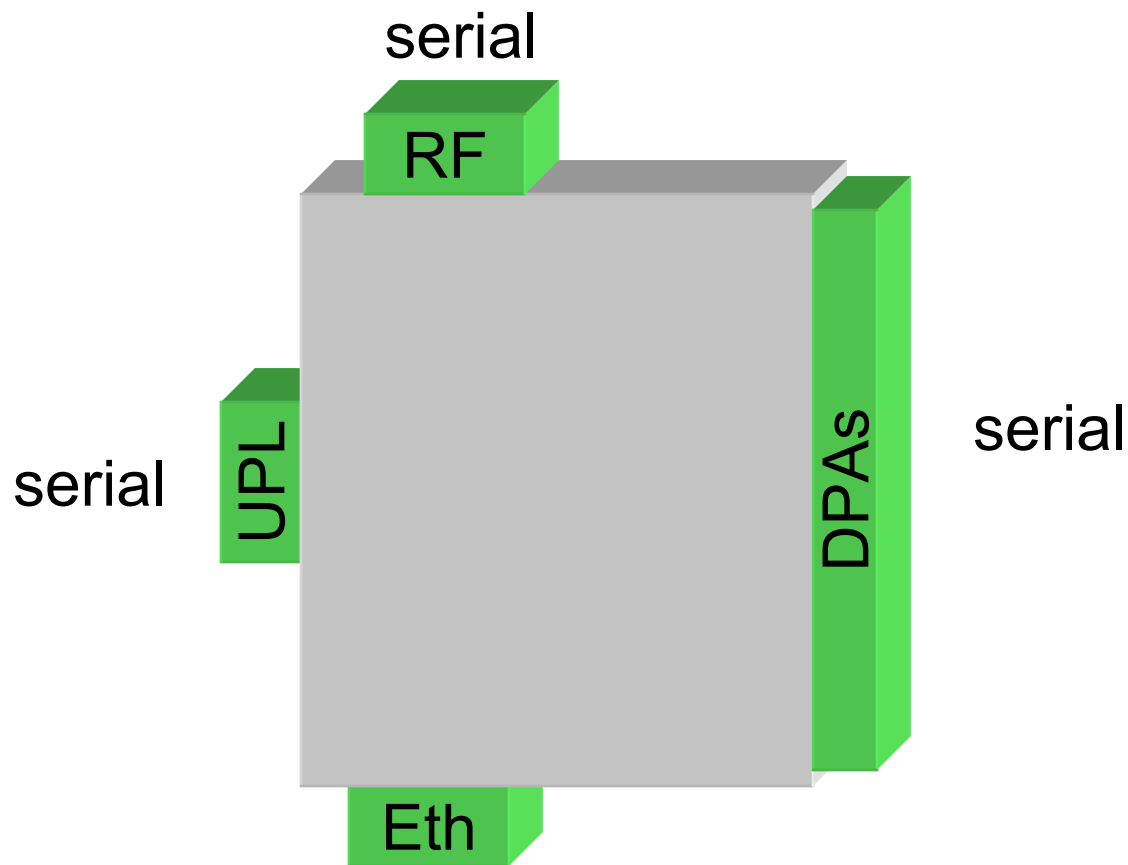


- When wireless link is up, sends commands to mooring nodes, retrieves telemetry from mooring nodes via Java *Remote Method Invocation (RMI)*
- Forwards telemetry to *Shore Side Data System (SSDS)* via Java *Messaging Service (JMS)*

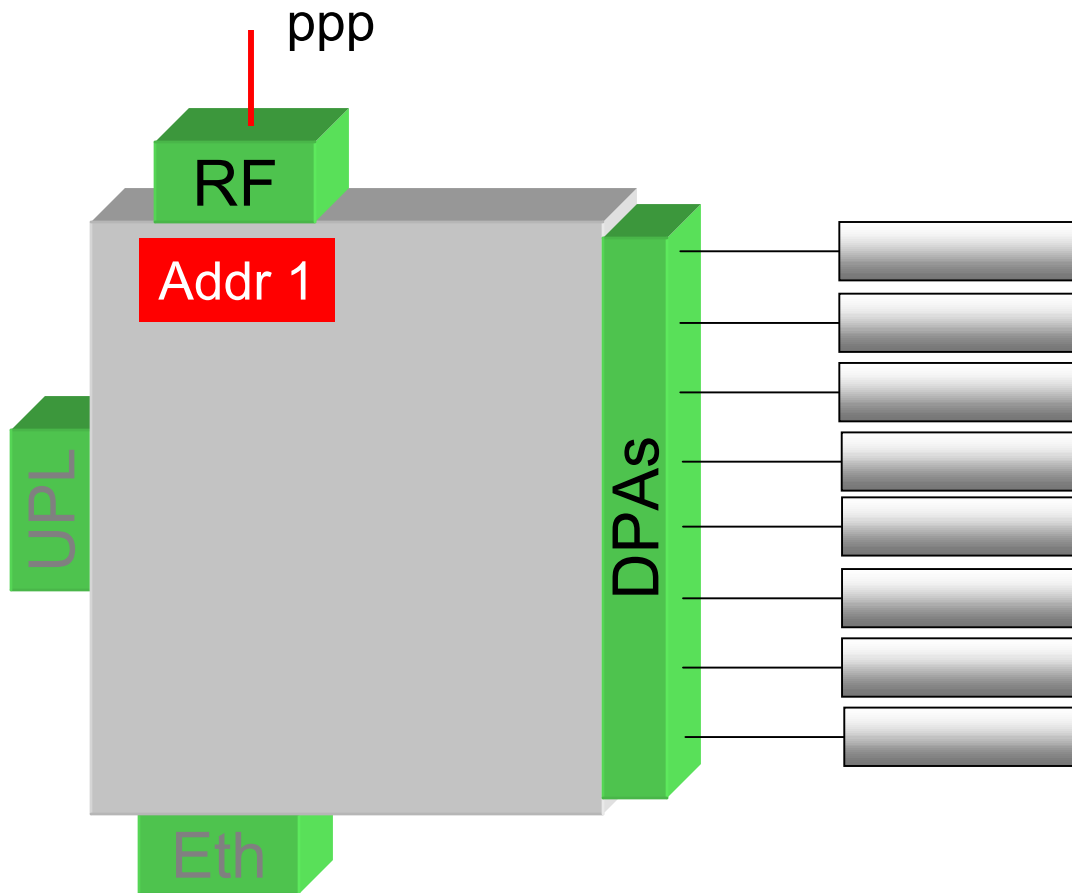
MMC power management

- Mooring power is limited resource
- MMC alternates between *running* and *sleep* states
- Goes to sleep when nothing to do for at least 60 seconds
- Awakened by serial or ethernet traffic, environmental alarm, or at scheduled acquisition time

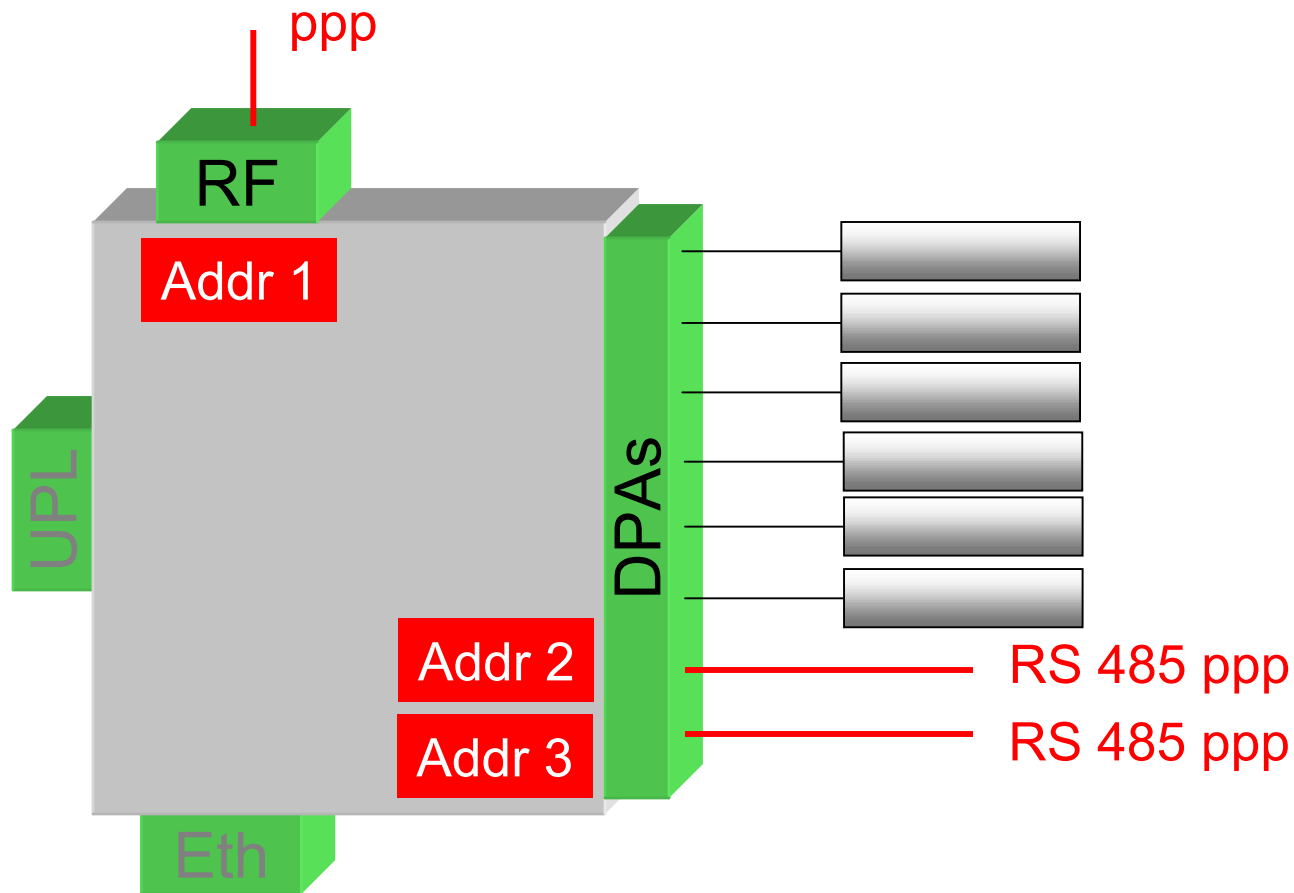
MMC network interfaces



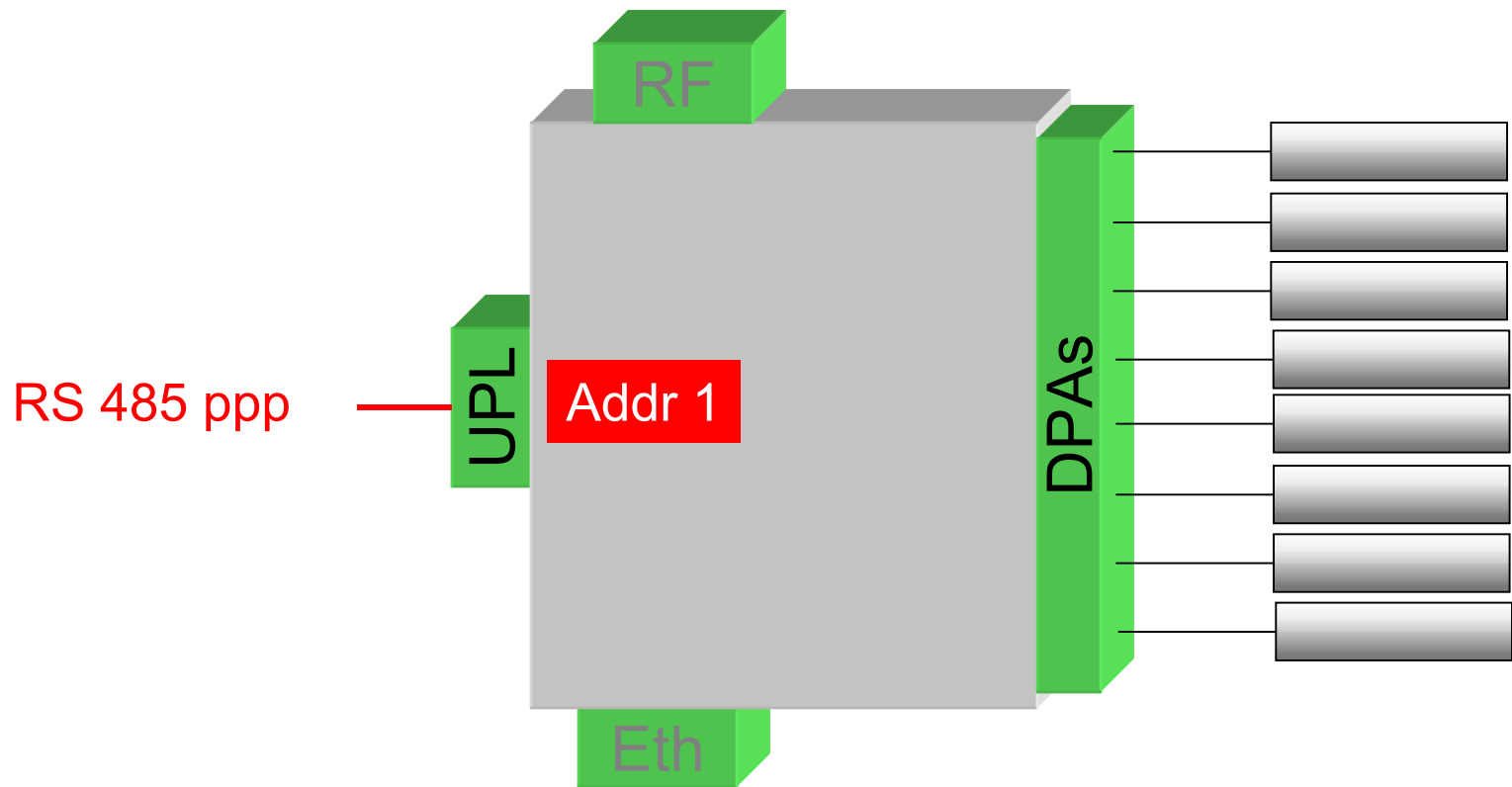
MOOS Lite, single-node



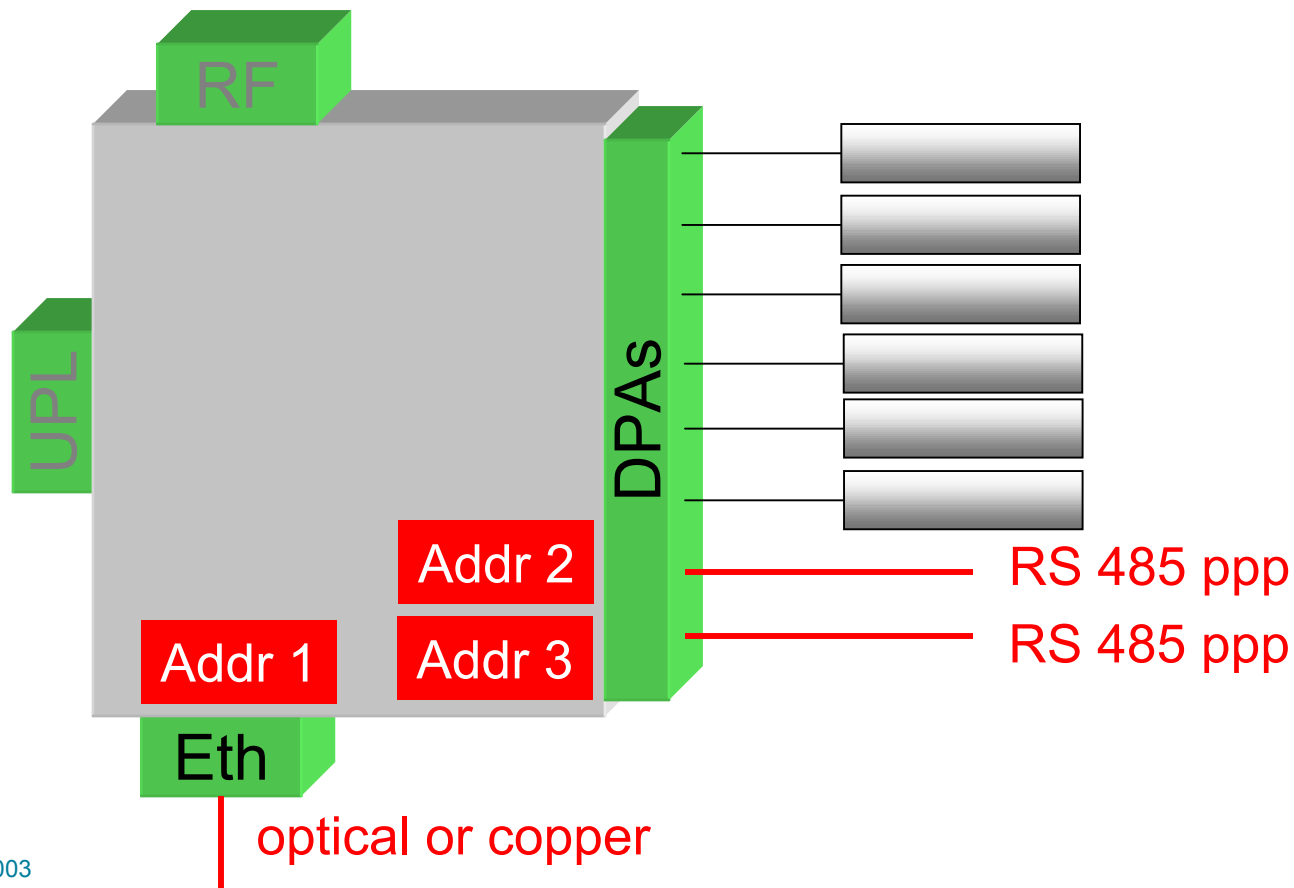
MOOS Lite, surface node



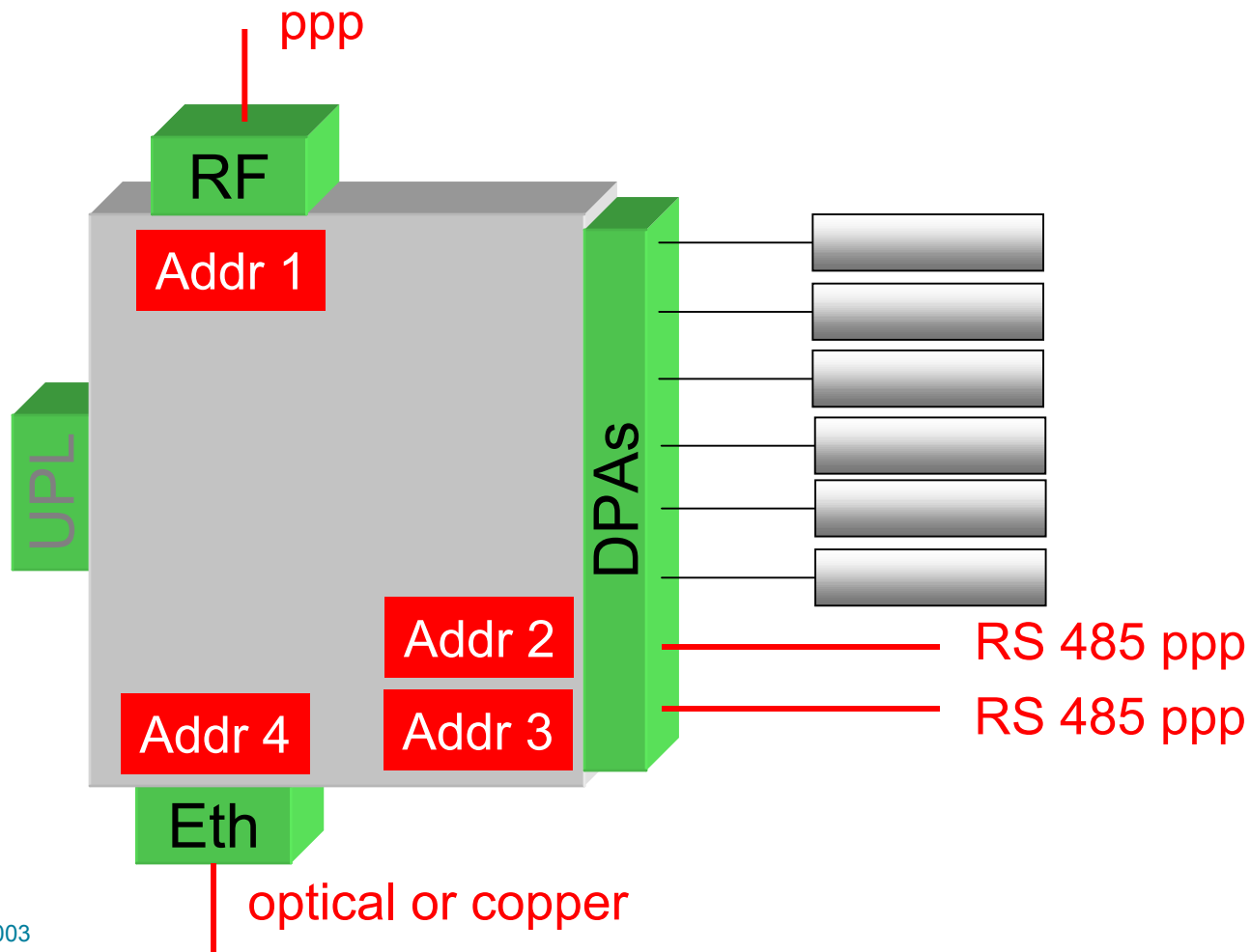
MOOS RS-485 node



MOOS benthic node



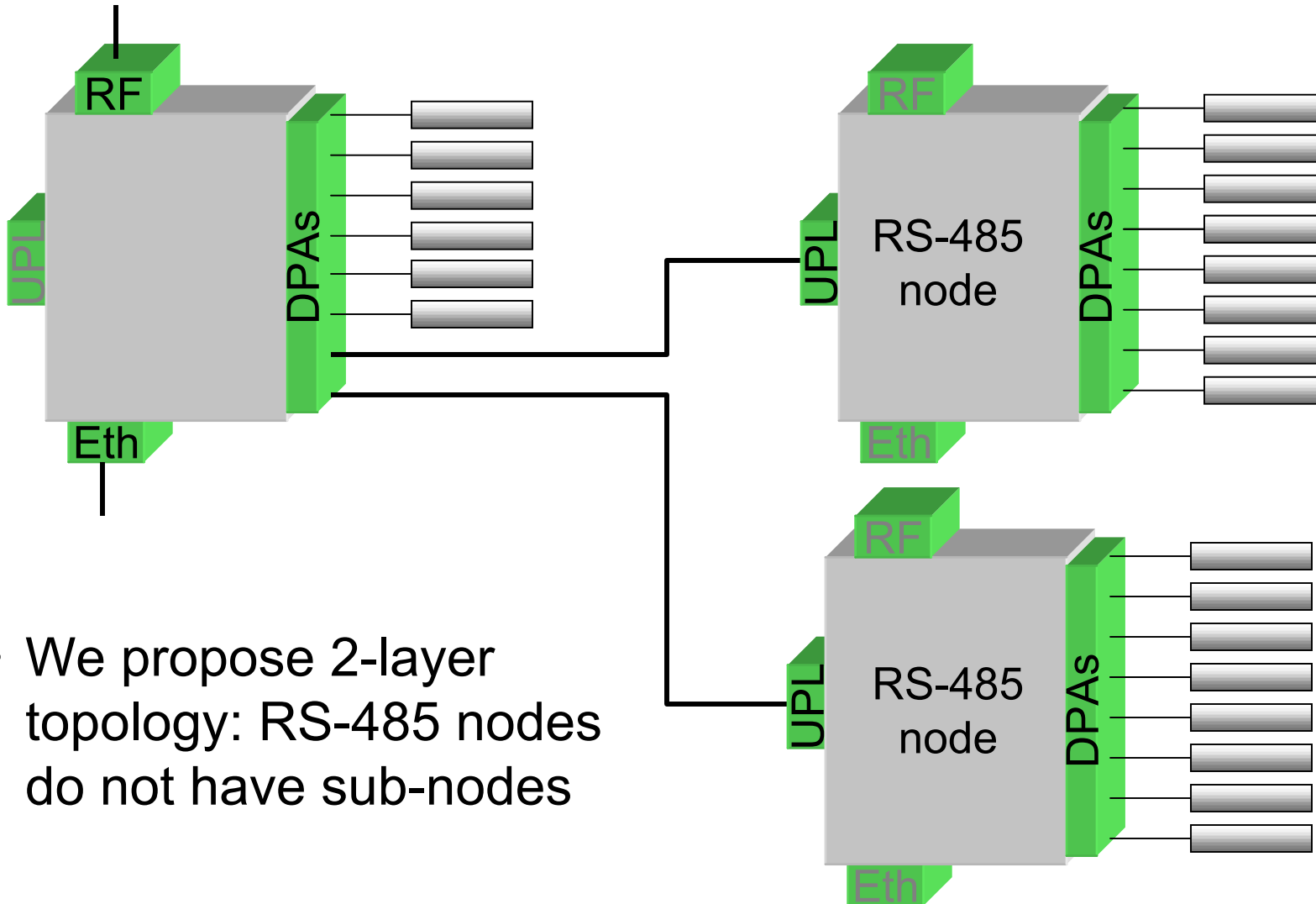
MOOS surface node



Multi-homed nodes

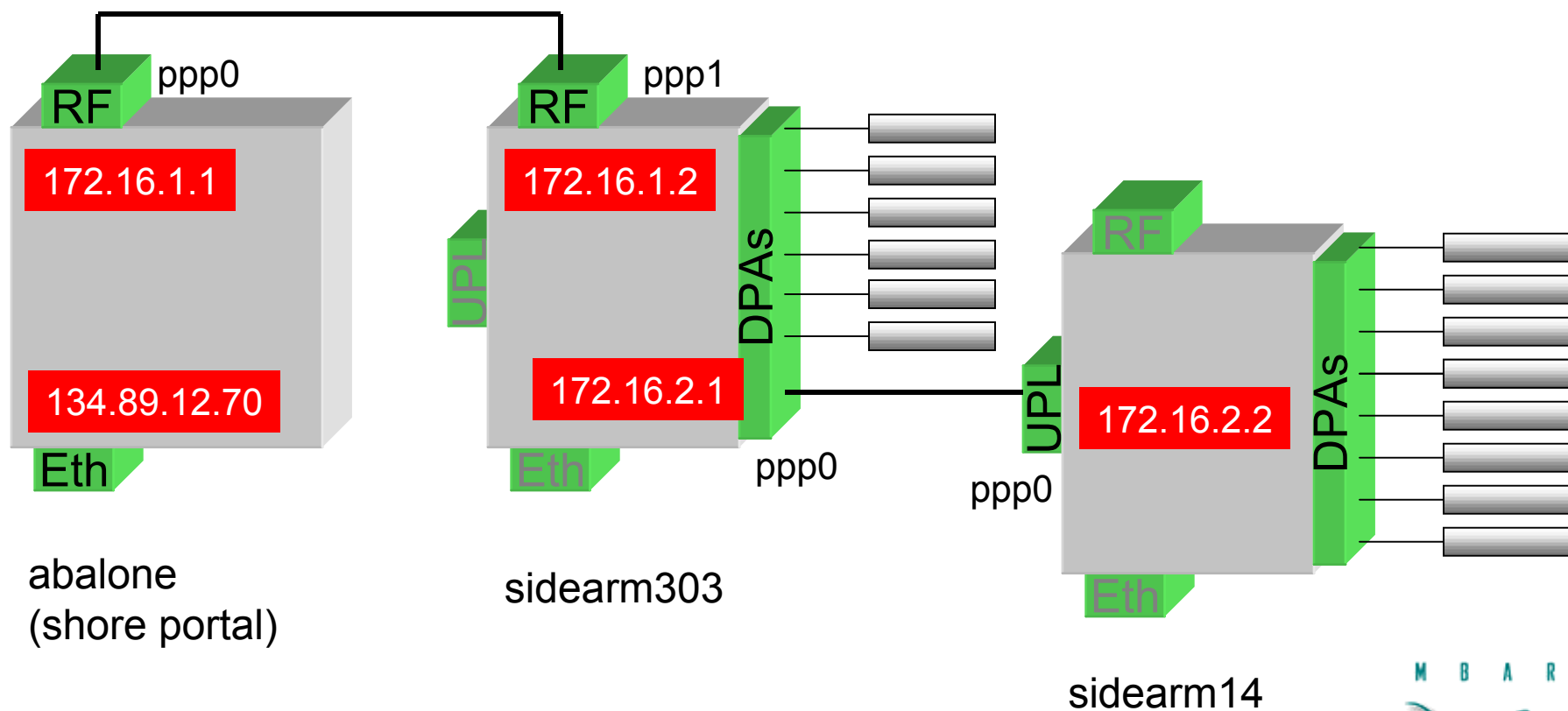
- Some nodes have multiple IP addresses
- Implications for
 - Network configuration and setup, routing
 - RMI configuration

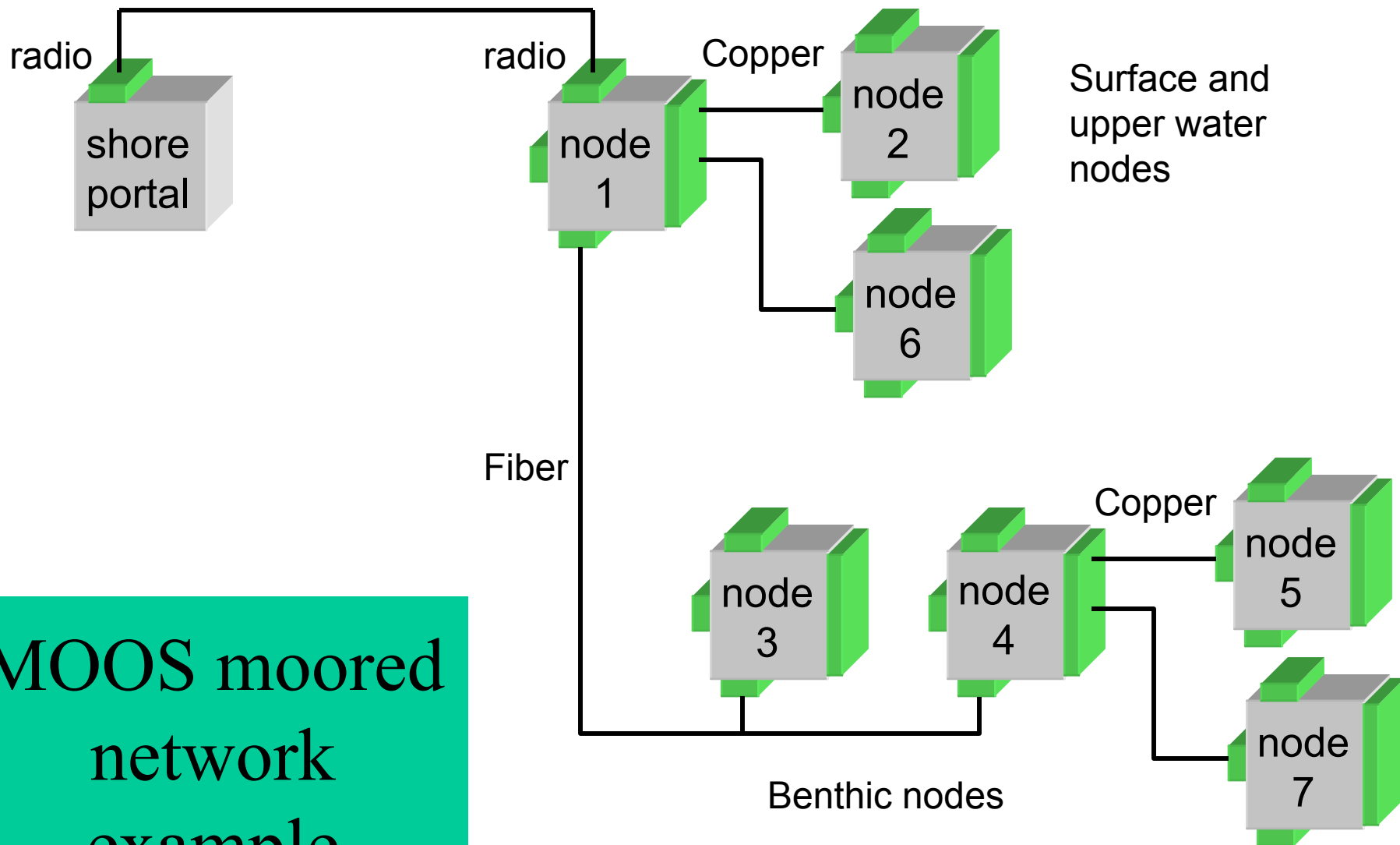
RS-485 node topology



- We propose 2-layer topology: RS-485 nodes do not have sub-nodes

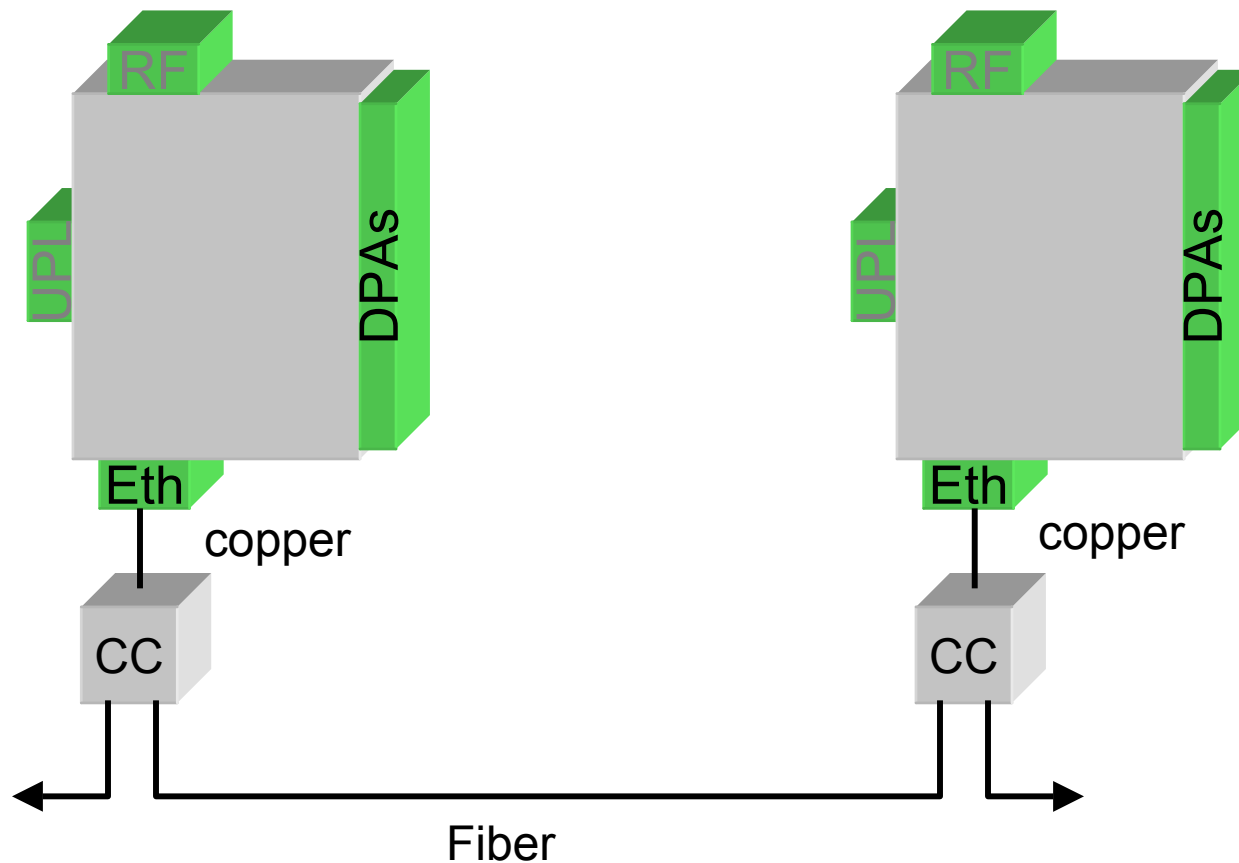
RS-485 node example





MOOS moored network example

Communication controller



Communication controller

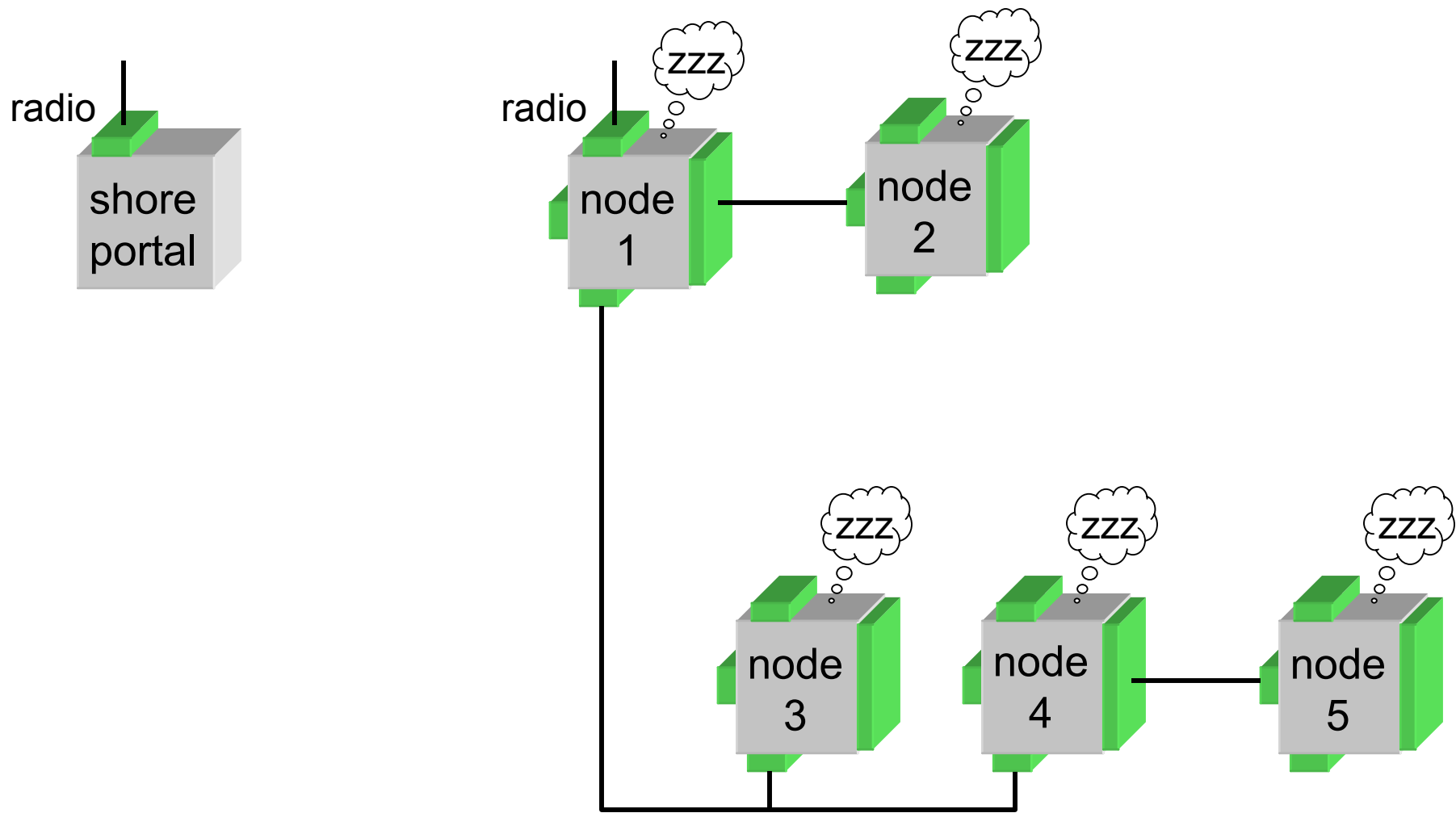
- Reception of multicast or broadcast packet always wakes up SideARM
- Reception of unicast packet wakes up destination SideARM

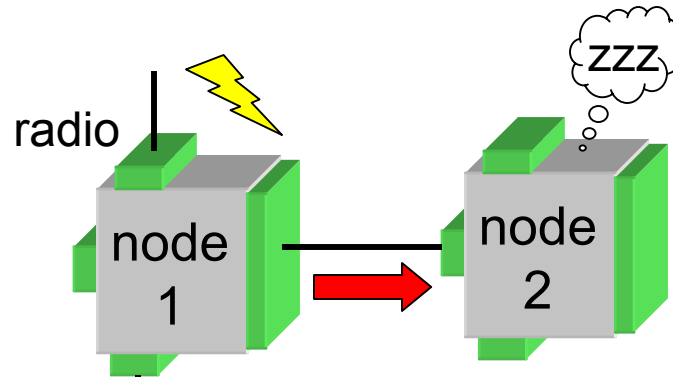
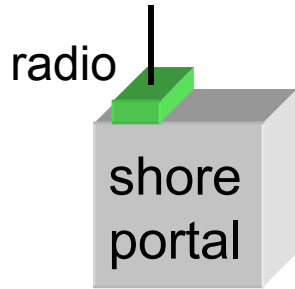
Zeroconf

- Zero-configuration networking
 - Apple has *Rendezvous* implementation
 - Utilizes existing DNS protocols
- IP address assignment, name-to-address translation
 - Applicable to link-local addresses only: no inter-network communications
- Service discovery

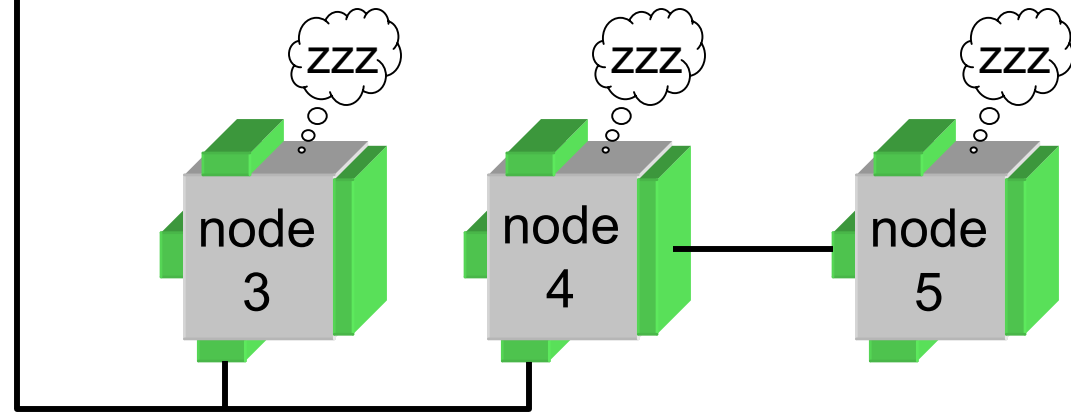
Telemetry management

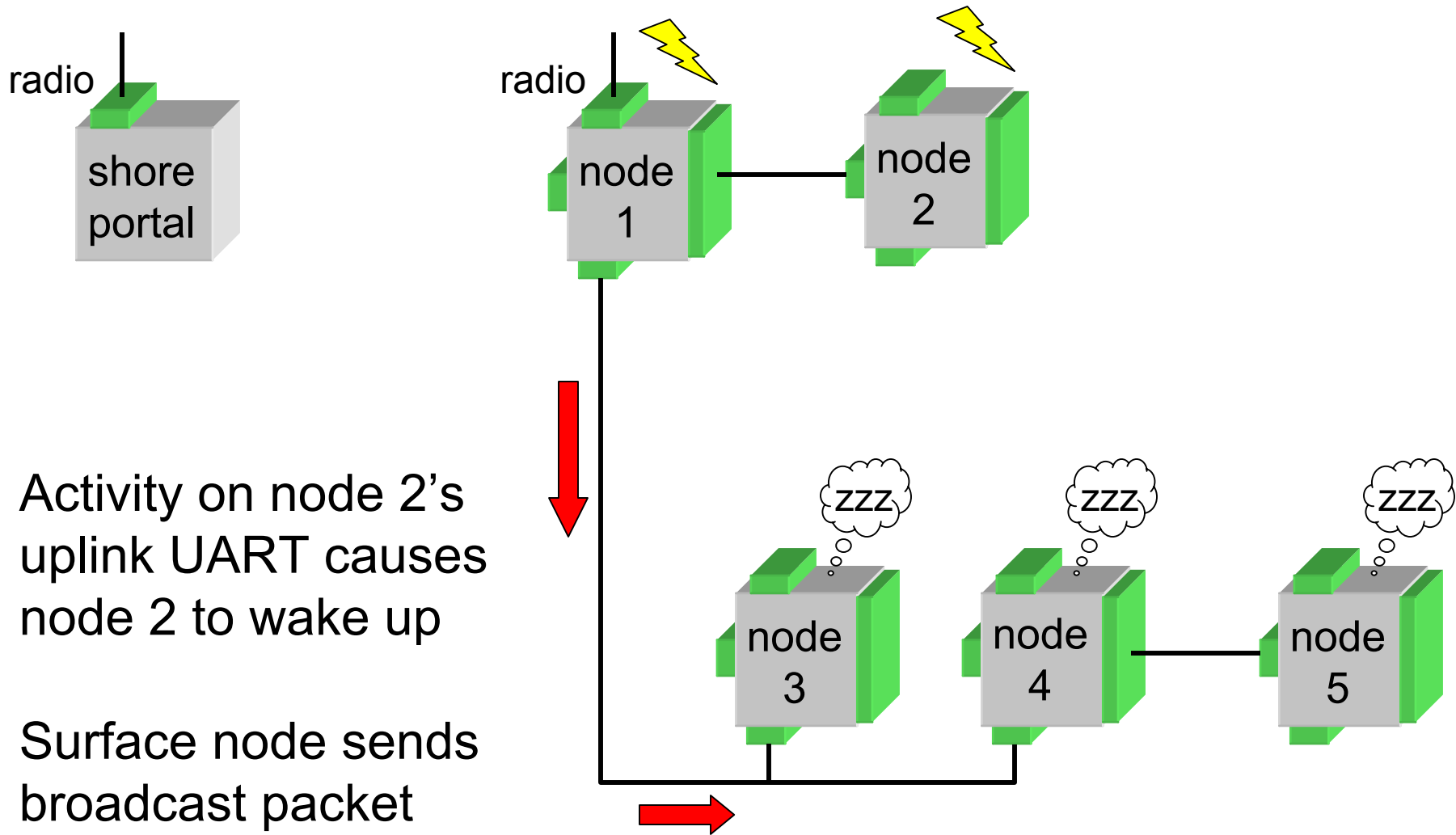
- Portal needn't have *a priori* knowledge of:
 - Moored network node addresses
 - Node power or communications schedules
 - Instruments present on each node



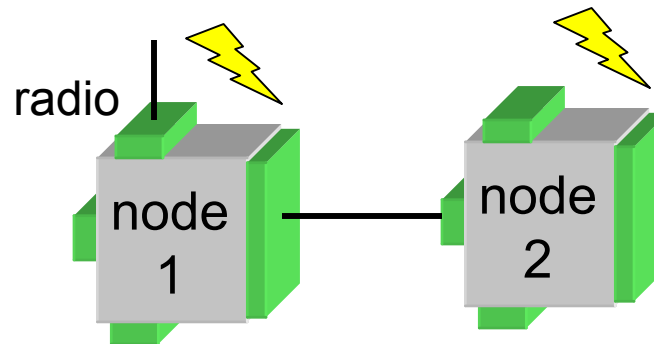
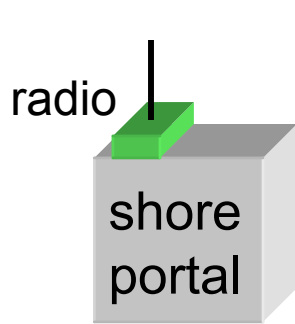


- Surface node wakes up according to telemetry schedule
- Surface node sends broadcast packet through each DPA network interface

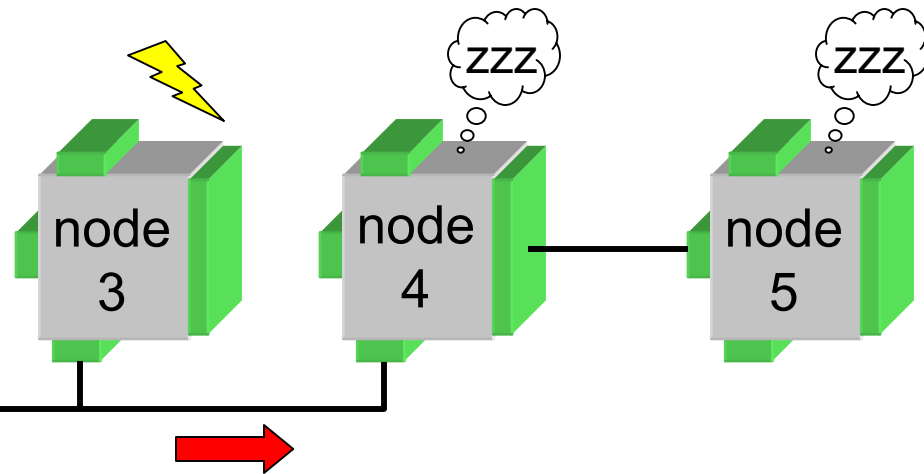




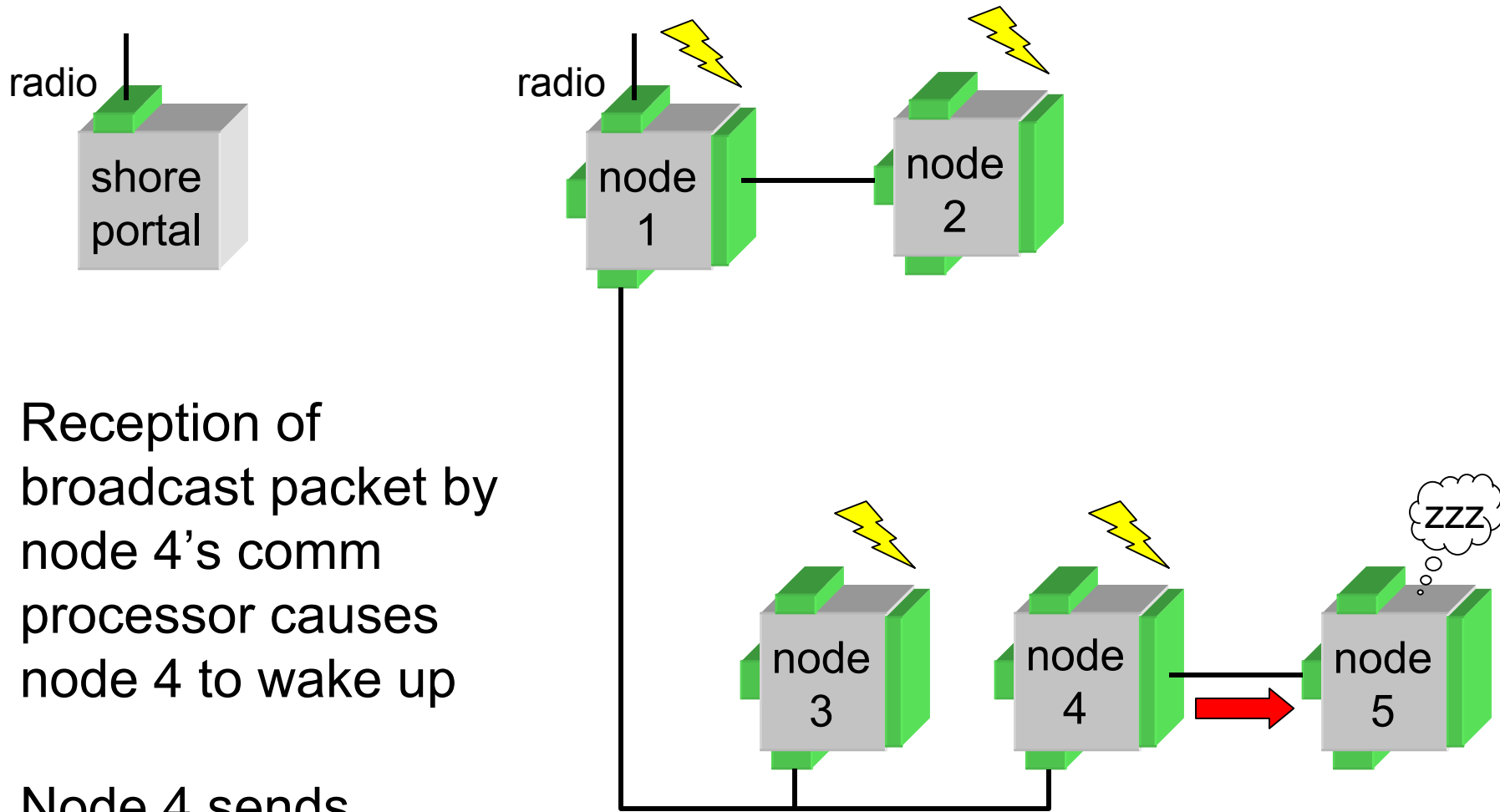
- Activity on node 2's uplink UART causes node 2 to wake up
- Surface node sends broadcast packet through Ethernet interface



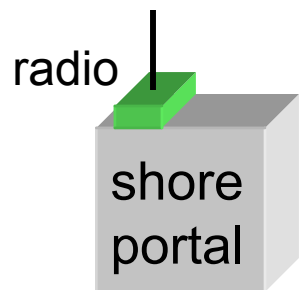
- Reception of broadcast packet by node 3's comm processor causes node 3 to wake up



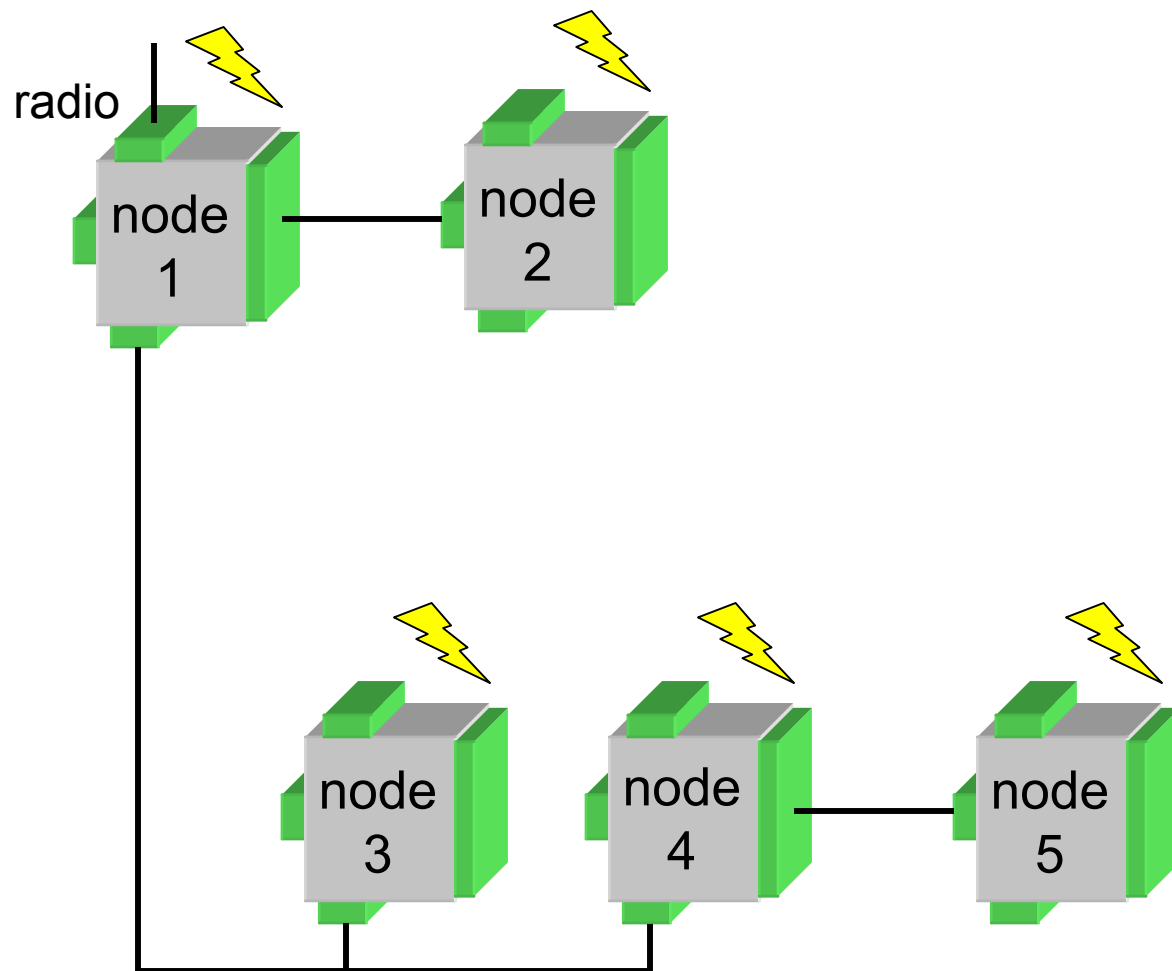
- Node 3's comm processor forwards broadcast packet to node 4



- Reception of broadcast packet by node 4's comm processor causes node 4 to wake up
- Node 4 sends broadcast packet through each DPA network interface

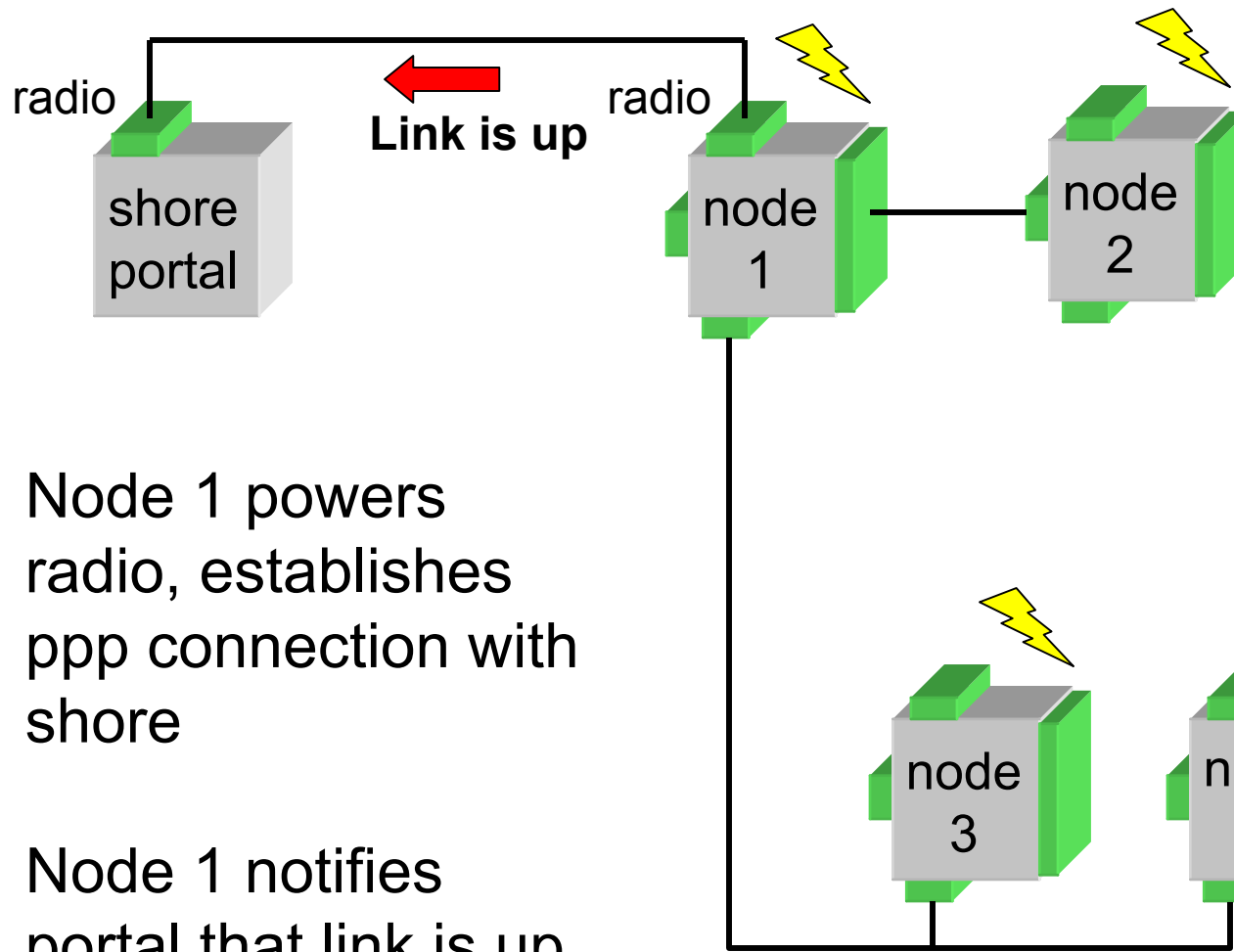


- All nodes now running

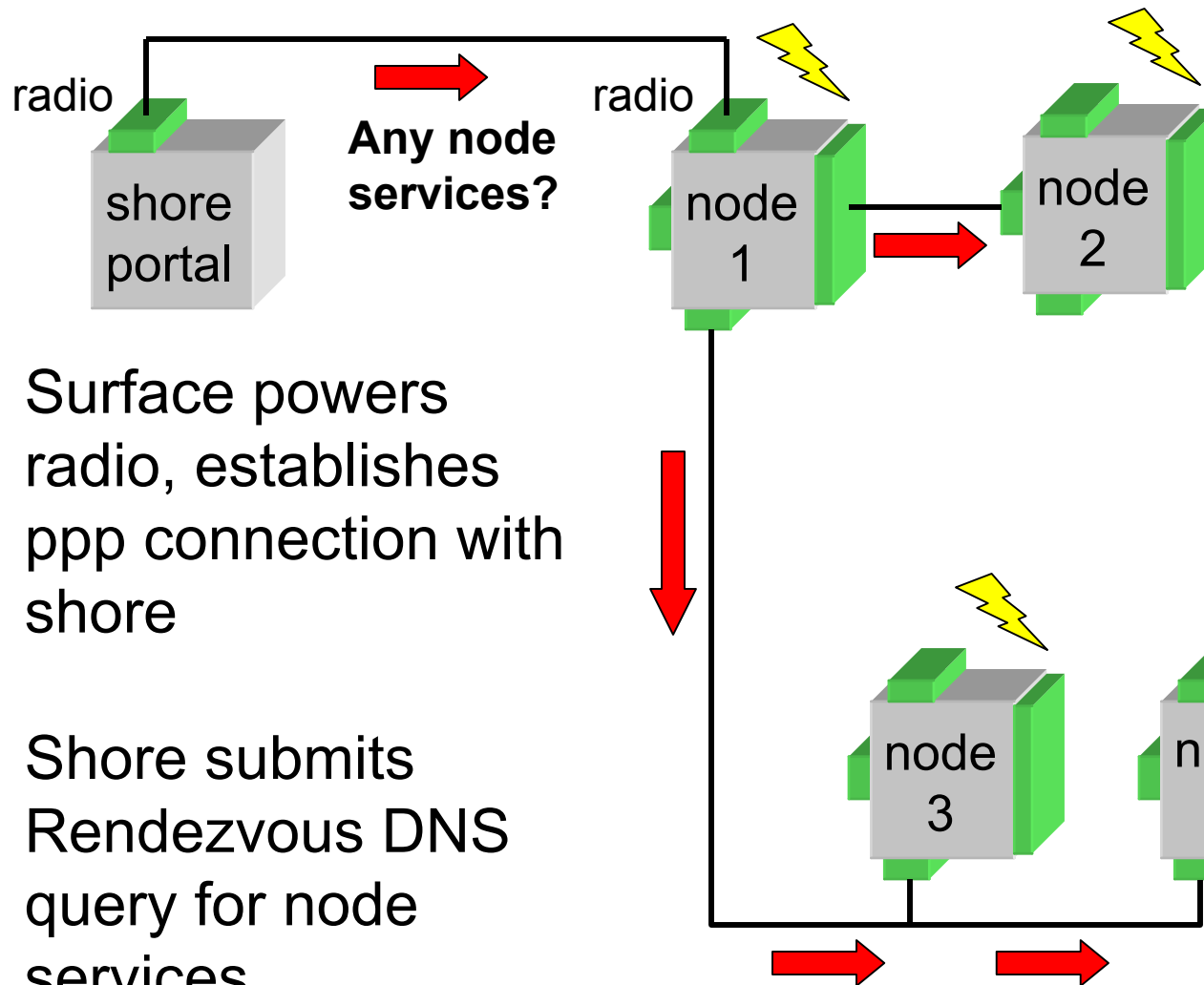


This strategy...

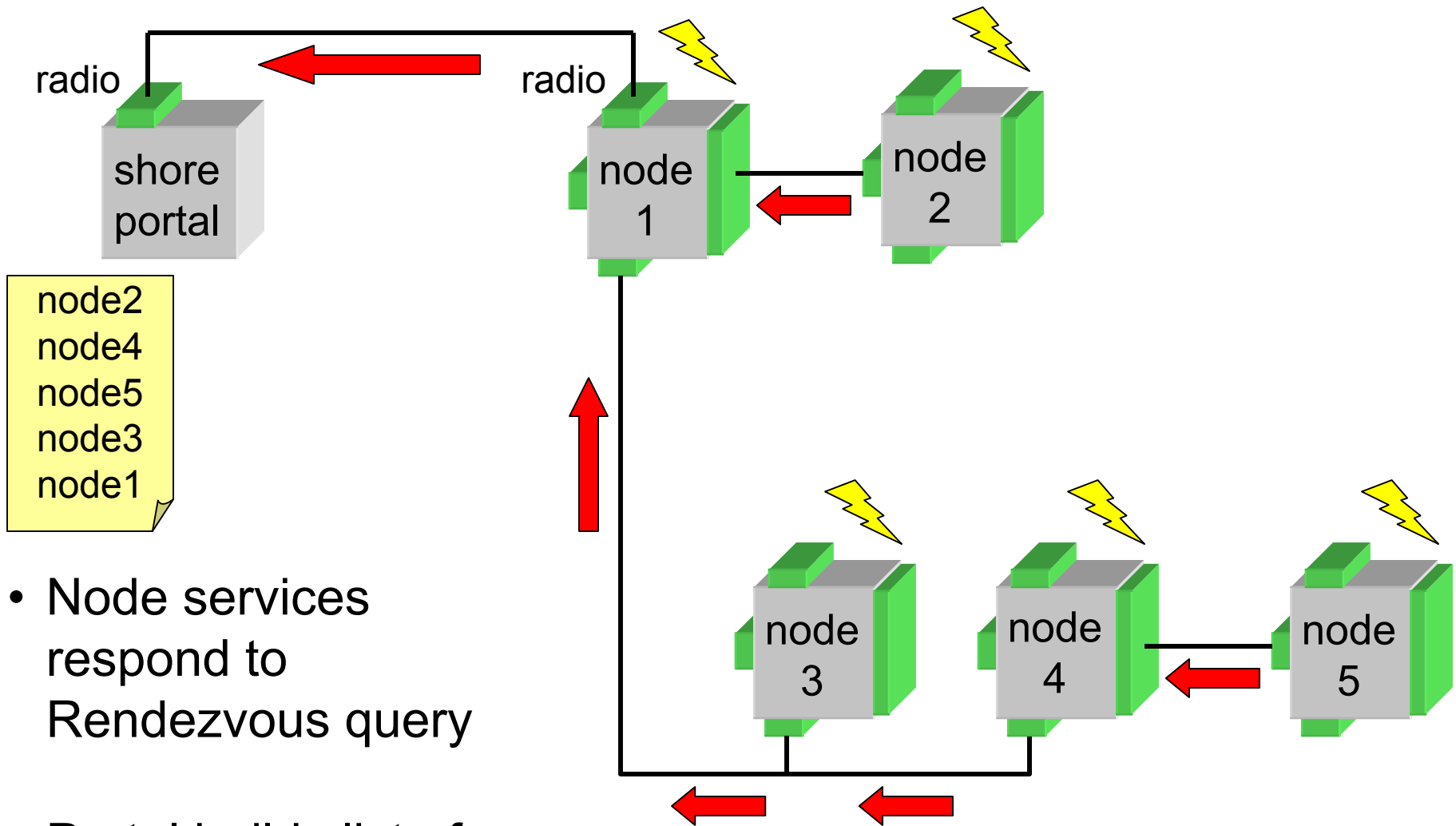
- Nodes don't need to know IP addresses or power schedules of other nodes
- But all nodes get powered on at once for node service discovery and telemetry download



- Node 1 powers radio, establishes ppp connection with shore
- Node 1 notifies portal that link is up



- Surface powers radio, establishes ppp connection with shore
- Shore submits Rendezvous DNS query for node services
- Multicast propagates through network



- Node services respond to Rendezvous query
- Portal builds list of node services

Tools needed for...

- RS-485/ppp link setup
- IP address assignment
- Packet routing

IP address assignment: Ethernet interfaces

- DHCP, automatic address allocation
 - DHCP server assigns client node an address which is valid until client reboots

DHCP

- *Automatic address allocation*
 - DHCP server assigns client node an address which is valid until client reboots
- We don't need the more complex *dynamic address allocation*

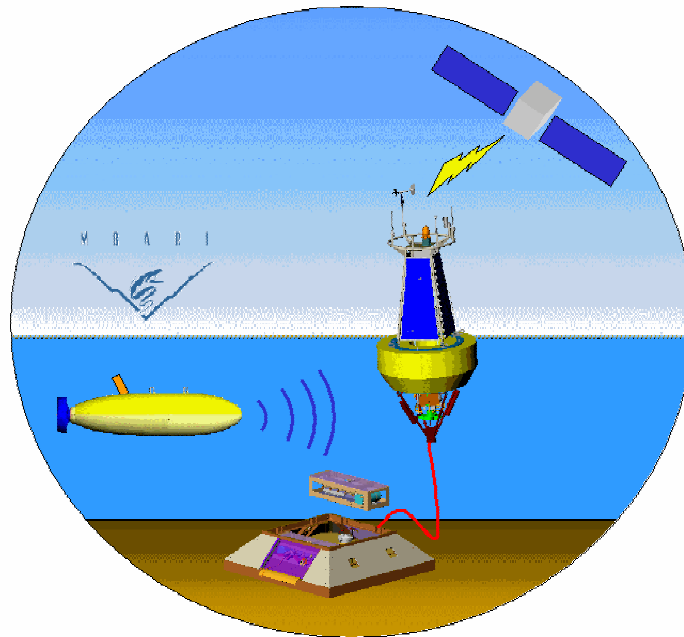
DHCP: interaction with power management

- Sleeping DHCP server: client request via *limited broadcast* will wake it
- Sleeping client: Clients should use *automatic allocation*, which does not require a lease
- Client requests address via broadcast protocol; new client will wake all nodes on network

IP address assignment: serial interfaces

- PPP endpoint assignment
 - Preconfigured before deployment?

Security



Kent Headley

Security

- Requirements
 - Current status
- Issues
 - General concerns
- Plan
 - How to proceed

Primary requirement source(s)

- *SIAM Deployed Software Requirements*
 - 3.7
- *SIAM Operations Software Requirements*
 - 2.2.6
- *Note: both referenced sections are empty!*

Security Requirements

SIAM security requirements

- Not well defined
- No users have set requirements, but there may be implicit assumptions :
 - Science users
 - data privacy
 - administrative privileges
 - Operations users
 - access control
 - Information systems
- Defining requirements will require input from experts



Security Issues

- Wireless access
 - New vulnerabilities
 - Level of importance
- Access control
 - Policies and mechanisms
- Data privacy
 - Protecting ‘proprietary’ data
- Control of bandwidth use
 - Intentional and inadvertent misuse

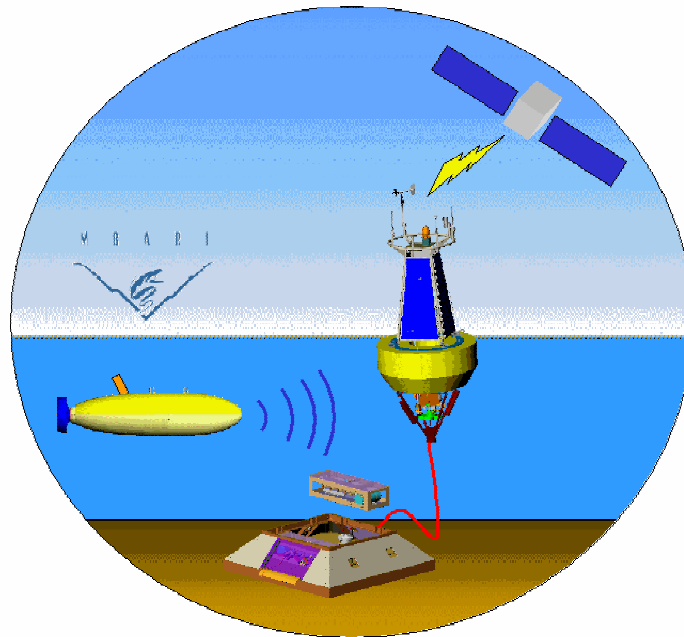
Security Issues

- Protecting access points
 - Balancing security and operational simplicity
- System activity monitoring
 - How much is needed
- Protocol selection
 - device discovery, event propagation, general networking
- Others...

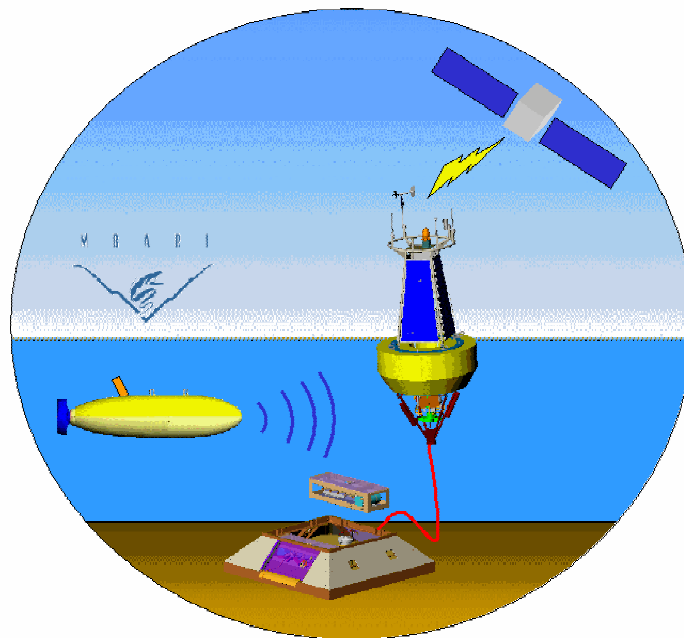
Security Plan

- Gather good requirements
 - Users (including as yet unidentified users)
 - Consult experts
- Construct security policies
- Examine architectural issues
 - Understand state of the art
 - Trade studies
 - Policy vs technology
- Develop design and phased implementation plan

Break



Fault Tolerance



Tom O'Reilly

Primary requirement sources

- *SIAM Behaviors Required by SSDS:*
 - numerous requirements
- *MOOS Deployed Subsystem Software Requirements Specification*
 - numerous requirements
- *MOOS Operations Subsystem Software Requirements Specification*
 - numerous requirements

Deployed file system fault-tolerance

- Onboard FLASH utilizes journaling JFFS2 file system
 - Less prone to corruption
- Compact FLASH file system could be upgraded to EXT3 (journaling)

Network fault-tolerance

- RMI distributed objects
 - Underlying TCP-IP includes retry mechanisms
 - RMI exception mechanisms allow applications to handle network failures
 - If RMI method call completes, very high confidence that data was transferred properly

Network fault-tolerance

- Portal
 - Keeps track of retrieved packet time-stamps; “picks up where it left off” each time RF link is restored
 - Network exception handling
 - Stores retrieved packets as well as distributes to SSDS

Network fault-tolerance

- Service discovery enables applications to respond to network failures
- Investigating event propagation mechanisms for intermittent networks (e.g. Jini events)

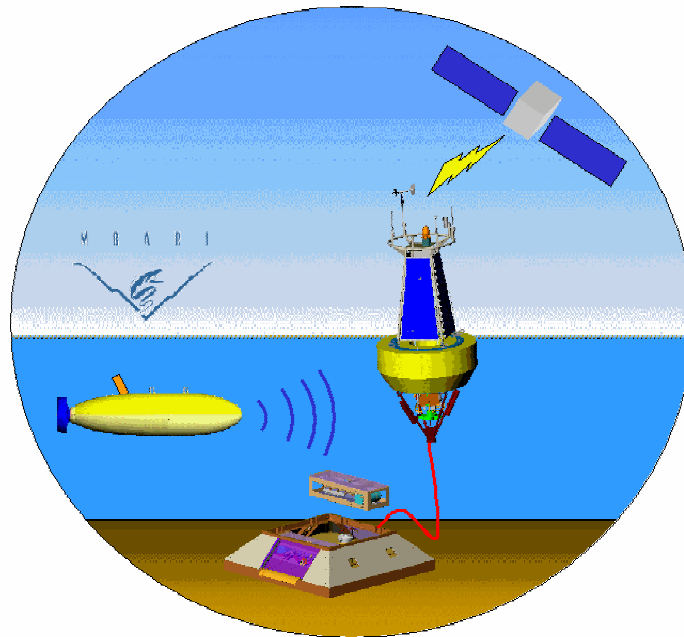
Issues

- What are requirements for automatic handling of environmental alarms and ground faults?

Issues

- Watchdogs
 - Software watchdog
 - RF communications watchdog
 - DPA safety watchdog
 - Others?

Revision Control, Bug Tracking



Mike Risi

Bug tracking and revision control

- Bug tracking system
- Revision control
- Debug message logging

Bug tracking system

- phpBugTracker
 - uses php scripting language
 - freely available at <http://phpbt.sourceforge.net/>
 - users and developers can create account and enter bugs

CVS revision control

- Use CVS for software revision control
 - developers have access to all modules
 - anyone on MBARI network can view code at anytime via [web interface](#)
 - user meeting and deployment releases are tagged
 - many clients available
 - WinCVS • gCVS • MacCVS
 - CLI • editor support (e.g. Visual SlickEdit)

Log4j message logging

- Log4j logging module used for all system error and information debug messages
- Messages can be directed to different message consumers via appenders
 - console
 - sockets
 - files

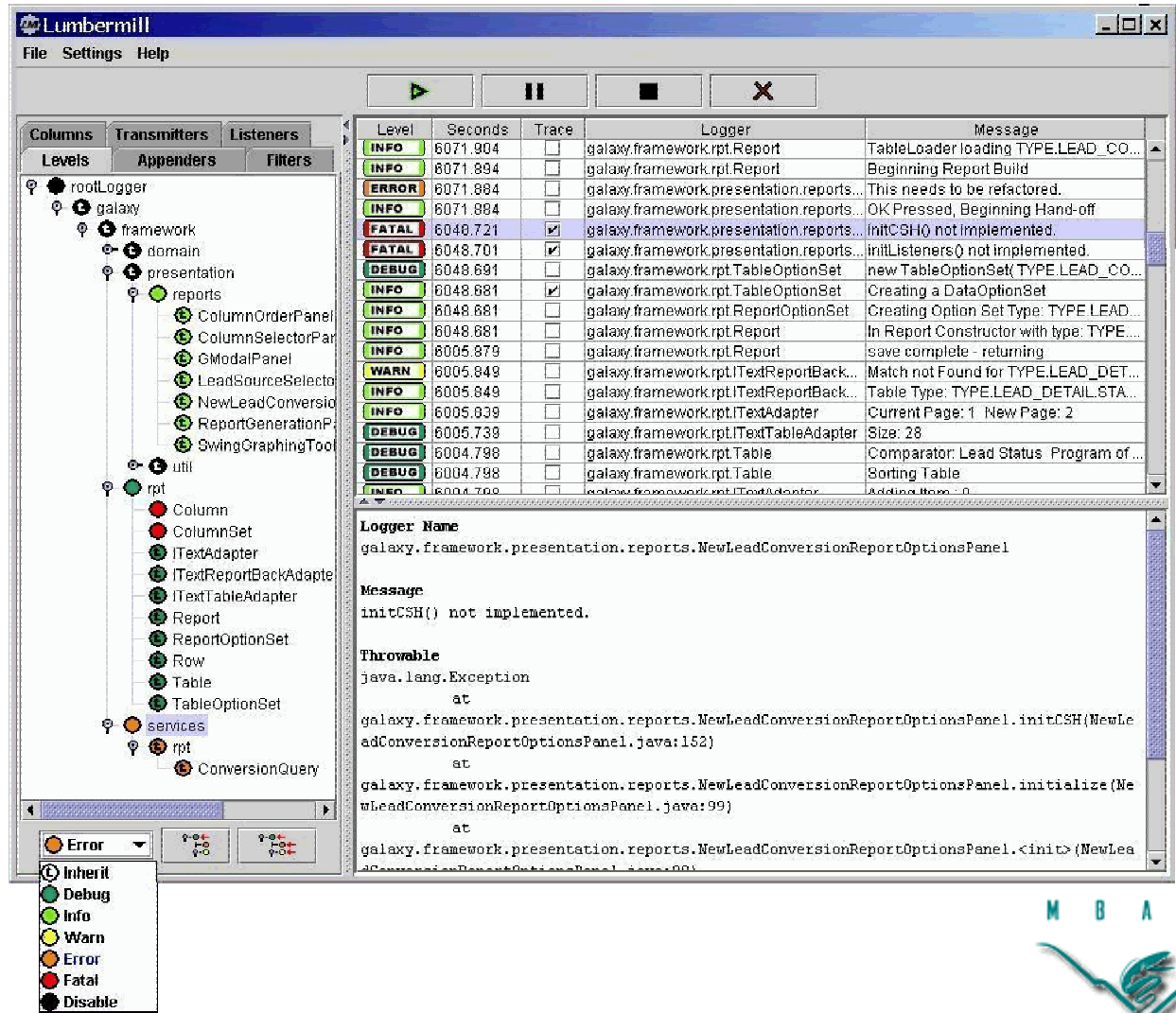
Log4j message logging

- Messages can be logged at different levels and filtered at message producer or consumer
 - ALL
 - WARN
 - OFF
 - DEBUG
 - ERROR
 - INFO
 - FATAL

Log4j message logging

- Socket appender client GUI
 - displays message from socket appender
 - filters messages by package, class, and level
 - free GPL license

<http://traxel.com/lumbermill/>



Discussion

