

MOOS Mooring Engineering Deployment Requirements

REV X.A.2

Purpose
1. Test reliability of data/power cable & mooring mechanical hardware
2. Test reliability/feasibility of ROV operations in connection to mooring
Items to monitor
1. Loads
2. Visual wear
3. Sea keeping ability
4. Riser strain relief
a. length
b. connection position
c. connection wear
d. connection movement
5. Meteorology using M2 or local NOAA

MOOS Electrical/Communications Subsystem Functional Requirements

1. Support the Engineering Deployment requirements by providing telemetry regarding
 - a. Loads
2. Reduce NRE by designing as closely as possible to the future MOOS requirements as stated in the documents at http://mwww.mbari.org/moos/Systems_Engineering/moos_systems_engineering1.htm including
 - a. Geographic deployment locations
 - b. Deployment location water depth
 - c. Deployment duration
 - d. Episodic event response
 - e. Supported instruments
 - i. Bandwidth
 - ii. Power
 - iii. Interface
 - iv. Location (surface/midwater/benthic)
 - f. Local storage consideration
 - g. Cost

Software Functional Requirements:

Introduction

These are the software requirements for the MOOS test mooring.

MOOS test mooring instruments:

1. Compass
Manufacturer: KVH

Part Number: KVH-C100 w/opt SE-10

2. GPS
Manufacturer: Garmin
Part Number: GPS25-HVS
3. Satellite Transceiver
Manufacturer: Qualcomm
Part Number: GSP-1620
4. Serial ADC - Controller Can
Manufacturer: Z-world
Part Number(s):
 - a. SR9050 (101-0487) - Backplane
 - b. SR9160 w/RAM (101-0506 w/130-0092) - CPU
 - c. SR9300 (101-0392) - 0-10V ADC
 - d. SR9320 (101-0444) - 4-20mA ADC
5. Serial ADC - Power Can
Manufacturer: Z-world
Part Number(s):
 - a. SR9010 (101-0512) - Backplane
 - b. SR9160 w/RAM (101-0506 w/130-0092) - CPU
 - c. SR9300 (101-0392) - 0-10V ADC
 - d. SR9310 (101-0423) - -10-+10V ADC
 - e. SR9210 (101-0390) - DIO
6. Heave Sensor
Manufacturer: Triaxys
Part Number(s): HEAVE SENSOR Buoy mounted wave heave sensor with 1 EA RAW
DATA LOGGER Buoy mounted data logger with analysis software

Instrument Requirements

See appendices A, B & C for detailed information regarding each instrument.

For appendix A, these file formats are based on the data currently retrieved from OASIS and presented on the MBARI website. The final format is still **to be determined**.

For appendix C, the interface spreadsheet:

Column	Description
1	The software engineer responsible for writing the software driver
2	The hardware engineer assigned to assist the software engineer as an expert for the hardware item
3	A description of the software channel/signal
4	An unofficial statement of the required voltage/current for the sensor if known
5	A generic classification of the type of signal
6	If a sensor is involved, the full range of the physical phenomenon being measured
7	If known, the hardware engineer's desired precision for the sensor/signal (should be the actual precision)
8	If known, the hardware engineer's desired accuracy for the sensor/signal (should be the actual accuracy)
9	Given the range and precision, this is the desired ADC resolution

10	The required software sample rate as specified by the hardware engineer
11	For logged data, how often the current value should be logged
12	For logged data, how often the minimum value, of the log period, should be logged
13	For logged data, how often the maximum value, of the log period, should be logged
14	For logged data, how often the average value, of the log period, should be logged
15	For the actual ADC, the total number of bits per sample
16	For the actual ADC, the full range of the channel/signal
17	For the actual ADC, the actual precision given the full range and total number of bits
18	If known, the method to convert between the ADC value and the logged value
19	For logged data, the logged value's full range (should be the same as column 6)
20	Whether the data should be logged, sent back to shore, or an event indicated in the log or a combination of the three
21	The method used to access the hardware channel/signal
22	A boolean indicator of whether to send the data back to shore
23	Miscellaneous notes regarding the channel/signal

For example,

for Battery Current 1, item 9: Mike Risi has been assigned to write the software driver and Ed Mellinger has been assigned as the expert to assist Mike if he has any questions. There is no specific supply voltage and current for this item since it is a single channel in a larger subsystem. It is an analog signal. The full range of the sensor is 0 to 10A. Ed would like the sensor to be precise to 7.5mA and accurate to within 0.10% of the full range. Given the full range and precision, Ed would like to use a 12-bit ADC. Ed would like the software to sample the ADC at 1Hz and average the data over 1 hr, storing the minimum, maximum and average to the log file every hour (NOTE: he does not need the current value). The actual hardware provides a 12-bit count over a full range of 0 to +10V, giving each count a precision of 2.441mV. The sensor will put out 192mV/A and has an offset of +5V. The final log file should present the data in a -10.XXXXXA to +10.XXXXXA scale (see the precision for the XXXX). Ideally, the data will be logged and sent back to shore. The signal is accessed via a serial port on a DPA. If necessary, the data is not required to be sent back to shore. You can read the notes.

1. Compass & Turns indicator

By default, the compass' serial port is set up as: **4800baud, 1 start, 8 data, 1 stop, and no parity.**

2. GPS

By default, the GPS unit's serial port is set up as: **4800baud, 8 data, 1 stop, and no parity.**

3. Satellite Transceiver

By default, the satellite transceiver's serial port is set up as: **38400baud, 8 data, 1 stop, and no parity.**

4. Serial ADC - Controller Can

By default, the serial ADC's serial port is set up as: **9600baud, 8 data, 1 stop, and no parity.**

i. Buoy & anchor load cells

- sensor range/units : 0-10,000 lbs. = 4-20mA
- sensor precision: 2.5 lbs.
- sensor accuracy: +/- 0.2% of FS

- desired ADC resolution (based on desired resultant data accuracy): 12 bit
- software conversion algorithm (i.e. lookup table with table size)
Linear conversion of current reading to lbs. tension using the formula:
$$\text{Tension (lbs.)} = \text{input current in } \mu\text{A} / 1.6\mu\text{A}$$
- format you'd like to see the resultant data in: lbs. tension

The following items from the returned data string are required to be time stamped and logged on the NMC at the fastest sample interval we can reasonably sustain given bandwidth and memory limitations:

Upper load cell - maximum, minimum and average (mean) values. Sampled at 4Hz, sample bin size TBD.

Lower load cell - maximum, minimum and average (mean) values. Sampled at 4Hz, sample bin size TBD.

The following items from the returned data string are desired to be returned via comms link to shoreside:

Return interval	Data items
1 hour	Upper load cell - maximum, minimum and average (mean) values for sample bins of previous hour. Lower load cell - maximum, minimum and average (mean) values for sample bins of previous hour.

ii. Fiber optic test

- software conversion algorithm (i.e. lookup table with table size)
Linear conversion of voltage reading to dBm of optical power using the formula:
$$\text{Power dBm} = \text{input voltage in } \mu\text{V} / \text{to be determined conversion factor}$$
- format you'd like to see the resultant data in (i.e. 0.01dB).
dBm (Power)

The following items from the returned data string are required to be time stamped and logged on the NMC at the fastest sample interval we can reasonably sustain given bandwidth and memory limitations:

Reference optical reading - maximum, minimum and average (mean) values. Sampled at 4Hz, sample bin size TBD.

Channel 1 optical reading - maximum, minimum and average (mean) values. Sampled at 4Hz, sample bin size TBD.

Channel 2 optical reading - maximum, minimum and average (mean) values. Sampled at 4Hz, sample bin size TBD.

The following items from the returned data string are desired to be returned via comms link to shoreside:

Return interval	Data items
-----------------	------------

1 hour	Reference optical reading - maximum, minimum and average (mean) values for sample bins of previous hour.
	Channel 1 optical reading - maximum, minimum and average (mean) values. For sample bins of previous hour.
	Channel 2 optical reading - maximum, minimum and average (mean) values. For sample bins of previous hour.

5. Serial ADC - Power Can

By default, the serial ADC's serial port is set up as: **9600baud, 8 data, 1 stop, and no parity.**

6. Heave Sensor

Mode of operation is for the raw data generated to be logged to the internal Flash card using the onboard data logger. A data acquisition run and duration (AC DUR) will be requested at the acquisition interval time (AC INT) and after acquisition is complete the processed data will be queried, time stamped and logged on the NMC/MOOS controller and selectively sent to shore.

Initialization commands:

1. Set Time: At initialization time should be set to match the NMC clock.
2. Set Center of Translation Offsets. At initialization time these values need to be sent to the Wave Sensor. Their value will be determined when the sensor is mounted in September.
3. Set File Enable: At initialization time no files should be enabled.
4. Set Run Mode: The set run mode command is used and the minutes of sampling (AC DUR) set to 25 minutes. The interval of commanding the run should be 30 minutes (see below).

All raw data is always stored at 4Hz on the on-board instrument 1GB disk and available for post processing.

The recommended mode is to set the desired sampling parameters, wait for the end of a sampling run and use the "?MWC<cr>" query to get the wave stats and the house keeping stats.

The following items from the returned data string are required to be time stamped and logged on the NMC at the AC INT:

- ASCII string from the combined "Short Wave Message" and the "Housekeeping message", (WC)

The following items from the returned data string are desired to be returned via comms link to shoreside:

Return interval	Data items
1 hour	Previously unsent ASCII strings from the combined "Short Wave Message" and the "Housekeeping message", (WC)

Appendix A: Data File Formats

```

#
#      MOOS Data Header
#
#      Instrument:      POWER SYSTEM
#      Mooring:         MOOS
#      Deployment Date:  19 August, 2002
#
#      DataFields:
#      Name              Description              Format
#      -----
#      time              GMT time (decimal julian day)  ddd.ffff
#      Battery Voltage 1 - chemistry type A
#      Battery Voltage 2 - chemistry type B
#      Battery Voltage 3 - chemistry type C
#      Battery Voltage 4 - chemistry type D
#      Battery Current 1              ###.###
#      Battery Current 2
#      Battery Current 3
#      Battery Current 4
#      Battery Current 5
#      Battery Current 6
#      Battery Current 7
#      Battery Current 8
#      Battery Voltage
#      Water detection 1
#      Water detection 2
#      Water detection 3
#      Water detection 4
#      Water detection 5
#      Water detection 6
#      Water detection 7
#      Water detection 8
#      Solar Array Current North
#      Solar Array Current East
#      Solar Array Current South
#      Solar Array Current West
#      Solar Array Voltage North
#      Solar Array Voltage East
#      Solar Array Voltage South
#      Solar Array Voltage West
#      Load resistor (lost potential energy)
#      Light sensor (PAR or pyrometer)
#      Wind Generator Load resistor (lost potential energy)
#      Power Feed NMC Current
#      Cable Current
#      Cable Voltage
#      Ground fault
#      Pwr Hsg Temp
#      Pwr Hsg Humidity
#      Dummy Loads
#      - 1 W
#      - 2 W
#      - 2 W
#      - 5 W
#      - 10 W
#      - 20 W
#      Ambient Air Temp

```

2002

```

time
230.70000
231.15833
231.61666
232.07499
232.53332
232.99165
233.44998

```

```

#
#      MOOS Data Header
#
#      Instrument:          CONTROLLER SYSTEM
#      Mooring:             MOOS
#      Deployment Date:     19 August, 2002
#
#      DataFields:
#      Name                 Description                 Format
#      -----
#      time                 GMT time (decimal julian day)   ddd.ffff
#      compass              Buoy magnetic heading          ###.##
#      Turns indicator      Integrated heading              ###
#      Satellite Link strength  Receive Signal Strenght Indicator #
#      Pager (reset)         Has a reset occurred?      Y or -
#      ground fault          Has a ground fault occurred?    Y or -
#      moisture detection     Has moisture been detected    Y or -
#      severed cable detection Has the cable been severed    Y or -
#      Benthic cable voltage   Cable voltage at the benthic node ###.###
#      Benthic ground fault    Has a ground fault occurred?  Y or -
#      Benthic moisture detection Has moisture been detected    Y or -

```

2002

230.70000

```

#
#           MOOS Data Header
#
# Instrument:      Garmin 12 Channel GPS
# Mooring:         M1
# Deployment Date: 5 October, 2001
#
# Data Fields:
# Name            Description            Format
# -----
# time            GMT time (decimal julian day)  ddd.ffffff
# latitude        Latitude (deg north)          floating point
# longitude       Longitude (deg west)          floating point
# std_dev        Position Standard Deviation (m) floating point
# samples        Number of samples taken        integer
# time_on        Power-On duration (s)          integer
# diffSamples    Number Differential GPS Samples integer
# hdop           Horizontal Dilution of Precision
# temp           GPS Receiver Temp (deg C)      floating point
# status         Garmin Status Byte            hex (see note)
#
# Note: Status Byte Format
# Bit  Description            Values
# 0    ROM checksum test      1 = Pass      0 = Fail
# 1    Receiver failure discrete 1 = Pass      0 = Fail
# 2    Stored data lost        1 = Retained 0 = Lost
# 3    Real time clock lost    1 = Retained 0 = Lost
# 4    Oscillator drift discrete 1 = Pass      0 = Excessive Drift
# 5    Board configuration data 1 = Retained 0 = Lost
# 6,7 Unused
#

```

```

DATE          : 27-10-1999
TIME          : 00:00:00
WAVAN4  2.0
MTN_F1       : 0.030
MAGNETIC_VAR : 0.000
FREQ_SPACING : 0.005
LOW_FREQ_CUT : 0.030
HI_FREQ_CUT  : 0.640
WVN_STR      : 0.010
N1           : 7761
T1           : 59.978
DT1          : 0.139
M33_STATUS   : 0
N_ZERO_CROSS : 281
AVE_HEIGHT   : 0.136
AVE_PERIOD   : 3.828
MAX_HEIGHT   : 0.346
SIG_HEIGHT   : 0.209
SIG_PERIOD   : 6.235
F1           : 0.030
F2           : 0.640
PEAK_PERIOD  : 28.571
TP5          : 28.854
4*(M0^0.5))  : 0.265
N_FRQ_NONDIR : 123
INIT_FREQ    : 0.030
FREQ_SPACING : 0.005
              1 0.030 1.34452641010284E-0001
              2 0.035 2.21106648445129E-0001
              3 0.040 8.43078494071960E-0002
              4 0.045 3.14780473709106E-0002
            119 0.620 1.69821281451732E-0003
            120 0.625 2.26324098184705E-0003
            121 0.630 2.32355110347271E-0003
            122 0.635 2.30335025116801E-0003
            123 0.640 1.72895647119731E-0003
MEAN_DIR      : 222.353
MEAN_SPREAD   : 63.297
N_FOURIER     : 118
INIT_FOURIER  : 0.030
FREQ_SPACING  : 0.005
              1 0.030 -7.83297792077064514E-0002 -7.21813365817070007E-
0002 -5.53748726844787598E-0001 1.23462758958339691E-0001
              2 0.035 -6.40451833605766296E-0002 -8.91567021608352661E-
0002 -5.42389452457427978E-0001 1.05476781725883484E-0001
              3 0.040 -3.87482307851314545E-0002 -1.40509992837905884E-
0001 -5.27283012866973877E-0001 7.43258669972419739E-0002
              4 0.045 1.09544638544321060E-0002 -1.96370631456375122E-
0001 -5.74521005153656006E-0001 -1.04809254407882690E-
0002
              .
              .
              .
            117 0.610 -2.52318441867828369E-0001 -5.43326199054718018E-
0001 -4.98808830976486206E-0001 2.25346058607101440E-0001
            118 0.615 -2.55536735057830811E-0001 -5.32469749450683594E-
0001 -4.92384165525436401E-0001 2.60102629661560059E-0001

```

STATUS

:9910270000, OWNERID, +022.9, 3022.614N08638.913W, 13.18, 4.0, 4800, 30, 30, 3, TAS
00080, 2.07, 1.05, 6, 0, 0.005, +00.0

```

#
#      MOOS Data Header
#
#      Instrument:          LOAD CELLS
#      Mooring:            MOOS
#      Deployment Date:     19 August, 2002
#
#      DataFields:
#      Name                Description                Format
#      -----
#      time                GMT time (decimal julian day)  ddd.ffff
#      buoy tension load cell (strain guage)
#      anchor tension load cell (strain gauge)

```

2002

230.70000

Appendix B: Channel Assignments

Controller Channel Assignment

Controller Backplane	<i>connects to</i>	
Slot 0 (J4)	Cerfboard	<i>connects to</i>
	Ethernet	SideKick
	Serial 1	Globalstar Modem
	Serial 2	
	Serial 3	Wireless Console
	USB	
	GPIO 0	
	GPIO 1	
	GPIO 2	
	GPIO 3	
	GPIO 4	
	GPIO 5	RF GGI Warning Interrupt
	GPIO 6	RF GFI Error Interrupt
	GPIO 7	RF GFI Test
	GPIO 8	
	GPIO 9	RF DSR
	GPIO 10	RF RI
	GPIO 11	RF POWER ON
	GPIO 12	RF RTS
	GPIO 13	RF DTR
	GPIO 14	RF CD
	GPIO 15	RF CTS
Slot 1 (J7)	SideKick	
	Ethernet	SideARM/Cerfboard
	Local Serial "8"	
	Local Serial "9"	
	Local Serial "10"	
	Uplink Serial "11"	
Slot 2 (J21)	DPA	
	Channel 6 Serial	Heave Sensor
	Channel 6 Power	Heave Sensor
	Channel 7 Serial	Power Controller (Smart Star)
	Channel 7 Power	Power Controller (Smart Star)
Slot 3 (J19)	DPA	
	Channel 4 Serial	Garmin GPS
	Channel 4 Power	Garmin GPS
	Channel 5 Serial	Controller Serial ADC
	Channel 5 Power	Controller Serial ADC
Slot 4 (J13)	DPA	
	Channel 2 Serial	KVH Compass
	Channel 2 Power	KVH Compass
	Channel 3 Serial	
	Channel 3 Power	
Slot 5 (J8)		

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Controller SmartStar Channel Assignment/System Analysis

CPU Slot		Sample
Slot 0	4Hz	
ADC 0-10V Ch 0	Fiber Optic Cable Tester ch. 1	4Hz
ADC 0-10V Ch 1	Fiber Optic Cable Tester ch. 2	4Hz
ADC 0-10V Ch 2	Fiber Optic Cable Tester ch. 3	4Hz
ADC 0-10V Ch 3	Fiber Optic Cable Tester ch. 4	4Hz
ADC 0-10V Ch 4		
ADC 0-10V Ch 5		
ADC 0-10V Ch 6		
ADC 0-10V Ch 7		
ADC 0-10V Ch 8		
ADC 0-10V Ch 9		
ADC 0-10V Ch 10		
Slot 1	4Hz	
ADC 4-20mA Ch 0	buoy tension load cell (strain guage)	4Hz
ADC 4-20mA Ch 1	anchor tension load cell (strain gauge)	4Hz
ADC 4-20mA Ch 2		
ADC 4-20mA Ch 3		
ADC 4-20mA Ch 4		
ADC 4-20mA Ch 5		
ADC 4-20mA Ch 6		
ADC 4-20mA Ch 7		
ADC 4-20mA Ch 8		
ADC 4-20mA Ch 9		
ADC 4-20mA Ch 10		
Slot 2		

Rev X.A

Appendix C: Detailed Channel Specifications

