

Sub-System Interfaces

	Surface Buoy	Controller	Battery	Power Take-Off	Instrumentation	Communication	Tether	Submerged Plate
Surface Buoy		M	M	M	M	M		
Controller	M		E,S	E	E,S	E,S		
Battery	M	E,S		E				
Power Take-Off	M	E	E				M	
Instrumentation	M	E,S						
Communication	M	E,S						
Tether				M				M
Submerged Plate							M	

M = Mechanical Interface
E = Electrical Interface
S = Software Interface