

A Modular Approach for Sensor Integration on the REMUS Vehicle

Mr. Andrew Dreiling

Engineer, Space and Naval Warfare Systems Center
San Diego
dreiling@spawar.navy.mil (619) 553-4033

Mr. G. Hong

Engineer, Space and Naval Warfare Systems Center
San Diego
ghong@spawar.navy.mil (619) 553-4033

Mr. Brian Granger

Engineer, Space and Naval Warfare Systems Center
San Diego
bgranger@spawar.navy.mil

Mr. V. Djapic

Space and Naval Warfare Systems Center
San Diego djapic@spawar.navy.mil

Mr. R. Arrieta

Project Manager
Space and Naval Warfare Systems Center
San Diego arrieta@spawarnavy.mil

Mr. M. Dock

Nomadics, Inc.

Mr. R. Stokey

Woods Hole Oceanographic Institution

Abstract: This paper describes the development of a standard for integrating environmental sensors onto the Remote Environmental Monitoring UnitS (REMUS) unmanned underwater vehicle (UUV). The integration will follow a modular approach by placing additional body sections between the Acoustic Doppler Current Profiler (ADCP) module and nosecone. New sensors can use the input interface provided on the REMUS for the Optical Backscatter. Most sensors can be mated with the vehicle via an intermediary collar device designed by SSC-SD along with a pressure vessel module or custom mounted on into a "dummy" nosecone. In addition to the physical integration, a generic NMEA 183 software interface has been developed in cooperation with Woods Hole Oceanographic Institution.