

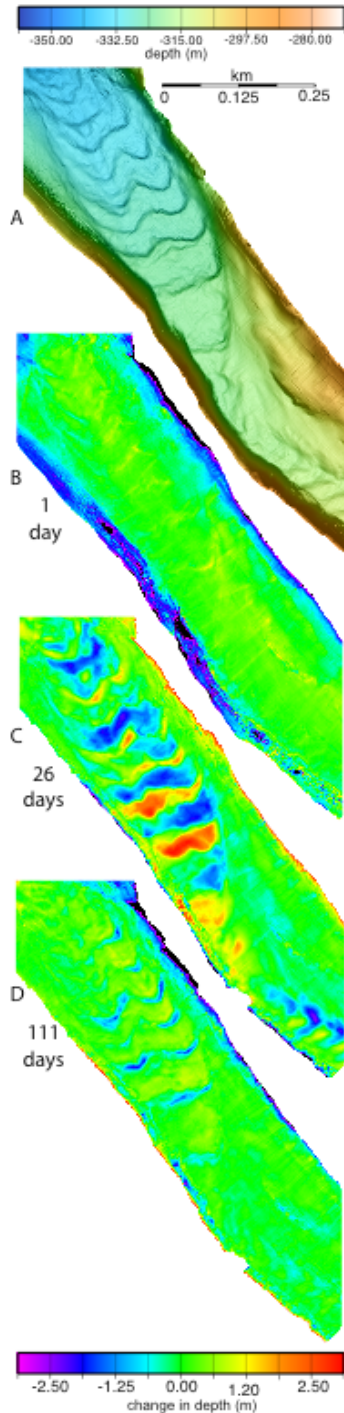
# BEDS Concept Design Review

December 16, 2010

# Agenda

- Statement of Science Problem and Goals
- Draft Functional Requirements
- Previous and relevant work
- Description of design concept being considered
- System block diagram
- High risk elements
- Power/Data budgets
- Future test and design plans
- Required resources

[https://mwww.mbari.org/pco/Project\\_Management/project\\_design\\_review\\_guidelines.pdf](https://mwww.mbari.org/pco/Project_Management/project_design_review_guidelines.pdf)



# Science Motivation

Monument experiments and Multi-beam data have shown that the Monterey Bay Canyon is very active.

The timing and mechanism of these sediment transport events is not well understood.

The ability to capture data during a sediment transport event would aid in understanding the nature of these events, and to test current models of sediment movement.

# Debris Field Motion



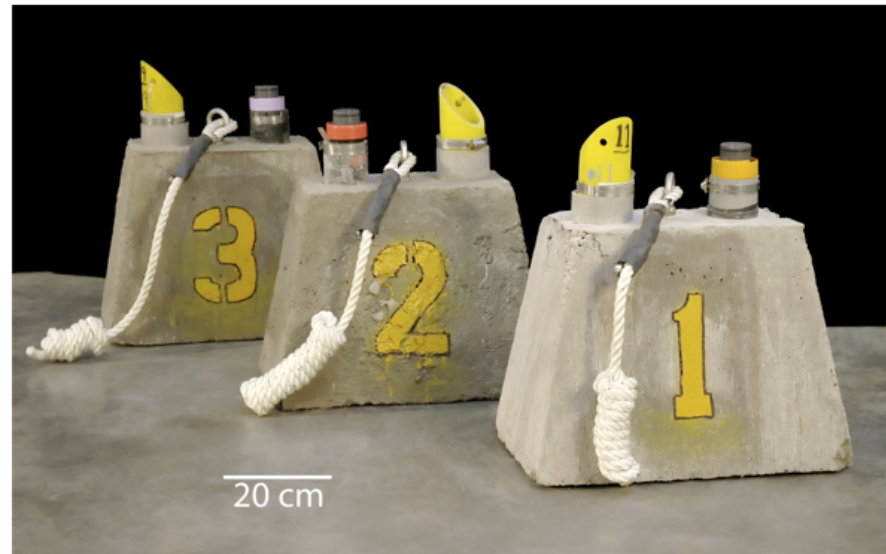
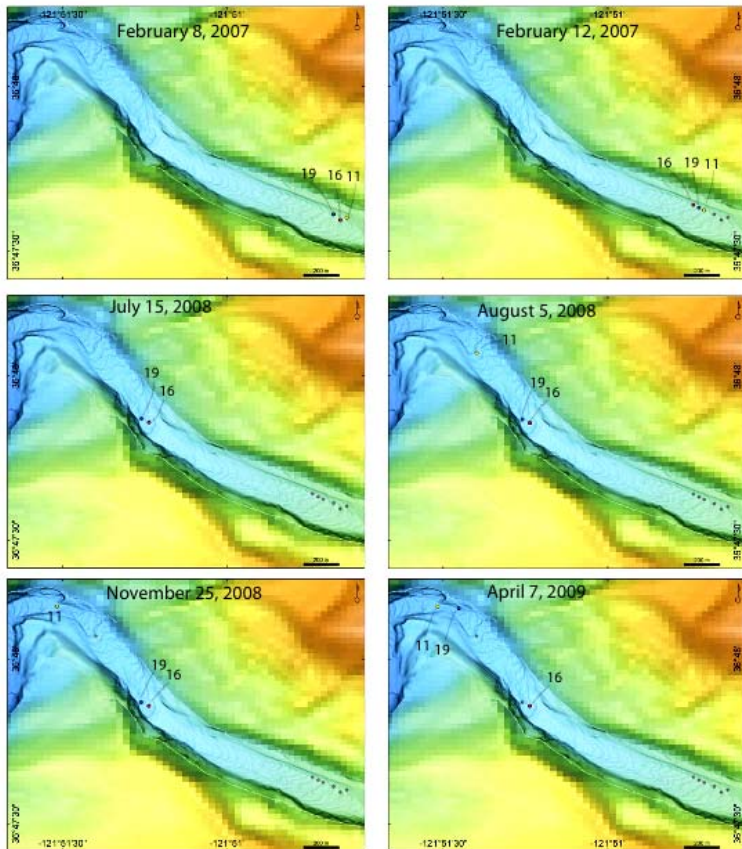
Debris Field

# Science Questions

- 1. Can we determine duration and frequency of these events?**
- 2. Can we characterize the type of sediment motion (a slab flow or erosive/turbulent or composite flow)?**
3. Can we determine the physical scale of the event?
4. Can we determine the depth of no motion?

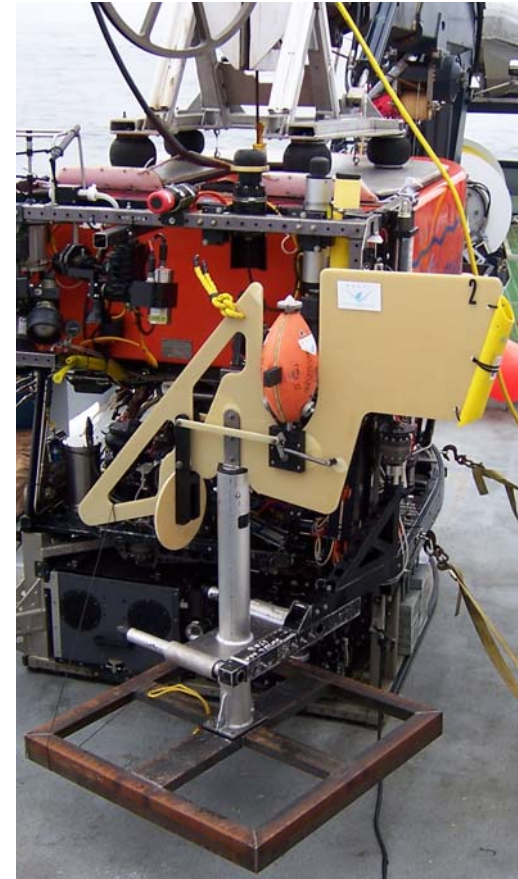
# Previous and Concurrent Work

- Monuments
  - Concrete blocks carried hundreds of meters over a year
  - Provide evidence that events did occur but not motion or timing data



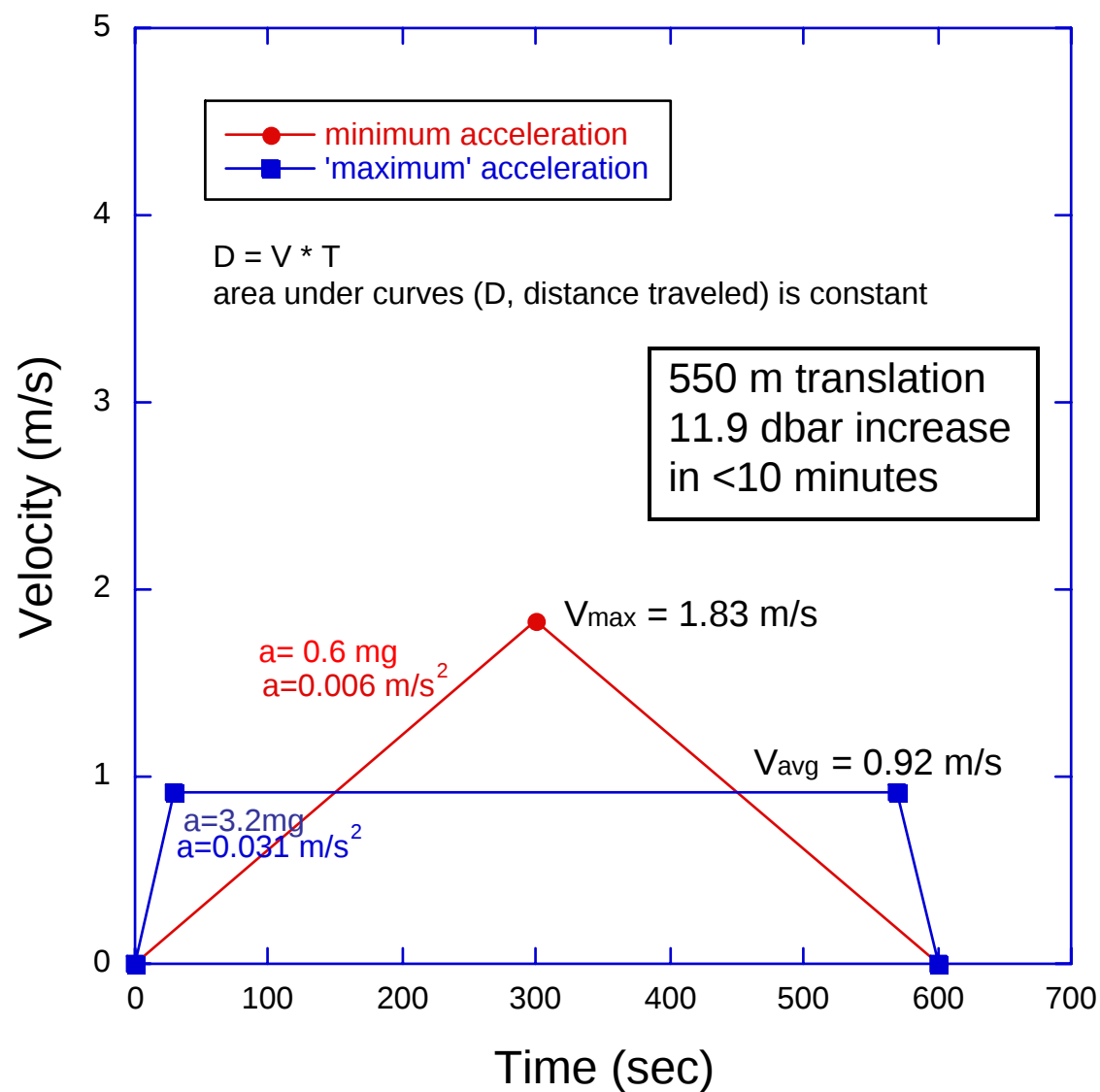
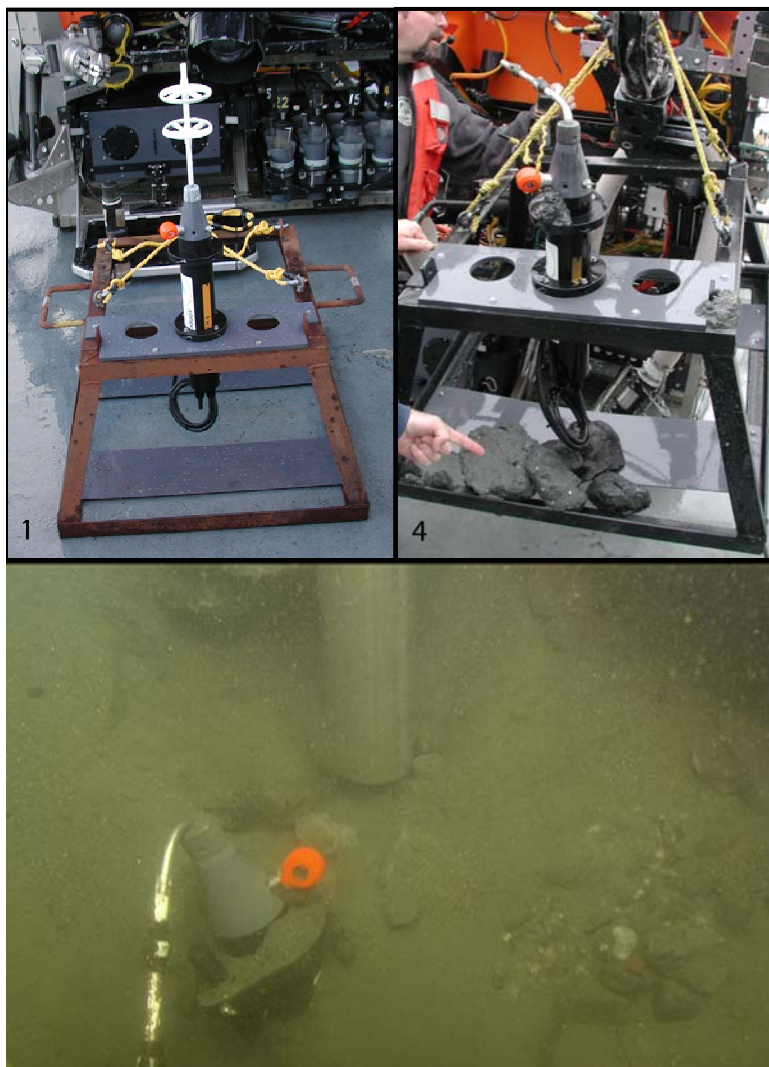
# Previous and Concurrent Work

- STEDs
  - Measures water column events
- McStar
  - Records sounds associated with sediment transport events, may provide timing but no motion or scope data
- Multi-Beam
  - Repeat mapping documents change in seafloor texture



# Only Transport Event Data

December 21, 2001 Event



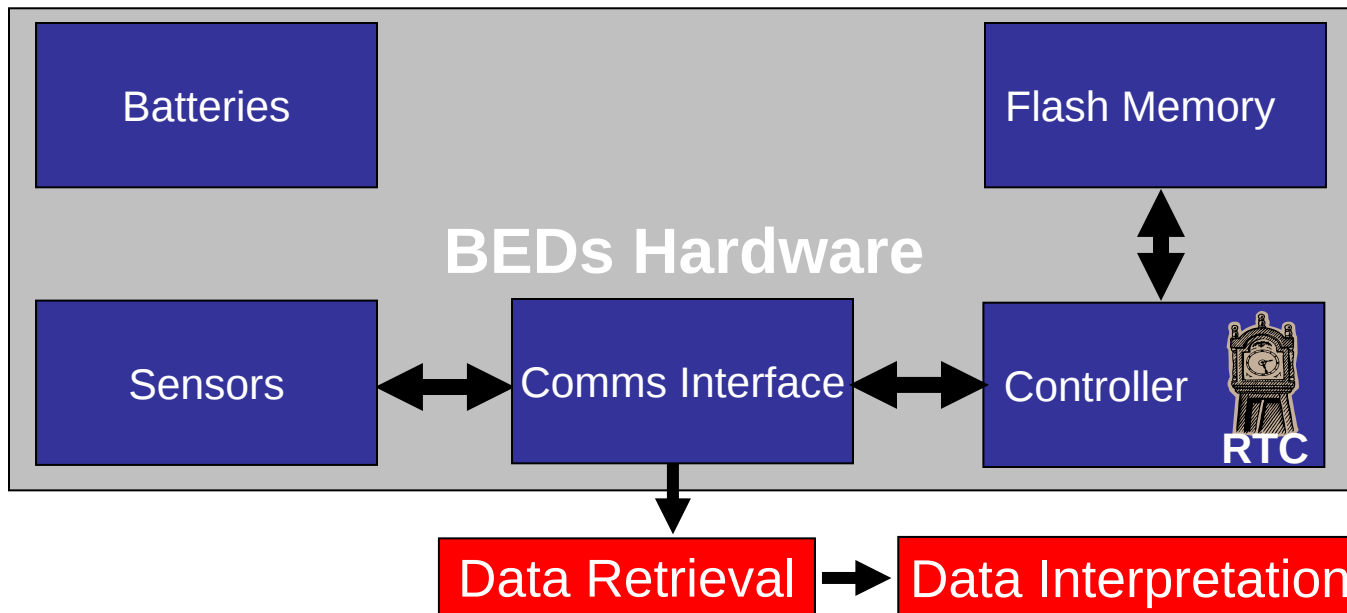
# Draft Functional Requirements



BEDs FRS rev 0.2

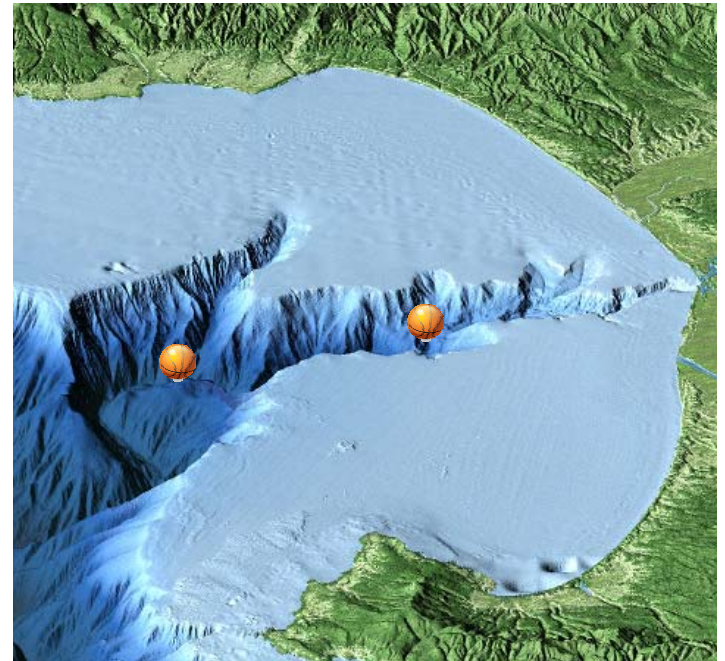
# BEDs Concept

- The BED will be a stand-alone instrument package with a computer, sensors capable of resolving motion, and adequate memory to store data



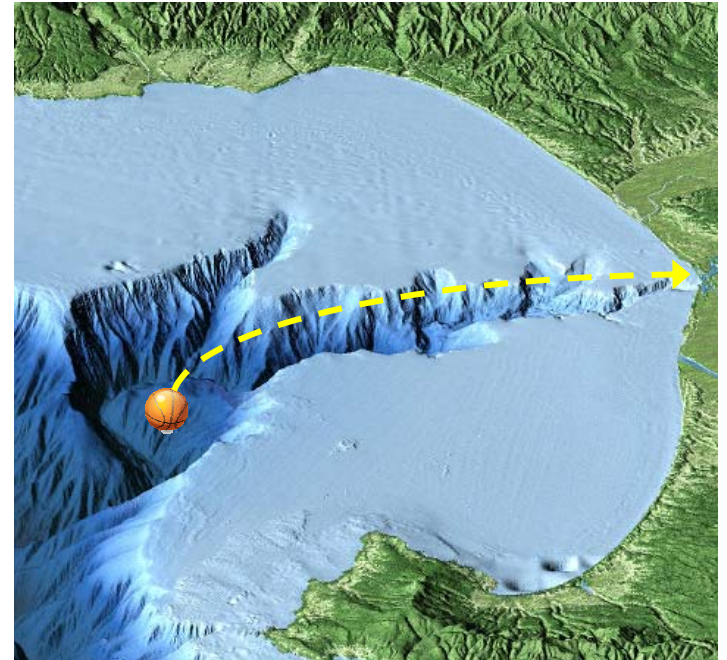
# BEDs Concept

- The instrument shall be deployed in canyon, free to be carried down canyon by events



# BEDs Concept

- Data stored on the instrument will be retrieved...somehow
- Analyze data and understand more about canyon events



# BEDs Concept: High-risk Elements

- Can we retrieve data, possibly from buried instrument

↓ Yes → No, start over-new concept

- Can we find sensors to resolve the motion we are trying to detect?

↓ Yes → No, back to drawing board

- Can we detect an event?

↓ Yes → No, hmmm...

- Can we interpret the data?

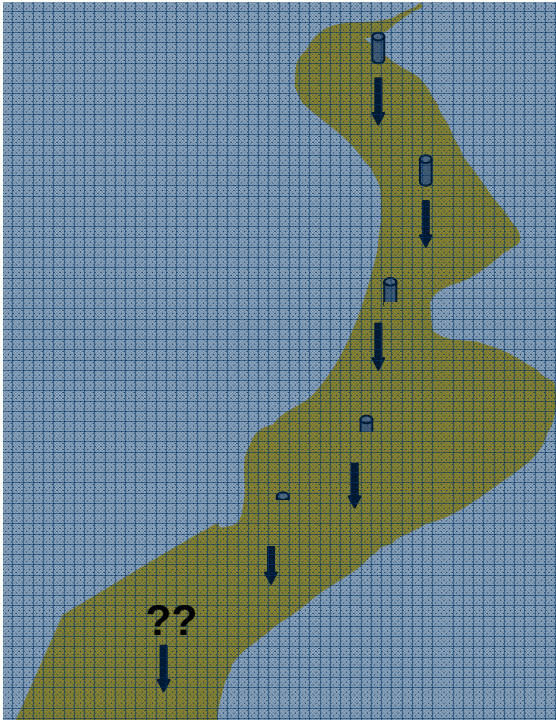
→ No, @%@# \$!%#

# BEDs Concept: High-risk Elements

- Can we retrieve data, possibly from buried instrument
- Can we find sensors to resolve the motion we are trying to detect?
- Can we detect an event?
- Can we interpret the data?

# High Risk: Data Recovery

How could we recover the data?



Pop-up buoy



Avalanche cord



Electro-magnetic  
comms

Acoustic

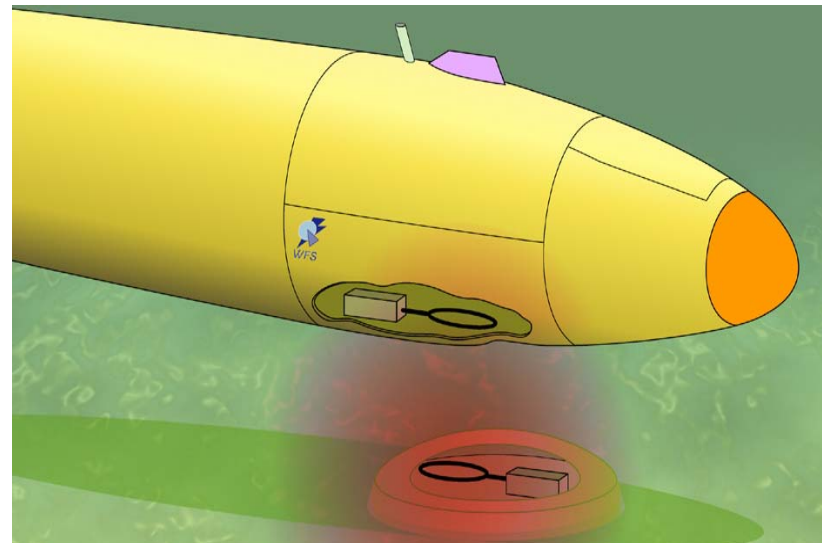


# Data Recovery

Technical and Operational Challenges of each:

EM modem pair from WFS Defense tank tested –

- does work through concrete wall and seawater
- packaging issues
- Antennae are directional: would need two orthogonal hoops to be omnidirectional
- Modems must be within 10 m for fast bandwidth
- cost? (standard \$25k)
- *Not ruled out as solution*



# Data Recovery

Technical and Operational Challenges of each:

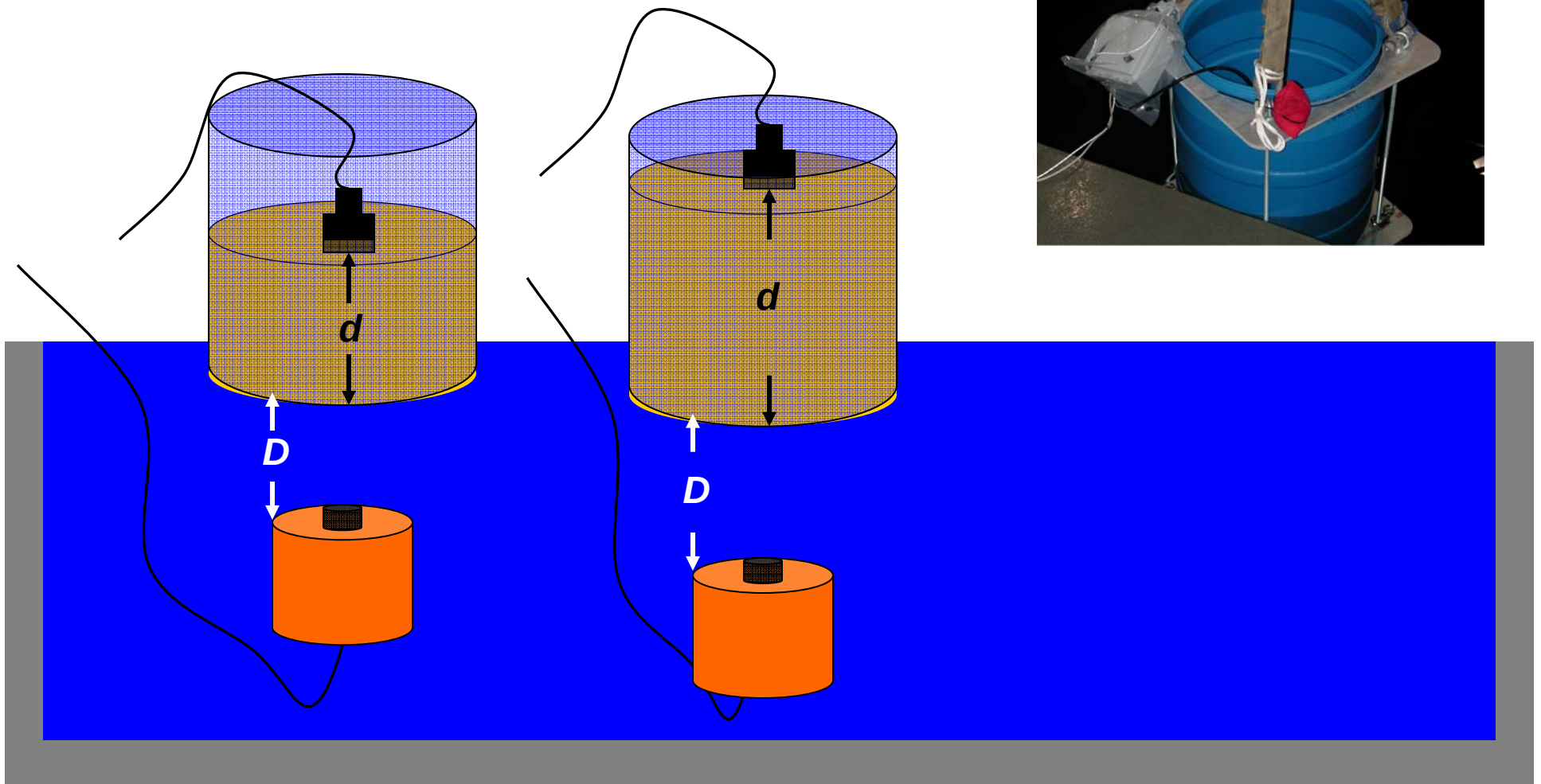
Acoustic

Will we be able to transmit through sediment?

Benthos says, “It should work...let us know.”

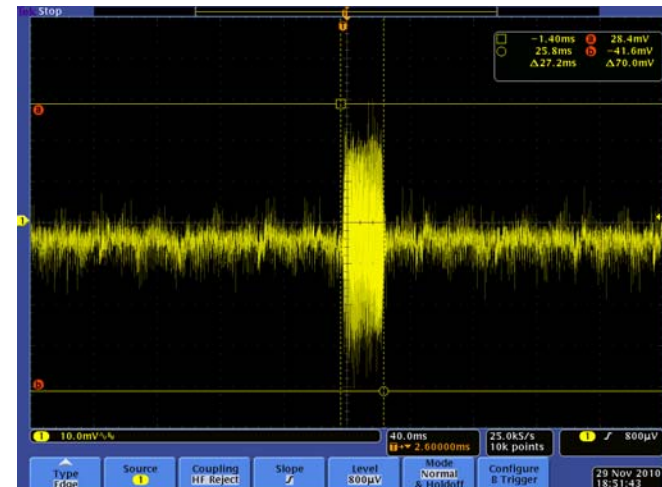
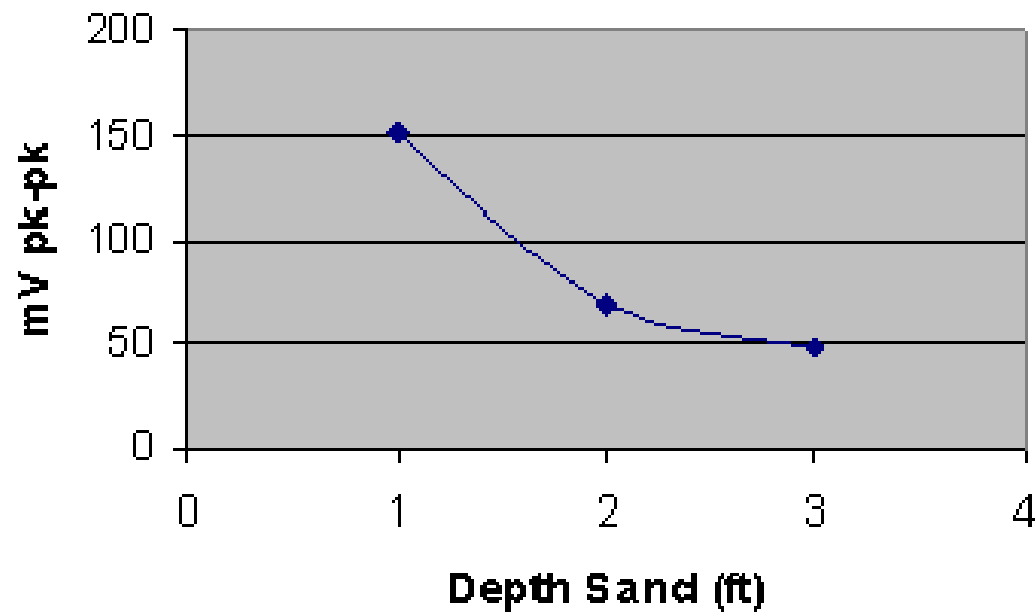
Developed tests for Benthos acoustic modem system

# Tank Test Set Up



# Tank Ping Test

Ping Amplitude

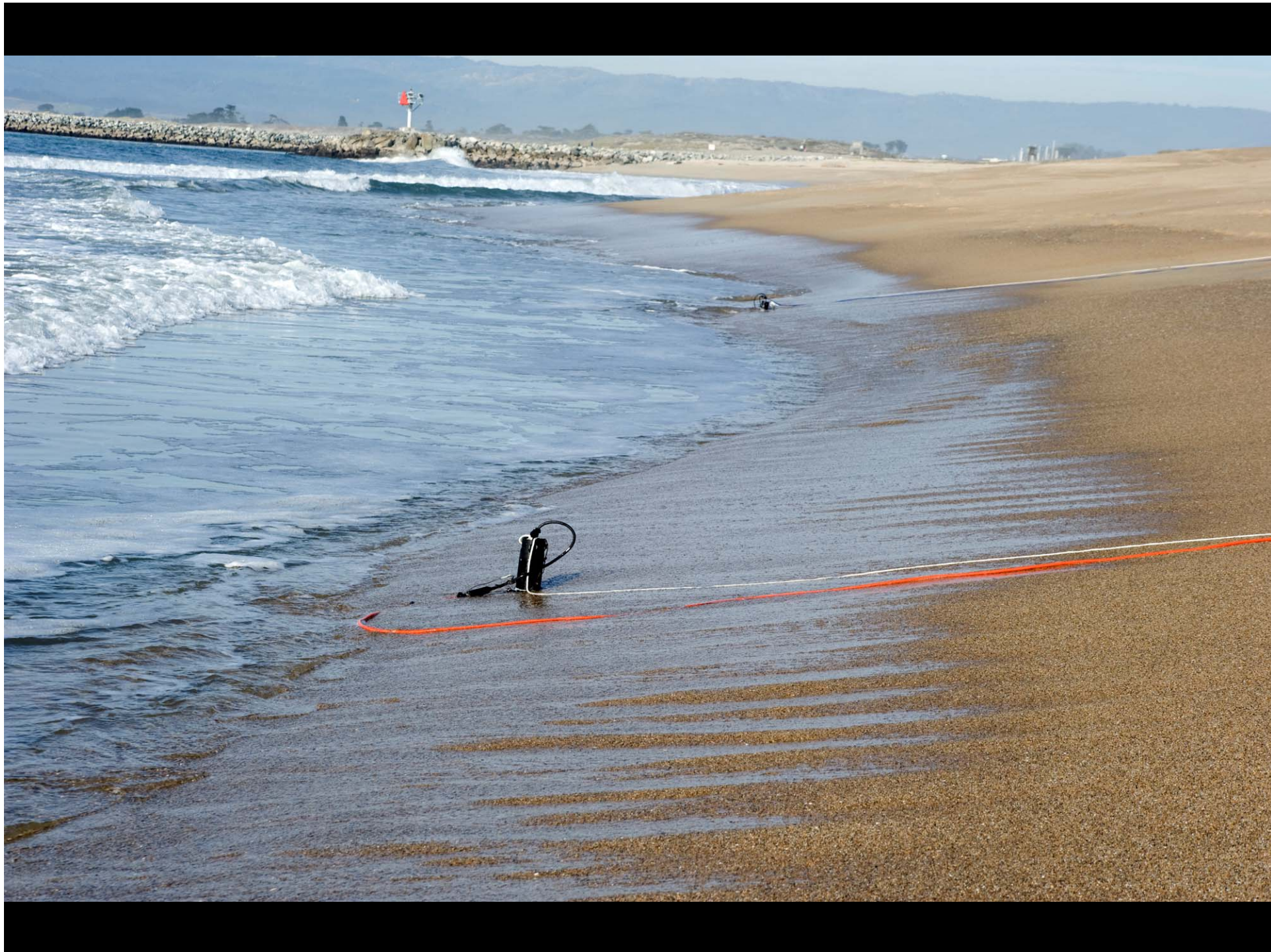


# Tank File Transfer Test

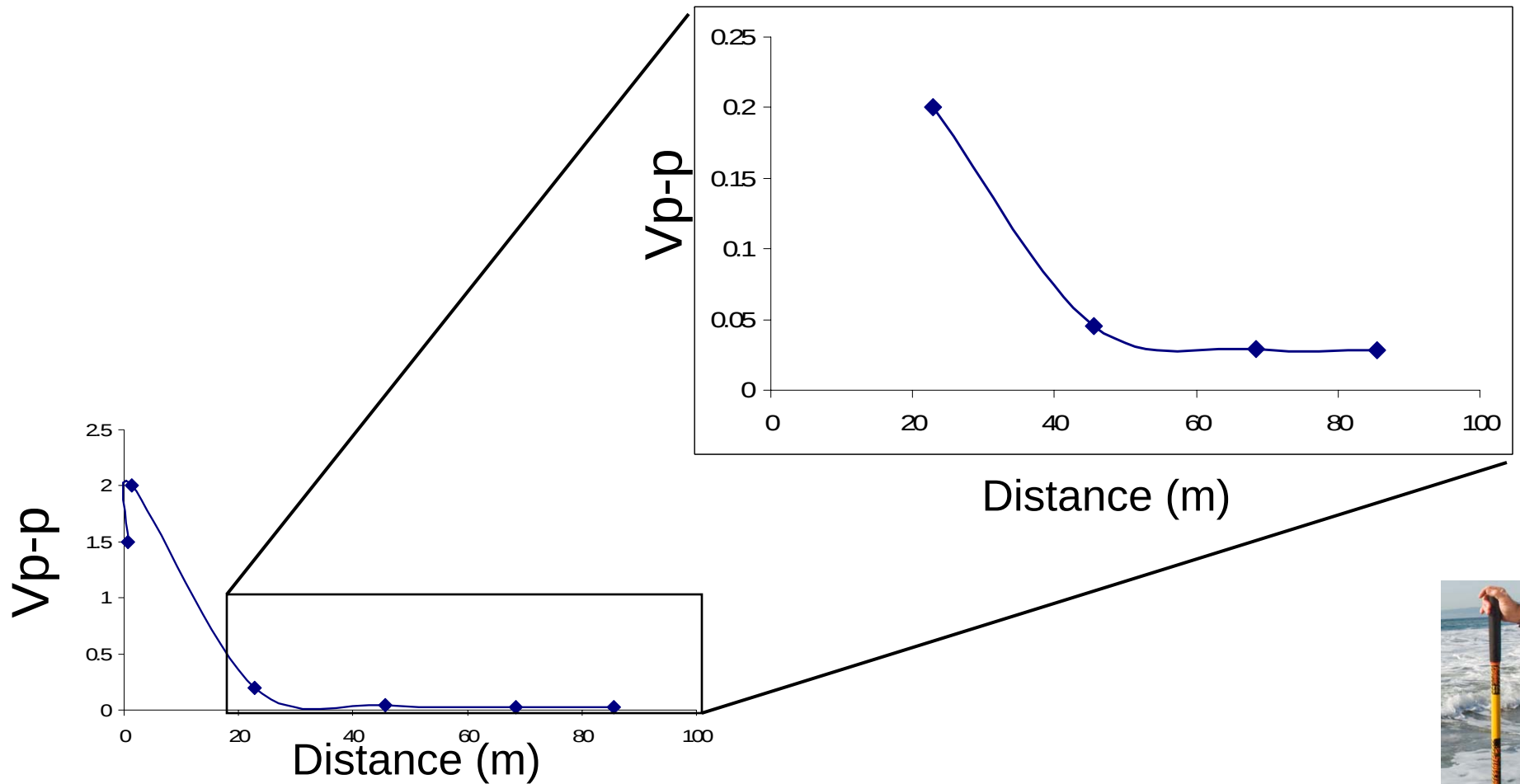
| <b>Sand thickness</b> | <b>Maximum rate</b> | <b>File size</b> |
|-----------------------|---------------------|------------------|
| 3 ft.                 | 1200 bits/sec       | 642 bytes        |



How far does sound travel when both modems are buried??



# Beach Ping Test



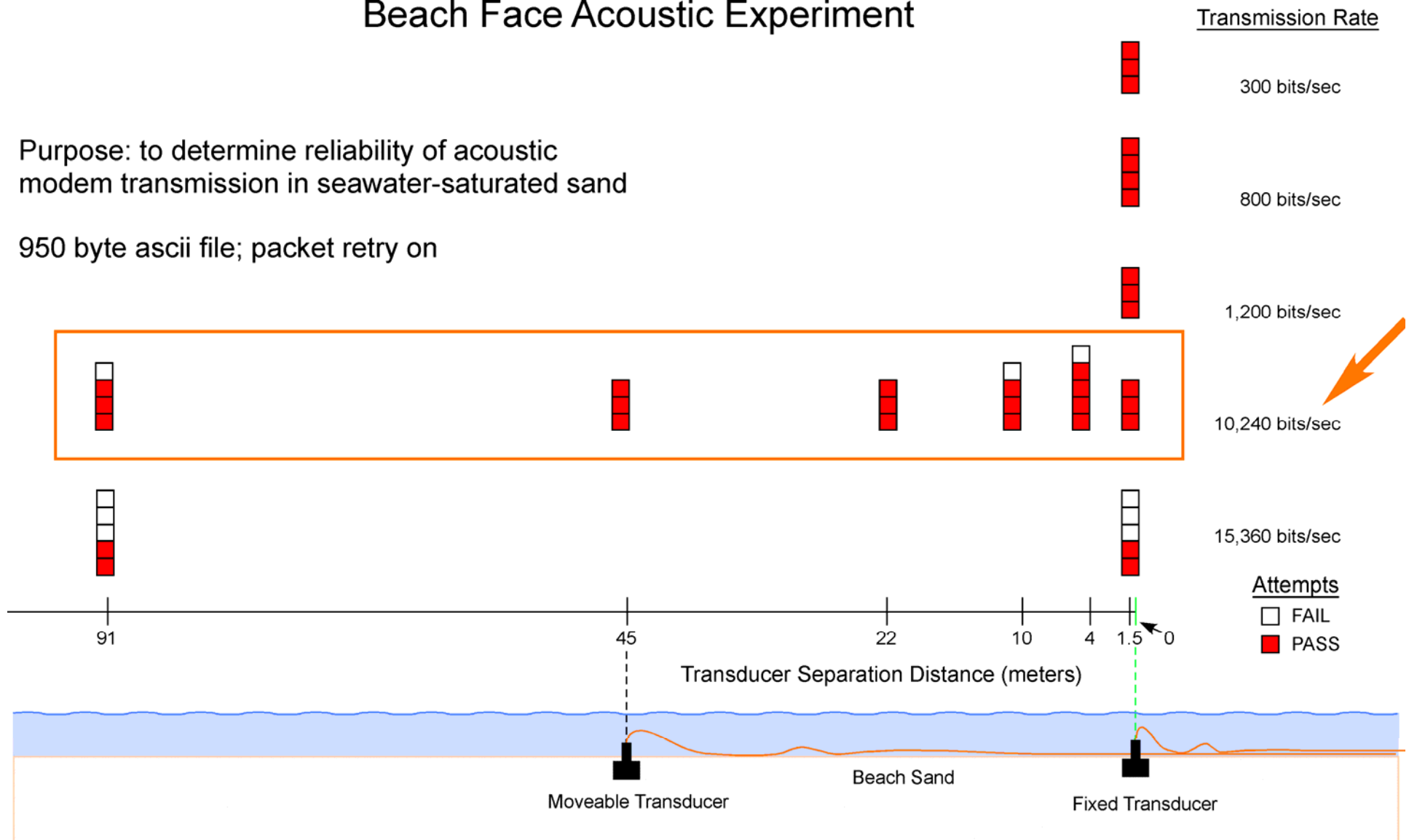
1 uS (Ussler) = 1.425m = 1 shovel length



# Beach Face Acoustic Experiment

Purpose: to determine reliability of acoustic modem transmission in seawater-saturated sand

950 byte ascii file; packet retry on





# Data Recovery Summary:

## Acoustics

- Bright colored shorts do not affect transmission quality
- Sand-sand transmission seemed promising (10kbits/sec at 91m apart)
- Water-sand interface further attenuates signal
  - possibly due to test tank set up (ping tests)
- Test results are encouraging further development

# Data Recovery Summary

|                      | Max baud | Range                          |
|----------------------|----------|--------------------------------|
| Benthos<br>Modem     | 10 kbps  | sed-sed $\geq$ 90 m            |
|                      | 1200 bps | H <sub>2</sub> O-sed: 3 ft - ? |
| Seatooth<br>EM modem | 100 kbs  | 10 m                           |
| Seatext<br>EM Modem  | 100 bps  | 350m                           |

Will pursue acoustic solution first because of the range/throughput issues

# BEDs Concept: High-risk Elements

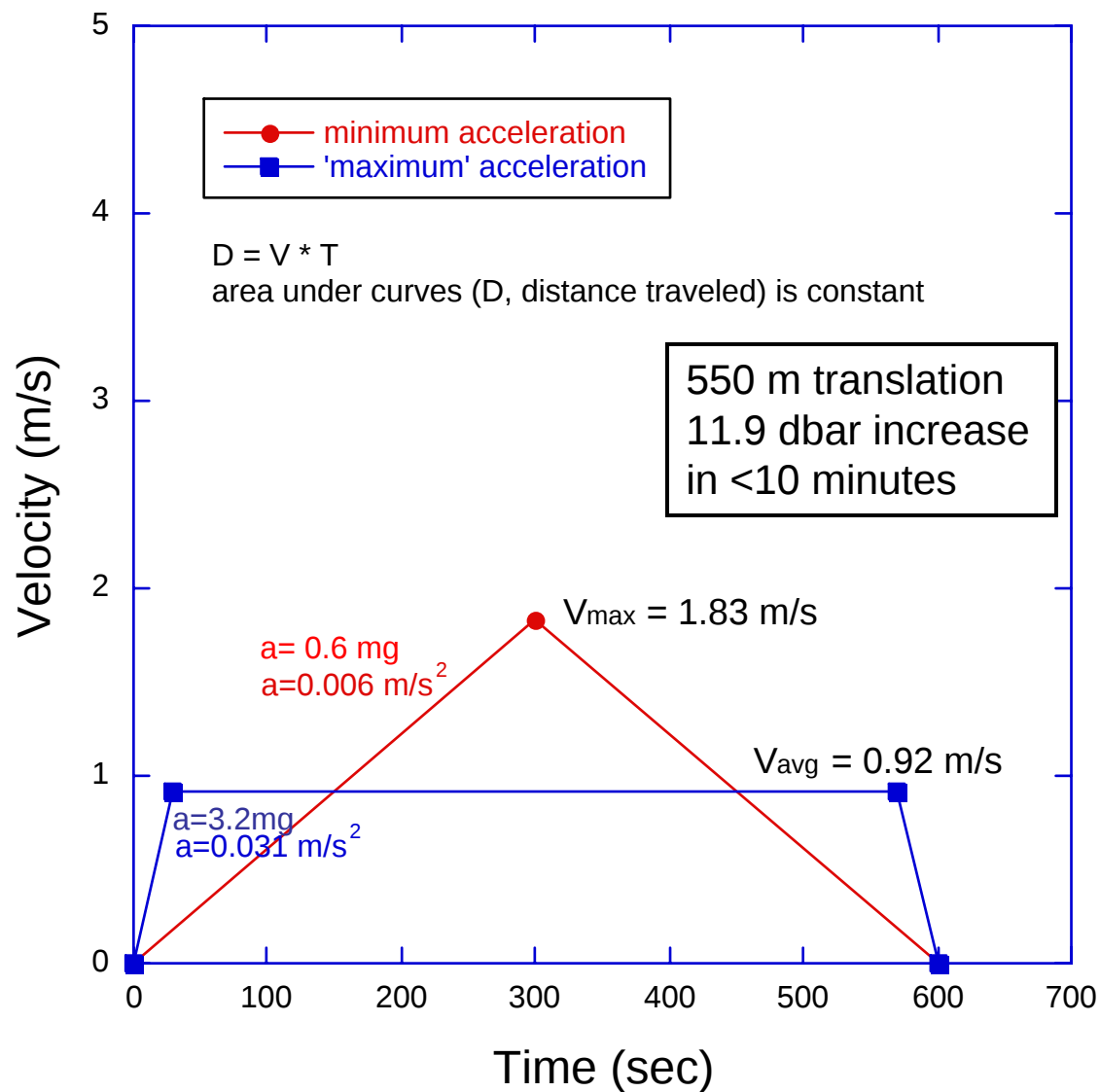
- Can we retrieve data, possibly from buried instrument
- Can we find sensors to resolve the motion we are trying to detect?
- Can we detect an event?
- Can we interpret the data?

# What measurements could be used to resolve the motion of the bed?

- Acceleration
- Inclination
- Pressure
- Magnetic compass
- A combination of the above
- Sensor selection is part of test plan coming in a few slides

# Only Transport Event Data

December 21, 2001 Event



# A Suite of Possible Sensors

| Manufacturer   | Type                                            | Specs                                                                                                      |
|----------------|-------------------------------------------------|------------------------------------------------------------------------------------------------------------|
| Analog Devices | Accelerometer<br>Inclinometer<br>6 DoF inertial | <1.25 mg accel sensitivity<br><.1° tilt sensitivity                                                        |
| Freescale      | Accelerometer                                   | 3 axis $\pm 2g/8g$<br>0.9 mg/bit sensitivity                                                               |
| Microstrain    | AHRS                                            | 360° about 3 axis<br>.1° orientation resolution<br>$\pm 5g$ acceleration range<br>1Hz – 1kHz sampling freq |
| Various        | Pressure                                        | Resolution to <1cm                                                                                         |

# BEDs Concept: High-risk Elements

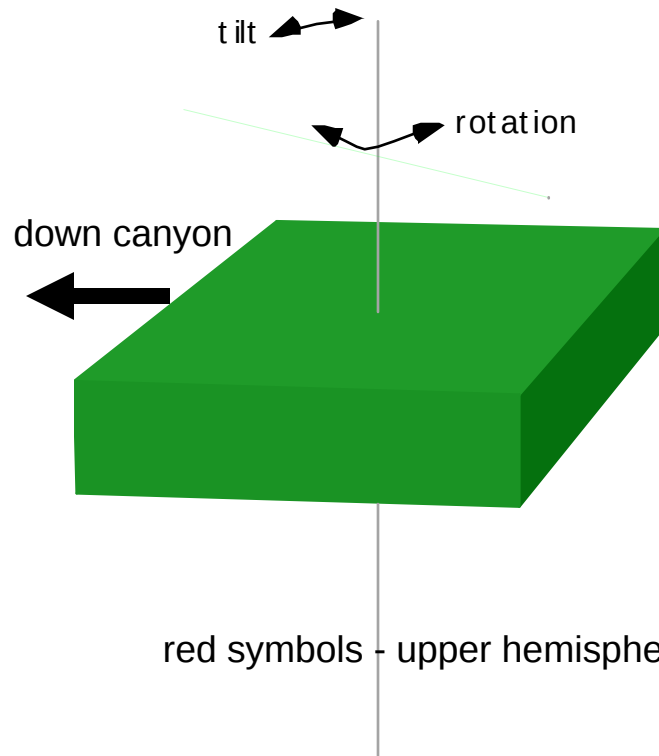
- Can we retrieve data, possibly from buried instrument
- Can we find sensors to resolve the motion we are trying to detect?
- Can we detect an event?
- Can we interpret the data?

# Simulation of rotation and tilt around a vertical axis

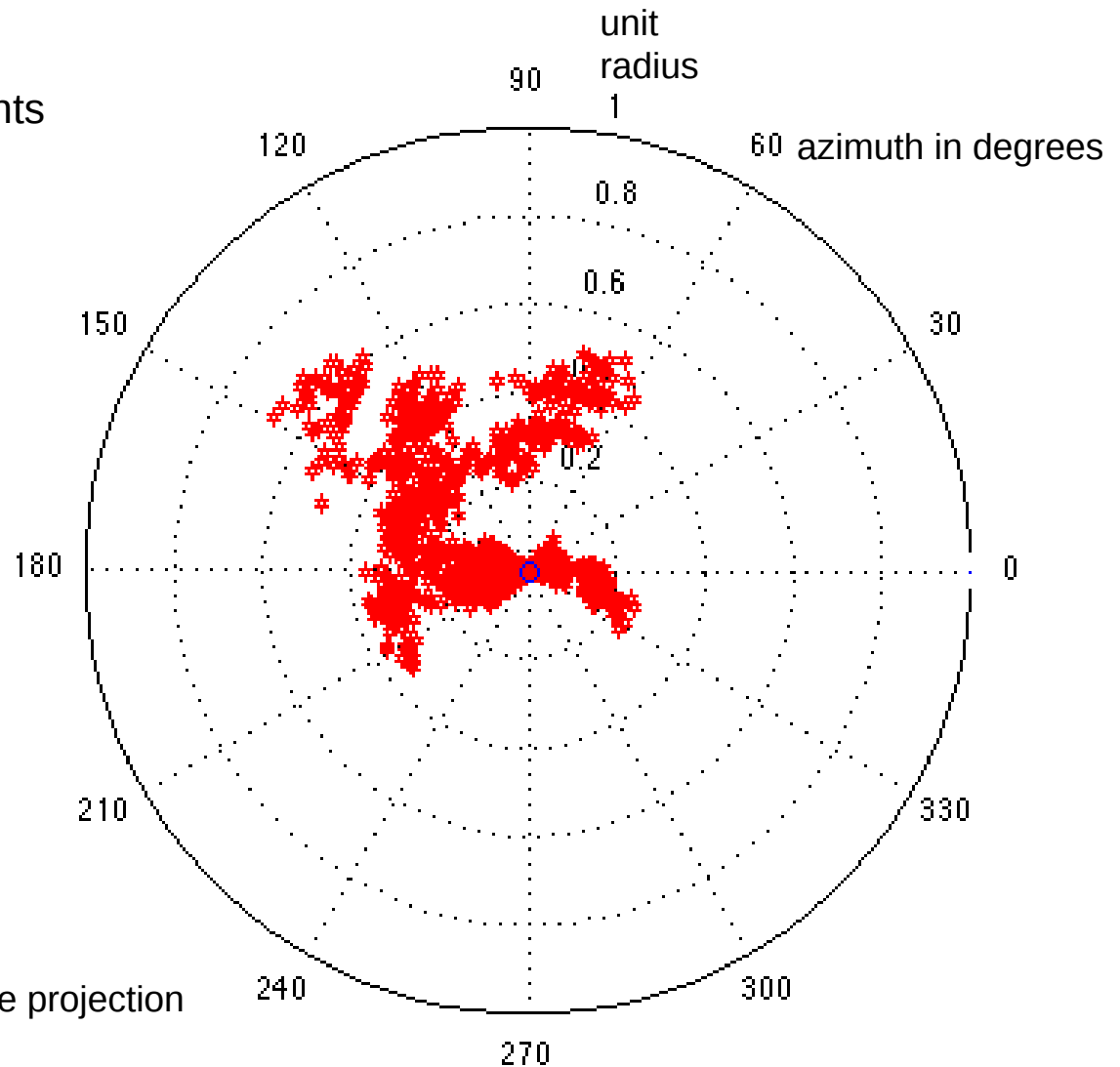
1000 samples

normally distributed random events  
mean=0; sd = 1

tilt and rotation independent



red symbols - upper hemisphere projection



# Simulation of rolling object

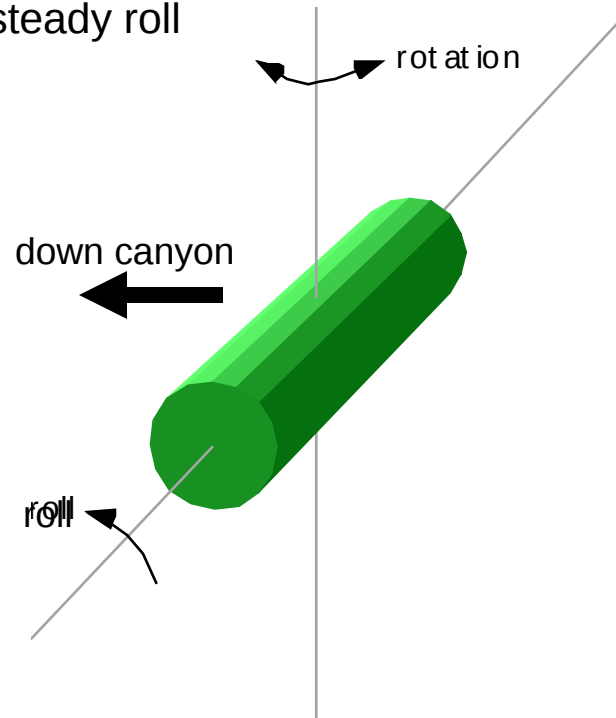
750 samples

normally distributed random events

mean=0; sd = 1

roll and azimuth independent

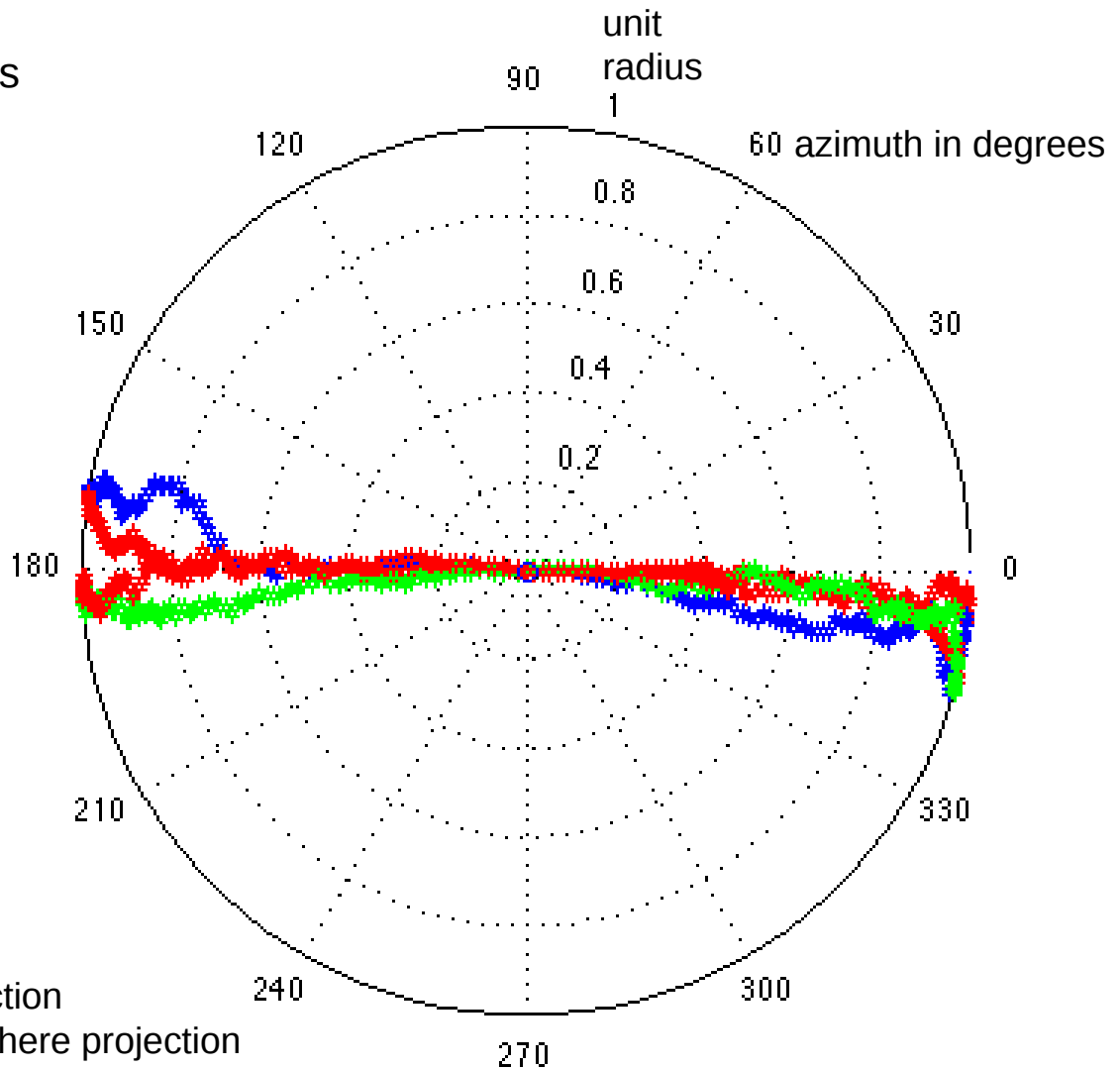
steady roll



red symbols - upper hemisphere projection

blue symbols - first roll in lower hemisphere projection

green symbols - second roll in lower hemisphere projection



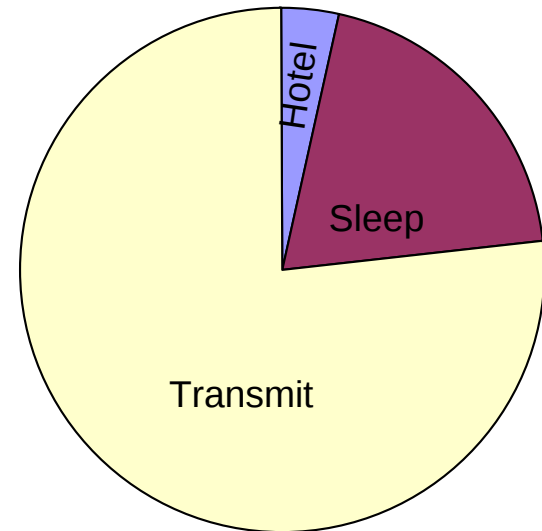
# Now what: Other uncertainties

- Will we have the power and bandwidth to transmit the data?
- How to package BED – TBD

# Data Budget

| DATA                                   |       |        |
|----------------------------------------|-------|--------|
| Variable                               | Value | Units  |
| Event Sampling Freq                    | 10    | Hz     |
| Event Duration                         | 960   | sec    |
| Individ. data record size              | 50    | Bytes  |
| Number of events                       | 5     |        |
| Individ. Event data size               | 480   | kBytes |
| Time to transmit one event at 600bps   | 6400  | sec    |
|                                        | 107   | min    |
| Time to transmit all events at 600 bps | 533   | Min    |
|                                        | 9     | Hr     |

| ENERGY                                |          |          |
|---------------------------------------|----------|----------|
| Variable                              | Value    | Units    |
| Deployment length                     | 1        | yr       |
| ROV visits                            | 3        | times/yr |
| Bottom Time                           | 3        | hours    |
| Ave Transmit Power                    | 20       | Watts    |
| Ave Sleep Power                       | 0.0105   | Watts    |
| Listening duty cycle                  | 50       | %        |
| Transmit Baud Rate                    | 600      | bits/sec |
| Control Electronics Power             | 0.001    | Watts    |
| Calculated Values                     | Value    | Units    |
| Max data transmit per visit           | 810      | kBytes   |
| Transmit Energy per visit             | 60       | WHr      |
| Annual Control energy                 | 8.76     | WHr      |
| Annual Sleep energy                   | 45.99    | WHr      |
| Annual Transmit energy                | 180      | WHr      |
| Annual Energy budget                  | 234.75   | WHr      |
| Number of Primary DD Cell<br>Li Batts | 2.934375 |          |
| min # of cells                        | 6        |          |



# Now what: Future Tests

## Modem sea trial

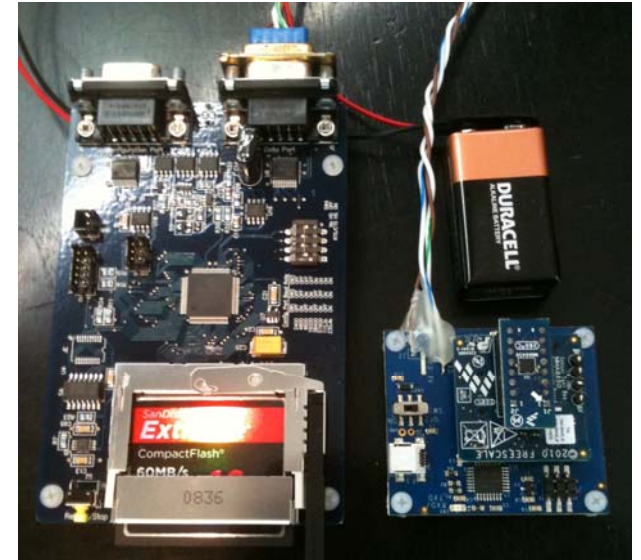
- Divers bury transducer ~1m in sediment
- Test will remove artifacts from tank testing
- Is sed-water worse than sed-sed?
- Can we avoid using an ROV for data recovery?

## Pass if:

- Data throughput  $\geq$  tank tests
- Determine additional attenuation from water/sand interface.

# Now what: Future Tests

- Research and evaluate available sensors
- Build sensor test bed
  - Package for land based test
  - Accelerate across proposed range. Varied sampling rates
  - Video tests, interpret results



Pass if:

- Collected data shows translation of package
- Proposed sampling rates adequately capture motion

# Now what: Future Tests

- Prototype BED
  - Deploy in canyon, near monument or STED
  - Limited sampling frequency
  - Limited deployment duration
  - Limited or no event detection
  - Recover full data set frequently

Pass if:

- Data is recovered
- Motion can be resolved from collected data

# Labor Resources for 2011

|               | Position            | Hours for 2011              |
|---------------|---------------------|-----------------------------|
| Brian Kieft   | Project Manager, SE | 400 wanted<br>180 allocated |
| Bill Ussler   | Project Scientist   | 400                         |
| Alana Sherman | EE                  | 440                         |
| Dale Graves   | ME                  | 270                         |
| Larry Bird    | ME                  | 270                         |
| Bob Herlien   | SE                  | 300                         |



**Hows this thing work??@#\$\$%?**



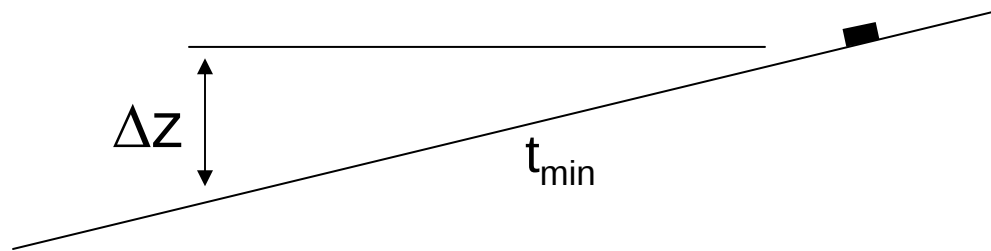
# 2011 Budget

| CATEGORY                            | COST                                 |
|-------------------------------------|--------------------------------------|
| Sensors                             | \$15,000                             |
| Interface boards                    | \$1,800                              |
| Microcomputer and ADC boards        | \$4,000                              |
| Acoustic or EM modem                | \$10,000 (acoustic) or \$25,000 (EM) |
| Mechanical packaging                | \$15,000                             |
| Sonardyne Homer Pro                 | \$8,000                              |
| Miscellaneous hardware and supplies | \$3,000                              |
| Cables and connectors               | \$3,000                              |

# What criteria is needed to select a sensor?

- Sensitivity
- Resolution
- Long-term stability
- Calibration
- Temperature compensation
- Signal conditioning - pre-amp, filters, shielded cables
- Range
- Power consumption

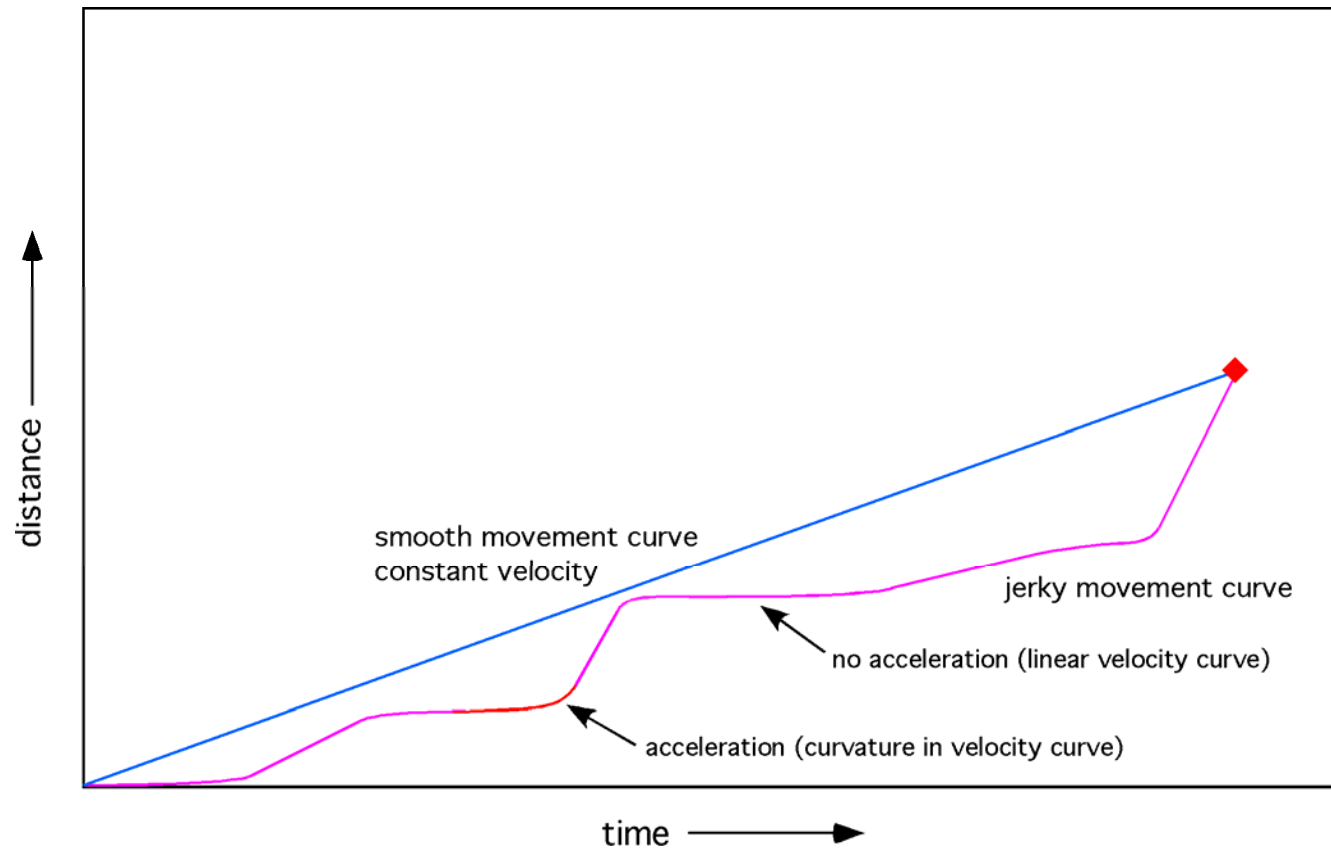
# Pressure-resolved Translation for Event Detection



| Sensor                      | Vertical resolution ( $\Delta z$ ) | Minimum translation ( $t_{\min}$ ) resolved on $1.7^\circ$ slope |
|-----------------------------|------------------------------------|------------------------------------------------------------------|
| Druck PTX600                | 15 cm                              | 5 meters                                                         |
| SeaBird standard transducer | 1.2 cm                             | 40 cm                                                            |



# Hypothetical displacement curves

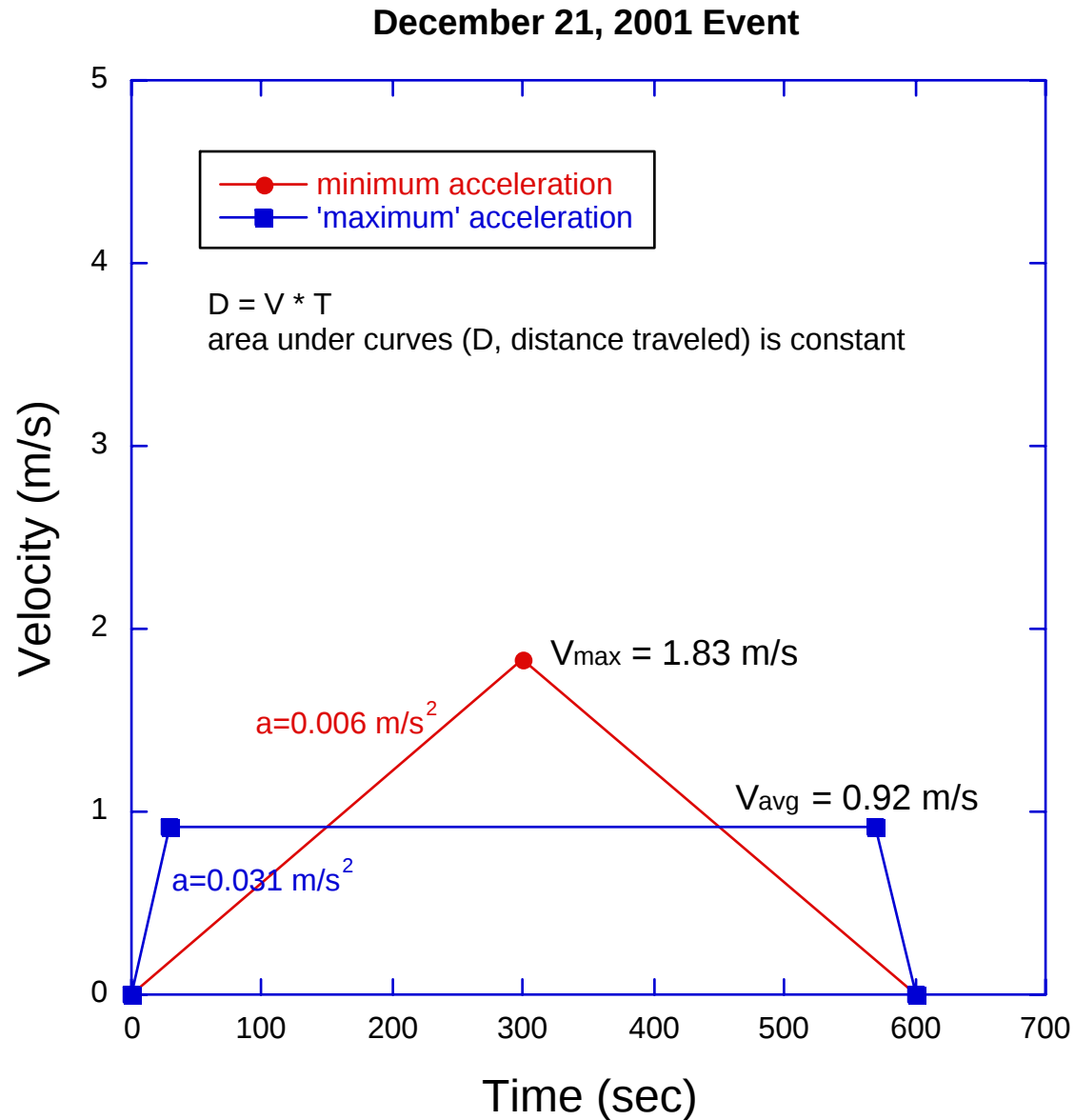


# The Raybould Defense

“ Even after the Concept Design Review you may not know with a high degree of certainty whether the concept will meet all of your Functional Requirements.”

- MBARI Guidelines for Project Design Reviews

# Range of Possible Accelerations



# Are there off-the-shelf sensors that meet our requirements?

- Acceleration - Kistler Model xx (give specs)
- Tilt - AGI tiltmeter Model xx with preAmp (give specs)
- Pressure - SeaBird OEM pressure sensor with electronics (give specs)
- Timing - ?
- Orientation - ?
- Gyros - ?
- Magnetic compass - ?
- Vibration/acoustic - ?

# Relevant work outside of MBARI and submarine studies

**Landslide research** - timing, acceleration, motion, acoustics

**Glaciology** - timing, creep, rheology, flow structure

**Geotechnical industry** - rheology, creep

**Seismology** - strainrate, wave propagation, acceleration, tilt

**Geodesy** - tilt, orientation,

**Structural Engineering** - vibration and acoustics, acceleration, tilt/sway

**Gaming Industry** - gyros and acceleration

**iPhone and clones** - gyros and acceleration

# Data Recovery

Technical and Operational Challenges of each:

1. Pop-up buoy

- Truncated data record
- Other logistic issues

2. Avalanche cord

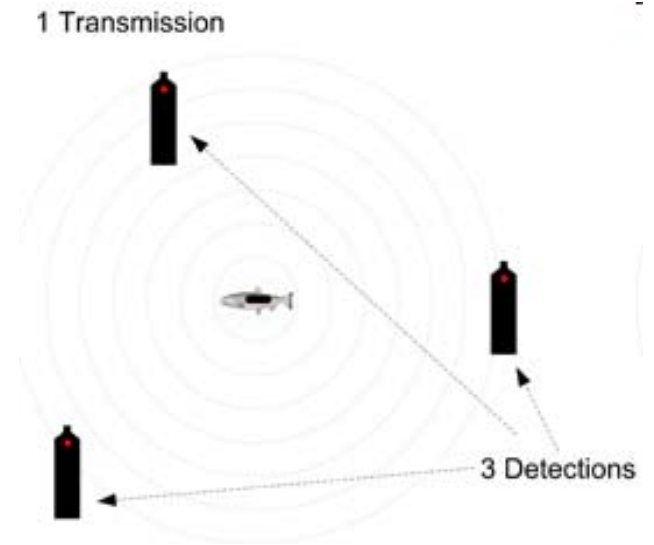
- How do you anchor
- Tether would probably break
- Excavation is difficult/impossible

# Data Recovery

Technical and Operational Challenges :

## RF ID

- Commercial RF ID tags (TI) tested short range  $<1\text{m}$
- Fish tags investigated (Vemco) range limited won't go through sediment



# Basic BEDs Concept

