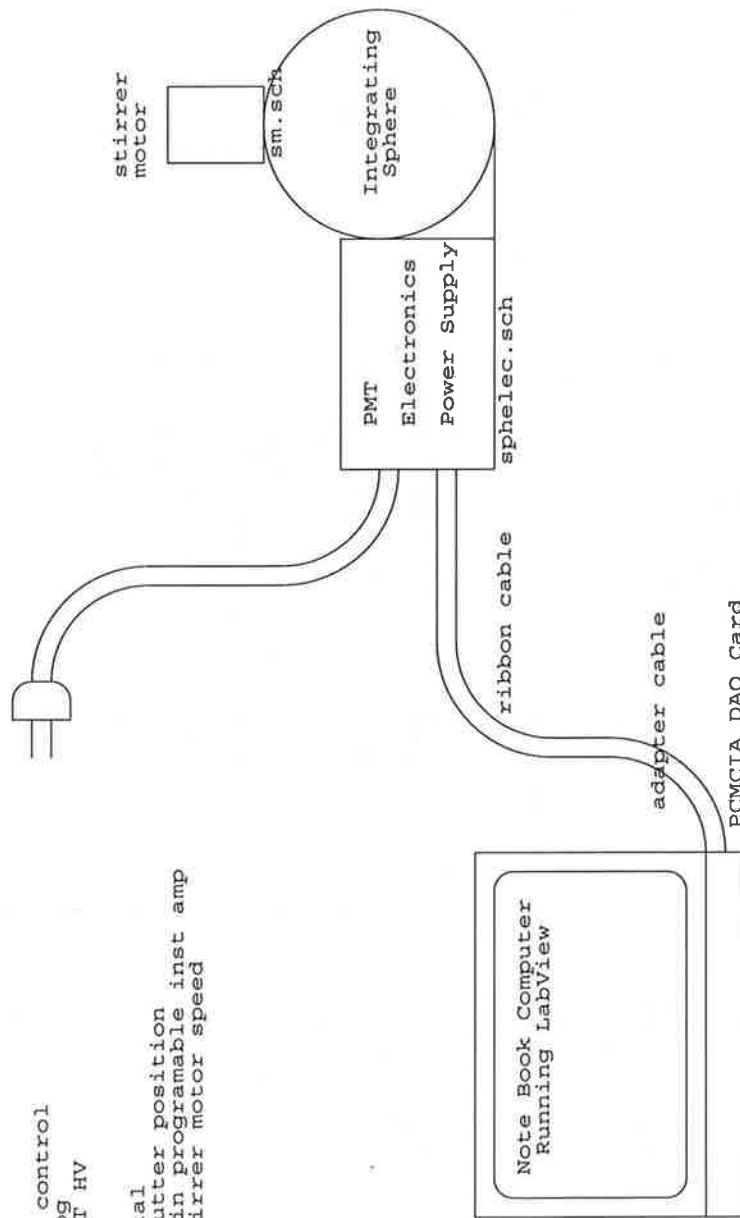


Sphere Signals SPHRSIGS. WPS 7/29/99 (scanned and modified 11/7/05)

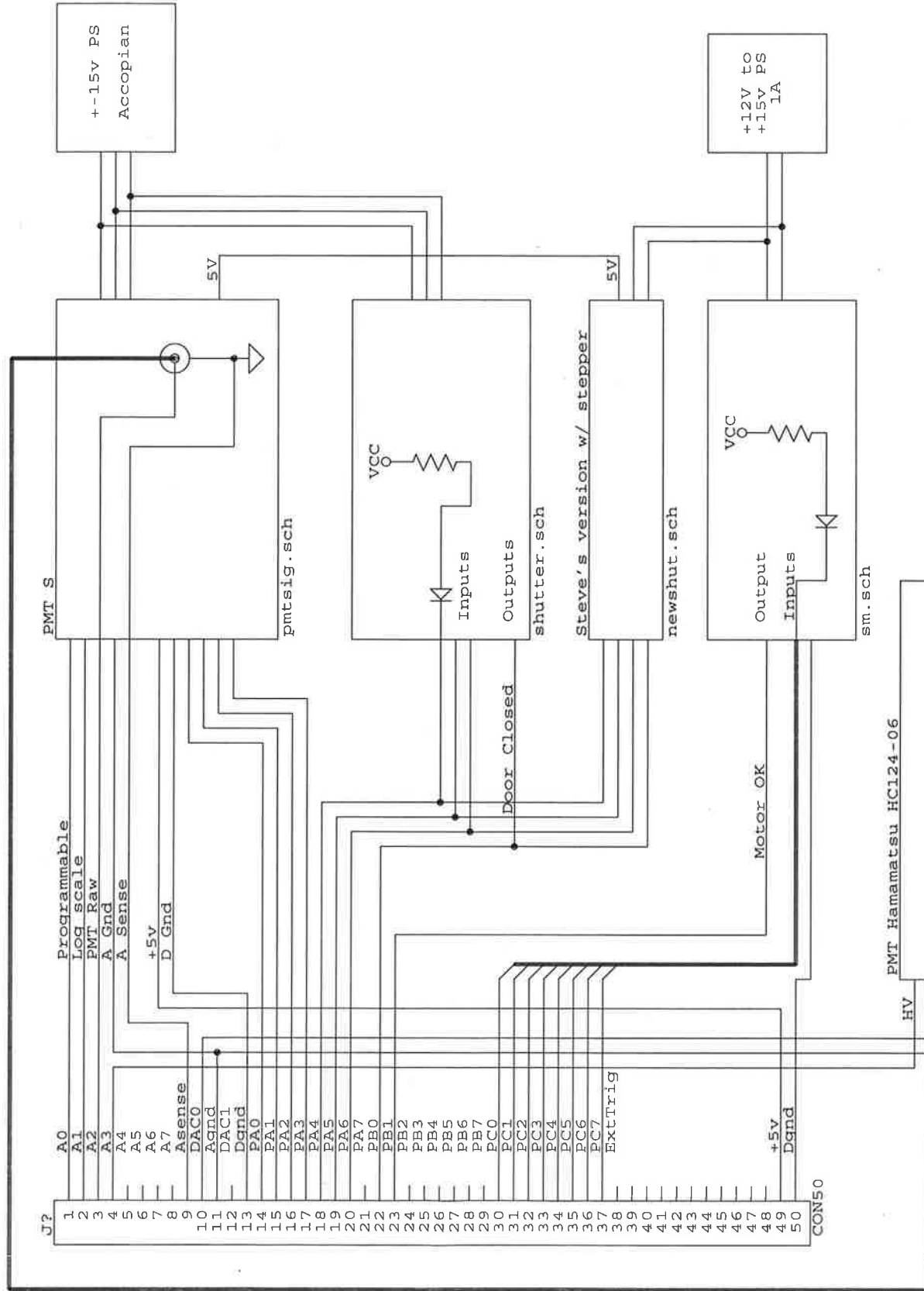
Function		Name	Pin no.	Signal desc.
PMT Prog	input	AO	1	PMT signal gain 1 to 1024 0 to 10V bandwidth 10Hz
PMT Log	input	AI	2	0 to 10 v PMT signal Log scale 5V(+/-)3.8 for 4 decades 1.9V/decade 5V=100nA
PMT Raw	input	A2	3	PMT signal 1 V = 1 uA 0 to 10V bandwidth 20K Hz
PMT HVin	input	A3	4	PMT HV feedback 1V = -1000V
PMT raw ref	input	Asense	9	PMT gnd reference use (reference) differentially for PMT Raw
Analog gnd		Agnd	11	Ground reference for Analog signals (except raw)
HV Comm. output		DACO	10	Sets PMT high voltage 10V = -1000V
Digital Gnd		Dgnd	13	
VCC		+5V	49	
PMT Gain set output		PAO	14	Digital code to set gain
"	"	PAI	15	Decimal 0 = gain 1 1 =2, 2=4
"	"	PA2	16	5=8 6=16 8=32 9=64 10=
"	"	PA3	17	128, 12=256, 13=512, 15=1024
Shutter Contr. out.		PA4	18	Shutter pos. PA4 PA5 PA6
"		PA5	19	Open 1 1 0
				first(ND.6) 0 1 0
				second(ND) 1 1 0 0
				third(ND2) 0 0 0
				close X X 1
(close shutter) output		PA6	20	when 1 always command to closed
Stirrer Motor	output	PCO	30	8bits to control speed
to	"	PC7-	37	decimal 0 or 255 = 0 rpm 40 to 1250 RPM
Door Closed	input	PBO	22	When hi = sphere door closed
Stirrer MotorOK	input	PB 1	23	

Data:

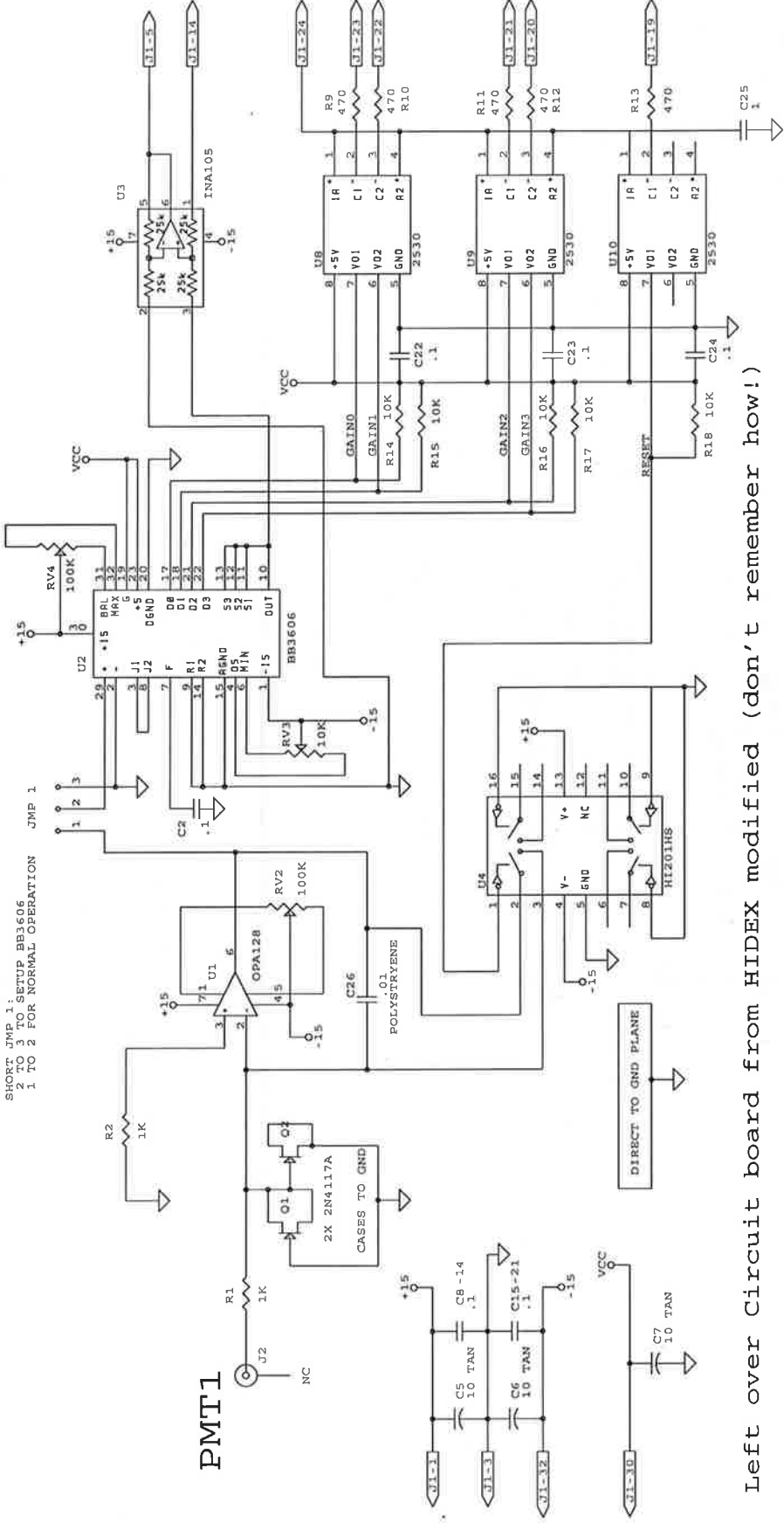
- Signals to computer
 - Analog
 - PMT
 - LOG Amp
 - Programmable Amp
 - Raw out from PMT
 - PMT HV
 - Digital
 - Door Open
- Computer control
 - Analog
 - PMT HV
 - Digital
 - Shutter position
 - Gain programmable inst amp
 - Stirrer motor speed



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By Cyril Johnson		REV
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Date:	December 3, 1999	Sheet of

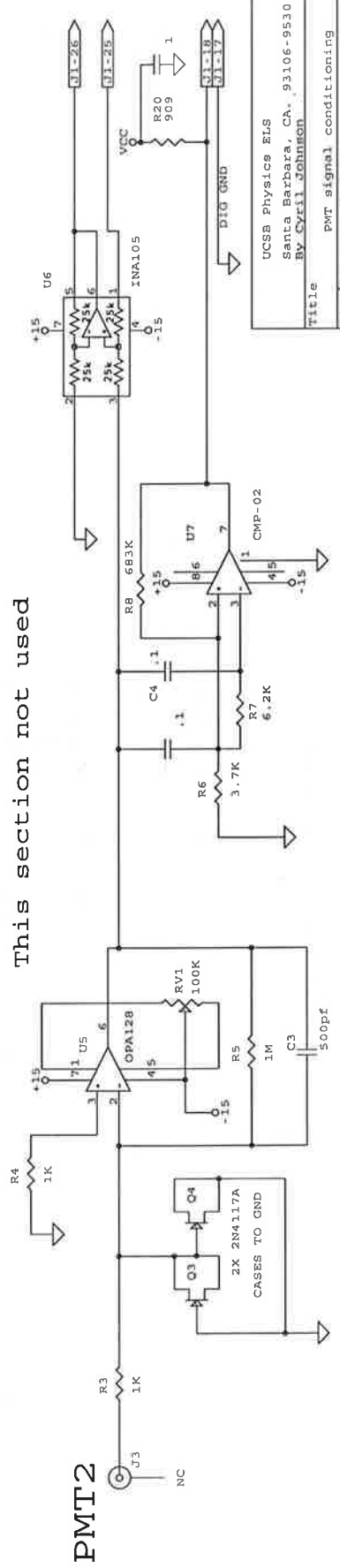


SHORT JMP 1:
2 TO 3 TO SETUP BB3606
1 TO 2 FOR NORMAL OPERATION

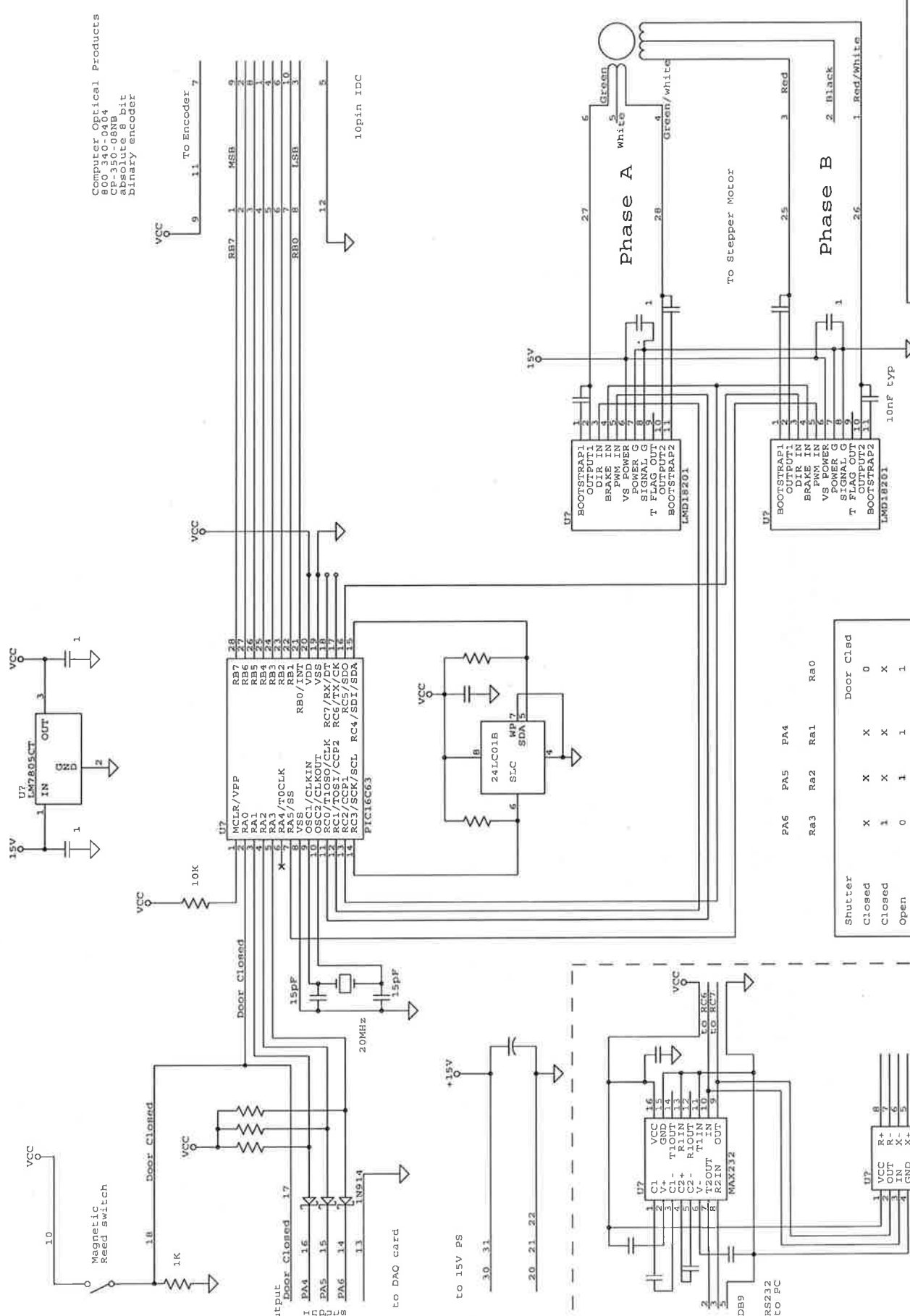


Left over Circuit board from HIDEK modified (don't remember how!)

This section not used



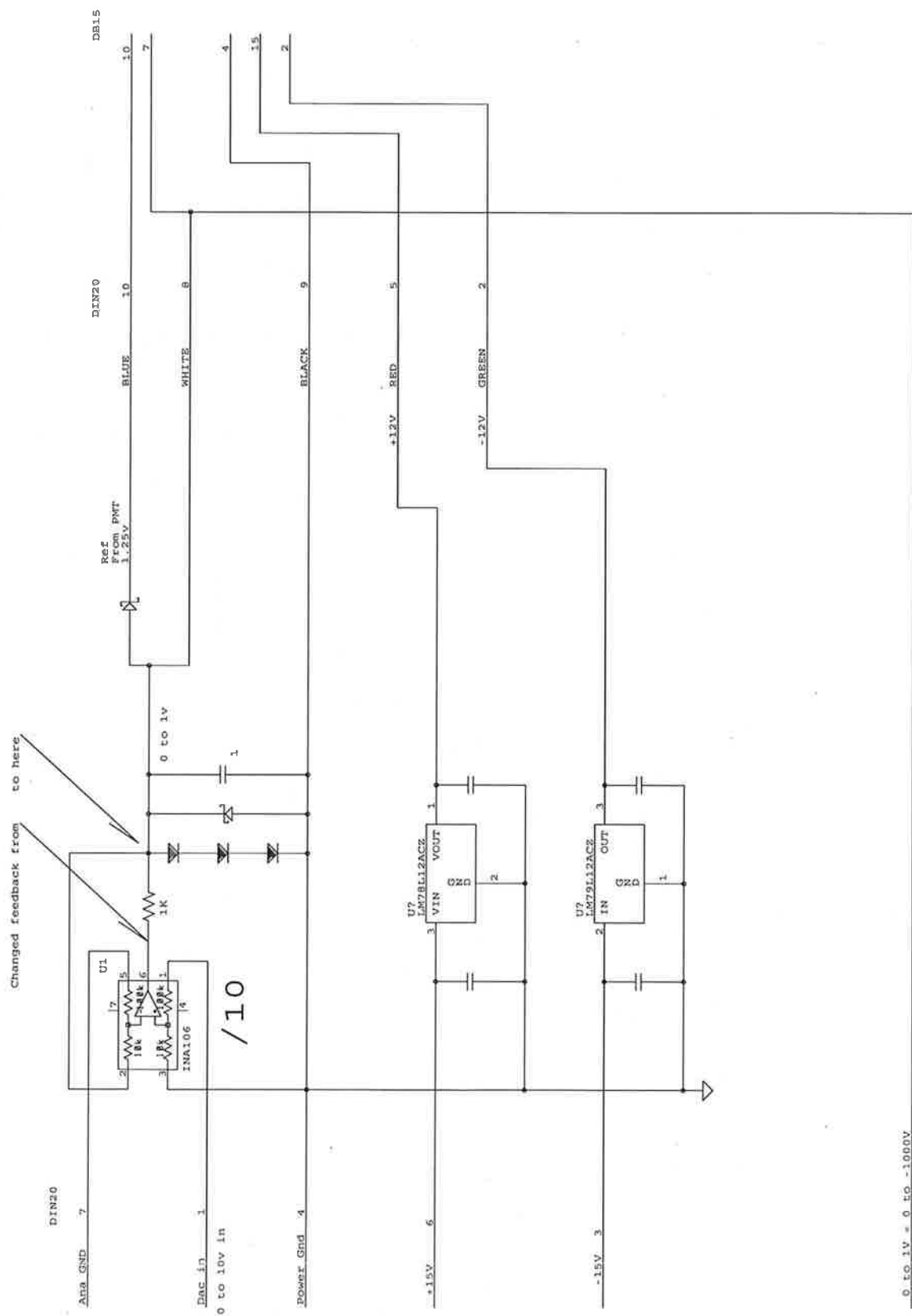




Computer Optical Products
800 340-0404
Encoder
Absolute 8 bit
binary encoder

Shutter	PA6	PA5	PA4	RA0
Closed	X	X	X	0
Open	0	1	1	1
Filter1	0	1	0	1
Filter2	0	0	1	1
Filter3	0	0	0	1

on separate board



0 to 1V = 0 to -1000V

TO DAD A/D A1N3

Pin 4 IDC50