

SV3-121: SV3 Pre-Launch Checklist

SV3 Pre-Launch Checklist

Date	2017-12-12T19:26:19.384Z	Glider Name	SV3-1531399927(SV3-121)
Tech(s)	cwahl	Organization	Mbari
Payload(s)	S1, s2, s3 and g2	Project	Canon and esp irauv
Ship/Op Area	Mb	Location	Using GPSUblox declination=13.177652, failover

Software Information

Id	SV3-121, sn=1531399927, Running Regulus 1.1.1, software version of 2016-08-24T17:05:27Z, production build
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Communication

Item/Procedure	Readings	Initials
WiFi Connection	WiFi is On	☒
Virtual Relay	ON. 0 queued msgs (Max=2500). Channel is WAITING.(no internet connectivity)	☒
WGMS Iridium	ON. 0 queued msgs (Max=1). Channel is TALKING. IMEI:300434060771430, consecutiveErrors=0, sessionError	☒
Vehicle telemetry received		☒
Tracker telemetry received	Battery (bars) 15.78 Report Rate 4 hrs	☒

Configuration

Item/Procedure	Readings	Specifications	Initials
Topside RDF Frequency	N/a		☐
Hull RDF Frequency	N/a		☐
Tracker WGMS name	Tiny tracker		☒
Drybox WGMS name	Tinytoo		☒
Float name	Tiny		☒
Glider name	Tiny		☒
Thruder Serial Number	2c001c	Last 6 digits of Hardware ID found on AMPS page	☒
Event definitions		Compare against standard list	☒
Vehicle and tracker op area defined		Note area name(s) and enable alarms	☒
Escalation list created/populated			☒

Vehicle Status

Item/Procedure	Readings	Initials
Battery [Wh] > 700 Wh	880.371	☒
Solar Power Indicators: > 0	13.349 0.0 2.04 3.18	☒

Item/Procedure	Readings				Initials
Domain Info	AMPS Hardware Status	Temperature (°C)	Pressure (kPa)	Hardware Uptime	
Domain_Name=Host, Node=1, HW_SerNum=0x333451153936383700260039 On=Y	OK	25.2	115.0	Uptime: 0 days, 18:52:30	☒
Domain_Name=Thruder-1, Node=2, HW_SerNum=0x3333470738373634002c001c On=Y	OK	29.1	167.5	Uptime: 0 days, 18:44:11	☒
Domain_Name=PydInt-	OK	22.9	116.3	Uptime: 0 days, 02:02:28	☒

0x3332470932363032002b0025, Node=4, HW_SerNum=0x3332470932363032002b0025 On=Y				
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Mechanical Checks

	Item/Procedure	Specifications	Initials
Float	Wet-mates connected/lubed	3M Silicone Lubricant Spray: 3M ID No. 62-4678-4930-3	☒
	Connector covers secure		☒
	Drybox secure	Wiggle test	☒
	Contact info secure		☒
	Hull	Free of cracks and dings	☒
	Skeg/Fin	Secure	☒
Sub	Hardware secure		☒
	Umbilical visual inspection	Free of voids/defects	☒
	Roll pins inserted	Flushed with surface	☒
	Wings	Hardware secure with Loctite and Lock Nuts	☒
	Thrudder	Hardware secure	☒

Vehicle Functionality

Item/Procedure	Readings	Specifications	Initials
Thruster Spin	0.0	Spins freely, slow and fast speeds	☒
Rudder Range of Motion		Rudder moves freely and smoothly	☒
Rudder right, left, center	Rudder(2017-12-12T19:26:16.306Z,desiredHeading=25.7,compass=20,rack=-3.9,post=-7.7rudderStatus=0x340)	Right, Left, Center	☒
Thrudder Compass Correction	Thrudder compass is NOT corrected		☒
Fixed heading test (spin)	180	Avoidance Off, Note Heading Used	☒
Waypoint course test (spin)	41	Avoidance Off, Note Waypoint Course Used	☒
Buoy Release Mechanism	device is disarmed, deviceState=OFF, deployCounter=1	Catch release buoy by hand	☒
Octopus Cable 01	OK	Must Pass	☒
Octopus Cable 02	OK	Must Pass	☒
AIS Status	MMSI 367742810 (JOHN H MARTIN). Pos=36.804023, -121.786130. t=37:0:NOT_DEFINED, 2017-12-12T19:25:4	If in harbor, must see MMSI	☒
Photo Document			☒

Vehicle Communication and Telemetry

Item/Procedure	Readings / Specifications
WX reporting	Temp=NaN°C, Press=NaNmb, Wind Speed=NaNkn, Wind Dir=NaN°. Heading=NaN°
UBLOX GPS	2017-12-12T19:26:19Z@36.8023115,-121.787163, lastRx=0.450s, quality=100, clockDt=1.555s
Airmar GPS	Not Available!
Torpedo GPS	2017-12-12T19:26:14Z@36.802318,-121.787157, lastRx=5.381s, quality=65, clockDt=6.556s
Water speed readings	Out of the water; Unknown speed; Not yet running, powerState=OFF, ampsPower=false
Obstacle Avoidance Status	Enabled
RDF beacon tested w/receiver	
Check alarms	<input all="" green"="" red.="" type="text" value="Out of bounds" yellow=""/>

Comments

G2 ecopuck plus vr2c
S1 hotspot with Mf Dat
S2 ctd plus do
S3 pco2 plus ph
Ecopuck still not working after station m cruise, no power to sensor

Technician Signature:

Note: Once vehicle is launched the following tasks must be completed

1. Clear alarms
2. Log vehicle modifications in notebook
3. Vehicle on mission
4. Create *LAUNCHED* comment into WGMS
5. Upload photos to gallery website with album name: *YYYY-MM-DD VehicleName*