

shutter 60,500
F ~ 3, ~ 5
iso ~ 25600

DeepPIV on 16 November 16 Deployment # 27 Checklist
v 5.0.0 22 August 16
K. Katija

Dive Objective: Assess sponge excurrent flow with deepPIV and Vector
current meter on sponge ridge.

-Target faux dirty sponge especially, perhaps also new white sponge (not dirty)

Deployment Date: 11/16/16

Recovery Date: 11/16/16

Person performing topside checklist: John Land

Pre-deployment alignment:

1. Verify that DeepPIV laptop and peripherals are connected (Ethernet, usb, mouse, monitor, AJA/Shogun recorder)
2. Power up DeepPIV
3. Open Silex USB Controller and connect
4. Open Sony Remote Camera Controller and modify camera settings
5. Verify laser and camera alignment
 - a. Place protective shroud around DeepPIV instrumentation
 - b. Remove protective covers on laser and camera housings
 - c. Check that housing markings on laser and camera housing are aligned
 - d. Power up the laser
 - i. Rotate the dial to 2 V in Laser dialog tab
 - ii. Record output of ADC: 2025
 - iii. Measure laser power: _____
 - e. Using digital level, compare laser sheet alignment with camera housing glass port
 - i. Record digital level reading on laser sheet: _____
 - ii. Record digital level reading on camera housing: _____
 - f. Power down the laser
 - g. Replace protective covers on laser and camera housings
 - h. Remove protective shroud from DeepPIV instrumentation
 - i. Close Remote Camera Controller software, disconnect Silex USB connection
6. Power down DeepPIV

Pre-deployment:

1. Verify that DeepPIV laptop and peripherals are connected (Ethernet, USB, mouse, monitor, AJA/Shogun recorder)
2. Power up DeepPIV
3. Run pre-dive test program and verify correct operation of the following systems:
 - a. DeepPIV camera (ISO, shutter speed, f-stop, record)
 - i. Open Silex USB Controller and connect
 - ii. Open Sony Remote Camera Controller
 - b. DeepPIV laser

- i. Power up the laser, rotate the dial to 2 V
 - ii. Record output ADC: 2.29
 - iii. Measure laser power: ✓
- c. AJA/Shogun HD recorder (record, stop, playback)
- d. Dye injector/vortex generator (disconnect tubing if dye injector being used, move piston, reset piston, set different increments)
 - i. Note COM port on ROV: _____
 - ii. Note COM port on Serial-to-USB converter (either 1/2): _____
 - iii. Open ELMO Controller software
 - iv. Direct connect to motor
 - v. Set baud rate to 19200
 - vi. Set COM port (either 3/4): _____
 - vii. Connect
 - viii. Use Velocity Mode, hit stop to prevent dye leakage
 - ix. Set speed to 100 rpm and hit go, stop; reverse direction, go, stop
- e. Translational stage
 - i. Ensure that Ethernet cable is connected
 - ii. Open ELMO Controller software
 - iii. Direct connect to motor
 - iv. Set baud rate to 19200
 - v. Set COM port (either 1/2): _____
 - vi. Connect
 - vii. Use Velocity Mode, hit stop to prevent screw from turning
 - viii. Set speed to 500 RPM and hit go, stop; reverse direction, go, stop
- f. Sizing lasers
- 4. Sync all components (including Science and DeepPIV camera) with ship's NTP and record video on both cameras
- 5. Check that all cable connectors and dummies are installed and tight
- N/A 6. Check that all dye/vortex generator tubing is installed and tight
- N/A 7. Open all dye valves and connectors
- 8. Remove protective covers on laser and camera housings
- record video of phone time

Deployment:

- 1. Deploy ROV, noting exact time and position of launch.
 - a. ROV launch time: 8:50 PDT
 - b. Latitude: 36 44.8039 deg
 - c. Longitude: 122 03.192 deg
- 2. Record time it takes for ROV to submerge: 10 min
- 3. Dive plan: refer to #3988
- 4. Start AJA/Shogun recorder when event of interest occurs; stop when finished

Recovery:

- 1. Record the time that ROV is on deck: 13:58 PDT
- 2. Power down DeepPIV
- N/A 3. Close all dye injector/vortex generator valves
- 4. Rinse instrument housings and attachments with fresh water
- 5. Replace protective covers for laser and camera housings

- download data ASAP