

pw: kakani

WINPROG - PIC DATA

ctrl + s $\Rightarrow$ start

ctrl + t $\Rightarrow$ stop

heartbeat wait non since it was not installed

launch all drivers (for simplicity)

check that RTI-DVL $\leftarrow$ DVL

VN-100 $\leftarrow$ glunco's sensor

MINIROV-NMEA $\leftarrow$ surelog (CTD, lat/long, thruster power, etc)

start drivers $\Rightarrow$ starts sensors & subroutines

start logger $\Rightarrow$ starts logging driver data

enable low cost $\downarrow$ DVL
NAV SENS

MINIROV_static.py $\leftarrow$ heading & attitude (optional)

SimpleViewer.py $\leftarrow$ track (optional)

- ① Select ubuntu
- ② Enter password: kakani
- ③ launch-pro-nv - minirov.sh $\geq$ run in terminal
- ④ ignore dialog box
- ⑤ start all drivers $\Rightarrow$ ctrl + s
- ⑥ check that RTI-DVL & VN-100 working (Cord 9 & Brod 4)
- ⑦ logger, ctrl + s
- ⑧ check low logger
- ⑨ nav, ctrl + s
- ⑩ UUV-KF not expected to work
- ⑪ viewer, ctrl + s

ctrl + t stops running the program