

Project Number: 901304

Project Start: Jan. 1, 2013

Project Duration (in years): 2

Please indicate what type of project is being proposed (mark only one).

☒	☐	☐	☐	☐
Feasibility/Scoping [Less than 100 days effort]	Development¹	Research	Infrastructure²	Education
	☐	☐		
	Time Series	Institute Initiative		

Project Manager²: Ken Smith

Principal Investigators: Francisco Chavez, Bruce Robison, Ken Smith

Lead Scientists: All the above

Lead Engineer: Alana Sherman, Kevin Gomes

Project Title: An integrated MBARI time-series program

¹ Development and infrastructure projects must complete the risk matrix (see item #5 at the end of the proposal form).

² Not all projects will require all four titles to be filled in. Please indicate individuals only for those titles that are appropriate for your project.

1) ABSTRACT (new projects only)

[Paste abstract here]

2) PROPOSAL

a) New Projects

Statement of the problem, why it is important

[Click here to enter text]

How does it relate/contribute to MBARI's mission and strategic plan?

[Click here to enter text]

How does it relate/contribute to the Packard Foundation's Ocean Visions Grantmaking policies?
(See http://mwww.mbari.org/oed/OED_Documents3.htm#Packard for documents.)

[Click here to enter text]

Approach to the problem

[Click here to enter text]

Publications (from other projects over the last 5 years)

[Click here to enter text]

b) Continuing Projects

Presently there are three independent long time-series projects being conducted at MBARI:

- ☐ *The Monterey Bay Time-Series project* is focused on the upper water column and collects data from multiple sites, relying on hydrocasts, moorings, AUVs/gliders, satellites and models.
- ☐ *The Midwater Time-Series project* collects data from mid-depths in Monterey Bay, using video transects by ROVs.
- ☐ *The Pelagic-Benthic Coupling project* collects data from the water column/benthic interface, using free-vehicle sediment traps and cameras, Benthic Rover, and ROVs.

For 2013, we proposed a feasibility and scoping project to determine if we can integrate these three efforts and develop a collaborative database. Each project is presently focused on a different habitat and each employs different technologies, but together they cover the predominant oceanic habitats of the region (Figure 1), from surface to benthos. In the first seven months of this project we have explored options for scientific coordination and technology development between the three projects. Our primary

goals have been to add value to the scientific and technological impacts of our time-series projects through increased data accessibility and widespread standardization of measures and data products, while also increasing efficiency and reducing costs.

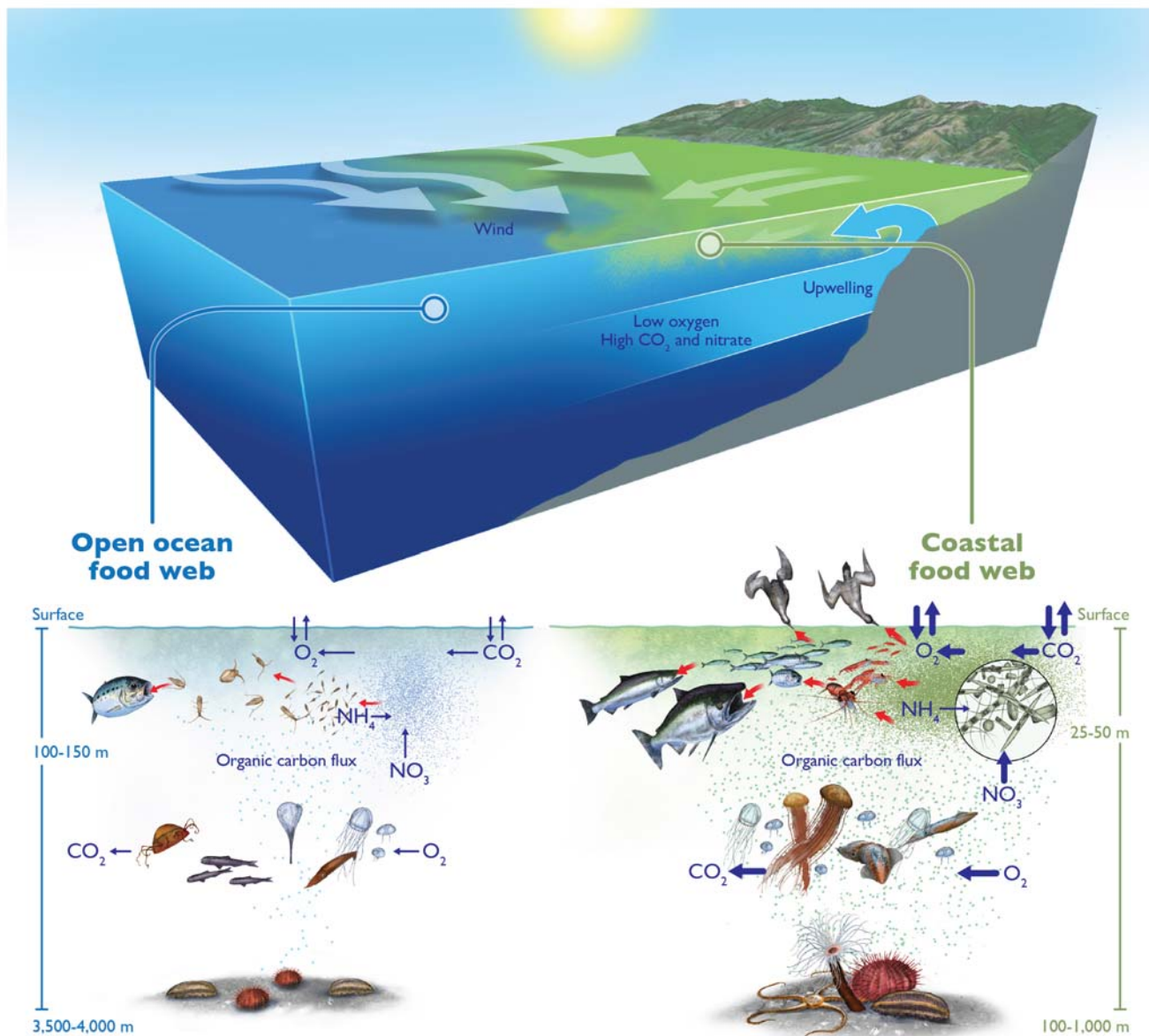


Figure 1. Predominant oceanic conditions and carbon exchanges in coastal California.

Current status of project and results to date

We have had monthly meetings since January to discuss the integration of the three time series projects with the following results to date:

1. Principal investigators agree to continue to occupy two time series stations in the future. A) A station representative of Monterey Bay in the vicinity of M-1 and Midwater #1, the location of

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which may also be influenced by the position of a MARS extension. B) Sta. M to represent the off-shore region of the California Current. Figure 1 depicts the ecosystem at both stations.

2. Merged data sets show similar trends from surface waters to abyssal depths over the 24-yr time series at both Sta. M-1/Midwater#1 and M. The surface water temperature anomaly shows significant cooling events since 2000 with increasing surface chlorophyll and decreasing dissolved oxygen (Fig. 2A,B,C). From 2002 to 2010, there was a major increase in *Dosidicus gigas* sightings in midwater (Fig. 2D). At abyssal depths the particulate organic carbon (POC) flux has significantly increased reaching major peaks in 2011-2012, the largest documented thus far at Sta. M (Fig. 2E).
3. Kevin Gomes has been integrating the existing data products from each of the three time-series projects. These parameters are summarized in Figure 3 with a more detailed flow sheet shown separately (Appendix, Fig. 1).
4. Alana Sherman and Brett Hobson have generated a table of measurements and currently employed instrumentation for each time series (Table 1). Together, we are working toward refining this table to integrate the time-series measurements at two stations, and identify the needed platforms and sensors envisioned in the future. Alignment with the Technology Roadmap is a key goal of this process.

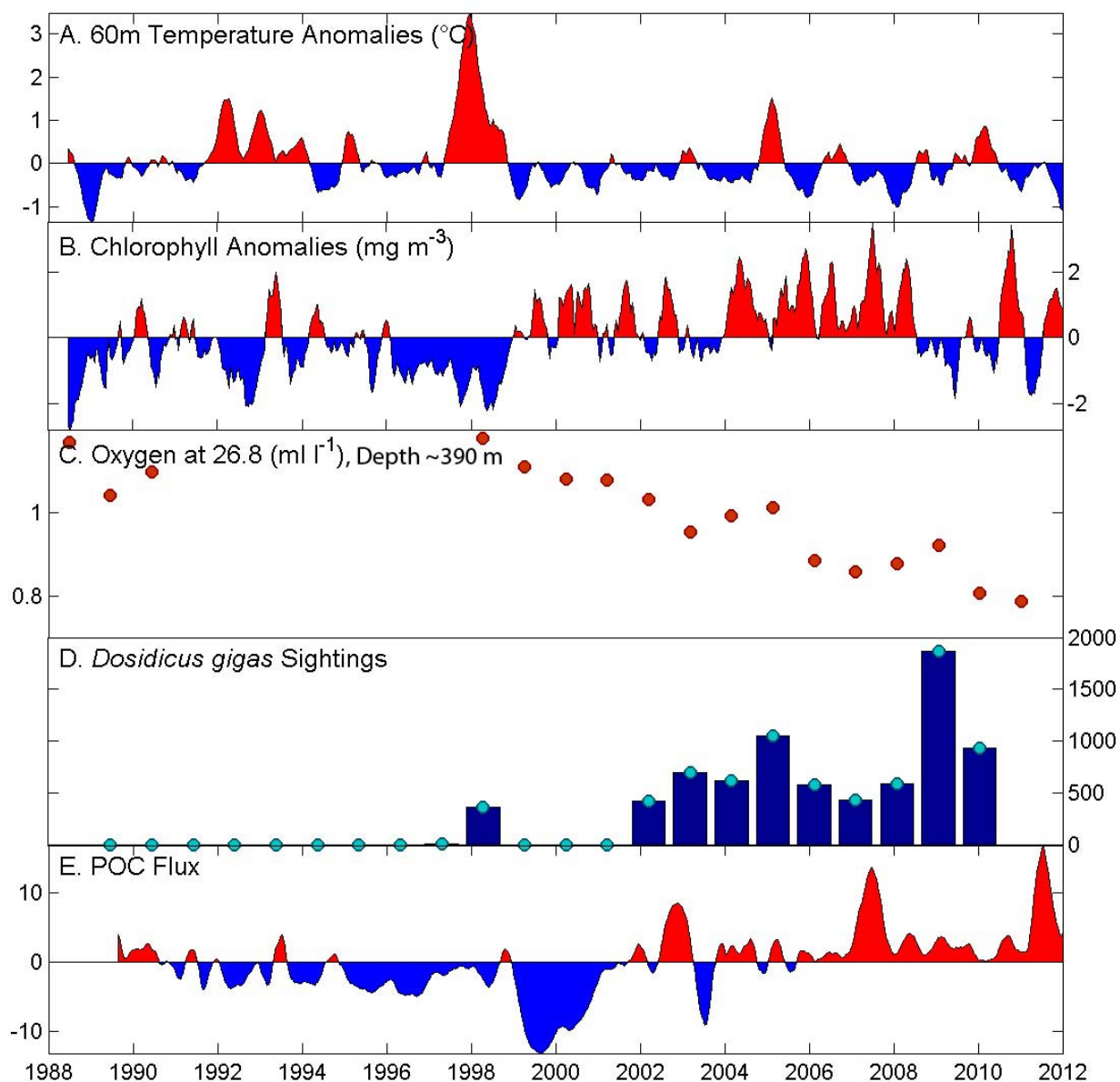


Figure 2. Integration of long-term time series data from surface to the deep-sea.

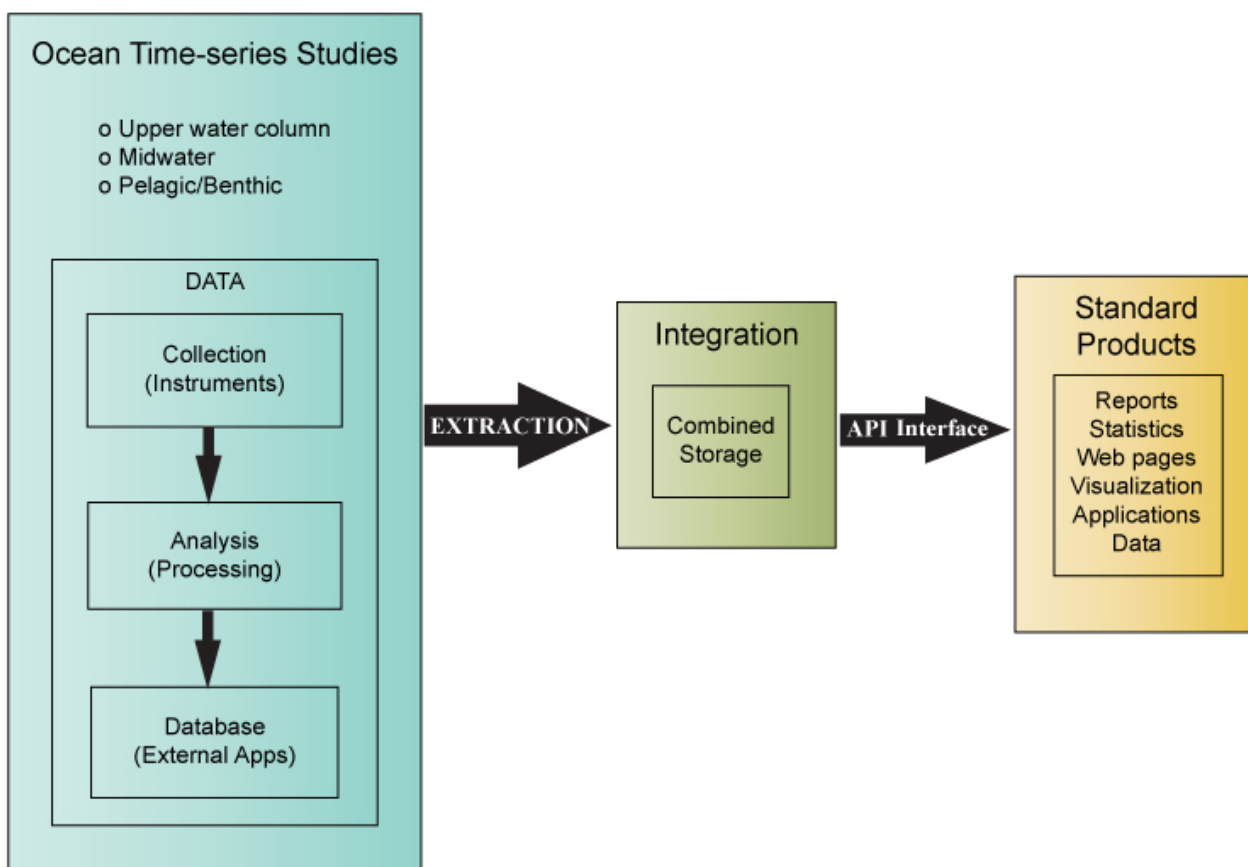


Figure 3. Schematic of time-series data integration. See appendix, figure 1 for details.

Significant changes from previous project proposal

None

Publications based on the results of this project only

None to date

c) New and Continuing Projects: Plans for 2014

Research Activities

1. Complete the integration of existing data sets from the three time-series projects.

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2. Identify the representative measurements needed to continue the time-series studies at both Sta. M-1/Midwater #1 and M.
3. Identify the sensors and platforms needed to carry out time-series measurements at both stations over the next 3 to 5 year and 5 to 10 year periods in concert with the projected technology in the Tech Roadmap, and projects such as i2Map and the VPC which are already underway.
4. Prepare a manuscript describing the integrated time-series data sets, and demonstrating how such studies are critical to understanding climate change impacts on marine ecosystems, from surface waters to the seafloor. We plan to submit this manuscript to a peer-reviewed journal.
5. Develop the integrated time series study with the vision of exporting the technology to other scientists, allowing them to replicate these studies in other areas of the world ocean.
6. Conduct a “synoptic” pilot survey of both stations using existing sensors on the LRAUV to measure upper water column parameters. We propose to conduct this survey in January-February 2014 as a proof-of-concept exercise to interrogate the Rover and SES at Sta. M for status reports. We aim to use these results as part of a full integrated time-series proposal to be submitted for 2015. The cost of operating the LRAUV, using a wave glider for towing out to Sta. M, has been added to the Pelagic-Benthic proposal (#901113).

Engineering/technology development

We have found this study is best represented by integration of engineering and science objectives (see above).

Field programs (detail ship requirements/deployments/diver requirements)

Conduct a “synoptic” survey of both stations using the LRAUV to measure upper water column parameters with existing sensors and interrogate Rover and SES for status reports at Sta. M. This survey will also be used for comparative measurements with Ken Johnson’s long-term float in the vicinity of Sta. M, collecting chlorophyll and nitrate data. We propose to conduct this survey in January-February 2014 as a proof-of-concept so that the results could be generated for use in a full integrated time-series proposal for 2015. The cost of operating the LRAUV with towing out to Sta. M by a wave glider, has been added to the Pelagic-Benthic proposal.

Specific deliverables

Integrated approach to time-series studies at MBARI documented in manuscript to be published in refereed journal

Milestones (see [personnel classification list](#))

Requested engineering time follows the limitations set by the MT for our 2013 project.

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2014 Project Start Date: MM/DD/2014	Milestone 1	Milestone 2	Milestone 3	Milestone 4	Milestone 5	Total Resources³ for each resource category for all milestones listed here
Milestone Date	Spring - 2014	Spring - 2014	Spring - 2014	Fall - 2014	Winter - 2014	
Milestone Description	Research Activity #1	Research Activity #2	Research Activity #3	Research Activity #4, #5	Research Activity #6	
EE			A.S. 20	A.S. 5	A.S. 15	40
SE	K.G. 60	K.G. 60	K.G. 60	K.G. 60	K.G. 56	296
ME			B.H. 20	B.H. 5	B.H. 15	40
EE Tech						
SE Tech						
ME Tech						
Machine Shop						
Divers						

Budget justification

No funding requested

Project team

Francisco Chavez, Bruce Robison, Ken Smith, Alana Sherman, Kevin Gomes, Brett Hobson, Crissy Huffard, Rob Sherlock, Tim Pennington, Reiko Michisaki

Project lab space

None required

Data availability outside project team, uniqueness

The final publication in a peer reviewed journal will present an organized overview of the datasets being generated by this project. Data requests by external researchers can be evaluated on a case-by-case basis in accordance with MBARI policy. The integrated database will allow data to be extracted and summarized easily for sharing as appropriate.

³ This number should be the same number you entered on the resource requests for this particular resource.

Export Regulation

None

Monterey Bay National Marine Sanctuary SESAs ([General map](#))

Projects will need to indicate whether or not work will be conducted within one of the Monterey Bay National Marine Sanctuary's Ecologically Significant Areas (SESAs). An interactive map can be found on the Sanctuary's SIMoN webpages at <http://sanctuarysimon.org/maps/sesa/>. (Note: It may take a moment for the page to load, so please be patient.) To determine if your work will occur in a SESA, specific coordinates can be entered using the locator function (click on the red "target" button in the toolbar at the top of the map). If your work will be conducted in one of these areas, please indicate which area, by number.

None

Risk matrix (development and infrastructure projects only)

	Technical Risk	Organizational Risk	Tech Transfer Risk	Labor Estimate Risk
High				
Medium				
Low	X	X	X	X

Table 1. Current and proposed parameters measured for integrated time-series

Parameter	Approximate depth	Instrument	Platform today
Beam Attenuation	0m	Chelsea/Seatech/Wetlab Cstar	Ship, Underway
Beam Attenuation	0m to 1000m	CTD: Chelsea/Seatech/Wetlab Cstar	Ship Cast
Chla	0m	WetStar/SeaTech/Turner	Ship, Underway
Chla	0m to 1000m	CTD: Fluorescence, Wetlab ECO-AFL/FL	Ship Cast
Chlorophyll	0m to 1000m	Water samples: Turner Fluorometer	Ship Cast
Chlorophyll	3950 m	SES: fluorescence, image	Mooring
Chlorophyll	4000m	Rover fluorescence	Benthic Rover
Conductivity	0m	SBE	Ship, Underway
Conductivity	0m to 1000m	CTD: SBE	Ship Cast
Density	0m to 1000m	CTD: SBE	Ship Cast
Faunal communities	50-1000m (ROV transects)	HD, color video	ROV
Faunal communities	4000m (time lapse)	moored time lapse camera	Mooring
Faunal communities	4000m (ROV transects)	HD, color video	ROV
Fluorescence	0m	WetStar/SeaTech/Turner	Ship, Underway
Fluorescence	0m to 1000m	CTD: Fluorescence, Wetlab ECO-AFL/FL	Ship Cast
Nutrients	0m to 1000m	Water samples: AlpChem autoanalyzer	Ship Cast

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Oxygen	0m to 1000m	CTD: SBE	Ship Cast
Oxygen	0m to 1000m	Water samples	Ship Cast
Oxygen	50-1000m, 1000m	ROV, CTDO	ROV
Particulate CHN	4950 and 3400m	Sediment traps	Mooring
Particulate organic matter	51 and 600 mab	SES	Mooring
pH	0m	Durafet II	Ship, Underway
Phytoplankton	0m to 1000m	CTD: Epifluorescence Microscopy	Ship Cast
Phytoplankton	4950 and 3400m	Sediment traps, microscopy, SES	Mooring
Primary Production	0m to 1000m	Water samples: Beckman LS-3801 liquid scintillation counter	Ship Cast
Salinity	0m	SBE	Ship, Underway
Salinity	0m to 1000m	CTD: SBE	Ship Cast
Salinity	50-1000m, 4000m	ROV, CTDO	ROV
Sediment CHN, chlorophyll	4000m	Sediment cores	ROV
Sediment community O2 use	4000m	Benthic Rover transect	Benthic Rover
TCO2	0m	Licor 820	Ship, Underway
TCO2/Alkalinity	0m to 1000m	CTD: Licor 820	Ship Cast
Temperature	0m	SBE	Ship, Underway
Temperature	0m to 1000m	ROV,CTDO	ROV
Transmissivity	0m	Chelsea/Seatech/Wetlab Cstar	Ship, Underway
Transmissivity	0m to 1000m	CTD: Chelsea/Seatech/Wetlab Cstar	Ship Cast,ROVt
Zooplankton (cms)	50-1000m	HD, color video	ROV
Zooplankton (microns - cms)	0-100m, 100m intervals to 1000m	Vertical camera profiler, acoustic profiler, Holo camera	Ship Cast/AUV

Table 1 ctd.

Platform Start of Time Series Project	Platform 3- 5 yr into project	Ultimate platform
wave glider?	Wave glider	Wave glider
ship cast/AUV Gulper (in shore)	Vertical profiler/AUV	Energy harvesting verticle profiler
wave glider?	Wave glider	Wave glider
ship cast/AUV Gulper (in shore)	Vertical profiler/AUV	Energy harvesting verticle profiler
ship cast/AUV Gulper (in shore)	LRAUV water sampler	In situ measurement
Mooring	Mooring	Mooring
Benthic Rover	Extended Benthic Rover	Extended Benthic Rover
wave glider?	Wave glider	Wave glider
ship cast/AUV Gulper (in shore)	Vertical profiler/AUV	Energy harvesting verticle profiler
ship cast/AUV Gulper (in shore)	Vertical profiler/AUV	Energy harvesting verticle profiler
i2map	i2map on AUV3	i2map on AUV3
Time Lapse Camera	Time Lapse Camera	AUV serviceable Time-lapse camera
ROV	Benthic Imaging on AUV3	Benthic Imaging on AUV3
wave glider?	Wave glider	Wave glider
ship cast/AUV (in shore)	Vertical profiler/AUV	Energy harvesting verticle prfiler

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ship cast/AUV Gulper (in shore)	LRAUV water sampler	In situ measurement
ship cast/AUV Gulper (in shore)	Vertical profiler/AUV	Energy harvesting verticle prfiler
ship cast/AUV Gulper (in shore)	LRAUV water sampler	In situ measurement
ROV	Dorado,0-1000m	LRAUV deep
Mooring	Mooring- extended deployment?	In situ Carbon measurement
SES	SES upgraded	SES upgraded
Mooring	Wave glider	Wave glider
ship cast/AUV Gulper (in shore)	LRAUV water sampler	In situ measurement
Mooring	Mooring	Mooring
ship cast/AUV Gulper (in shore)	LRAUV water sampler	In situ measurement
Mooring	Wave glider	Wave glider
ship cast/AUV Gulper (in shore)	Vertical profiler/AUV	Energy harvesting verticle prfiler
ROV	Dorado, 0-1000m	LRAUV deep
ROV	Benthic Rover with corer	Benthic Rover with corer
Benthic Rover	Extended Benthic Rover	Extended Benthic Rover
wave glider?	Wave glider	Wave glider
ship cast/AUV Gulper (in shore)	Vertical profiler/AUV, Dorado	Energy harvesting verticle prfiler
wave glider?	Wave glider	Wave glider
ship cast/AUV Gulper (in shore)	Vertical profiler/AUV	Energy harvesting verticle prfiler
wave glider?	Wave glider	Wave glider
ship cast/AUV Gulper (in shore)	Vertical profiler/AUV	Energy harvesting verticle prfiler
i2map	i2map on LRAUVdeep	i2map on LRAUVdeep
AUV with Holo camera	AUV with Holo camera	AUV with Holo camera

Table 1 ctd.

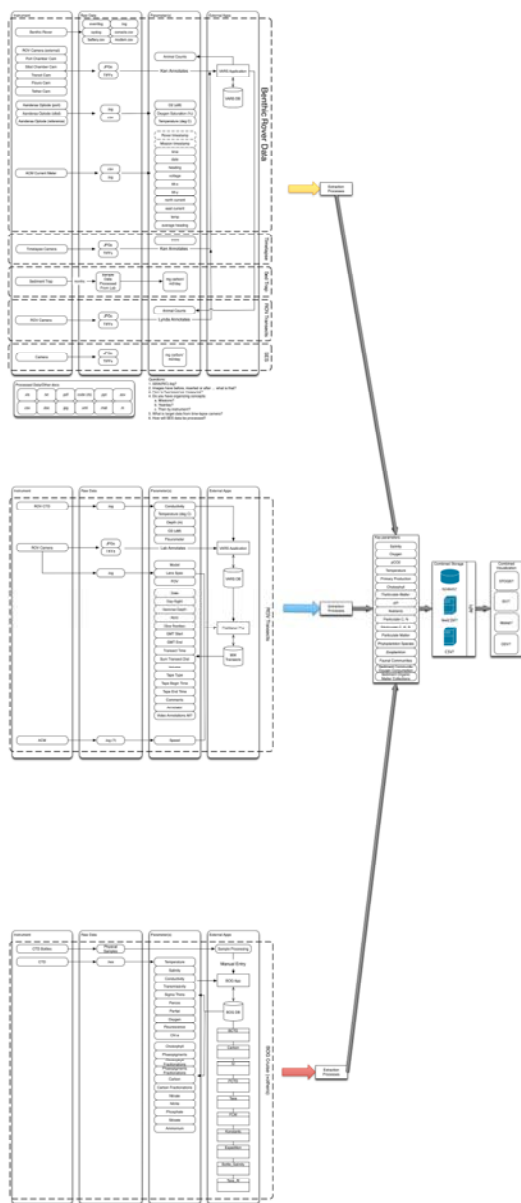
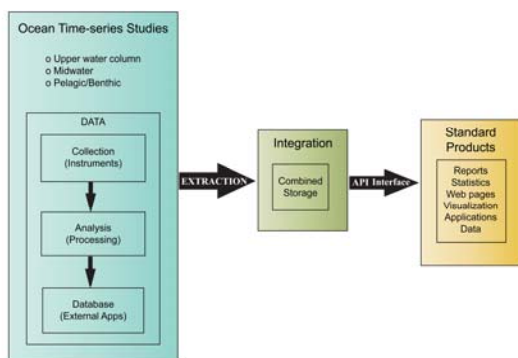
How often today?	How often future?
every 21 days	(blank)
every 21 days	(blank)
every 21 days	(blank)
every 21 days	(blank)
every 21 days	(blank)
3-12 hours	3-12 hours, adjustable
2-4 day	(blank)
every 21 days	(blank)
every 21 days	(blank)
every 21 days	(blank)
daily to weekly	monthly
hourly	(blank)
6-12 months	monthly
every 21 days	(blank)
every 21 days	(blank)

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every 21 days	(blank)
every 21 days	(blank)
every 21 days	(blank)
Every two months, Midwater, annually benthic	monthly
every ten days	(blank)
6-12 hour	(blank)
every 21 days	(blank)
every 21 days	(blank)
every ten days	(blank)
every 21 days	(blank)
every 21 days	(blank)
every 21 days	(blank)
every 21 days	(blank)
Every two months, Midwater, annually benthic	(blank)
6-12 months	(blank)
2-4 day	(blank)
every 21 days	(blank)
every 21 days	(blank)
every 21 days	(blank)
every 21 days	(blank)
every 21 days	(blank)
every 21 days	(blank)
30-60 days	monthly
daily to weekly	(blank)

Appendix, Figure 1. Detailed organization of time-series data integration

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Appendix, Figure 2

1. M1: SE 60
2. M2: SE 60
3. M3: SE 60
4. M4: SE 60
5. M5: SE 56

Kevin

☞ ☰ Title	Effort		Qtr 1
▼ 1) Identify combined visualization platform (STOQS?, IDV?, Matlab?, etc.?)	1w 4d		
• 1.1) Generate list of options for combine visaualization	2d		
• 1.2) Create comparison document for combined visualization	1w		
• 1.3) Conduct review on visualization tool	2d		
• 2) Identify combined parameter storage mechanism (RDMBS?, File?, MongoDB?)	2d		
▼ 3) Smith Lab – Extract key parameters	1w 2d		
• 3.1) Identify where parameters are in sources	2d		
• 3.2) Write extraction processes	1w		
▼ 4) Robison Lab – Extract key parameters	1w 2d		
• 4.1) Identify where parameters are in sources	2d		
• 4.2) Write extraction processes	1w		
▼ 5) Chavez Lab – Extract key parameters	1w 2d		
• 5.1) Identify where parameters are in sources	2d		
• 5.2) Write extraction proceses	1w		
• 6) Write loader to pull extracted parameters into combined visualization	1w		