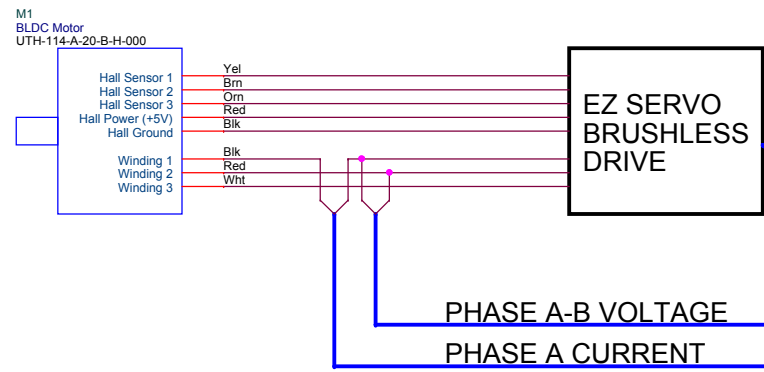


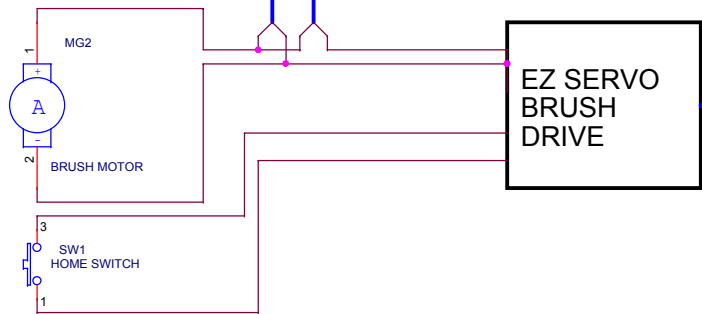
TO LRAUV LOAD CONTROL PCB

LRAUV LAB DATA COLLECTION SYSTEM PHASE 1

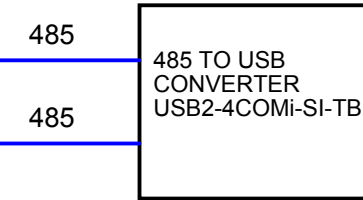
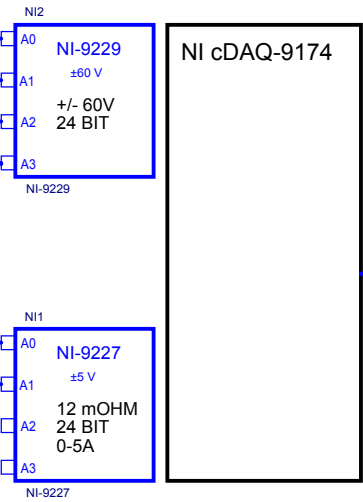
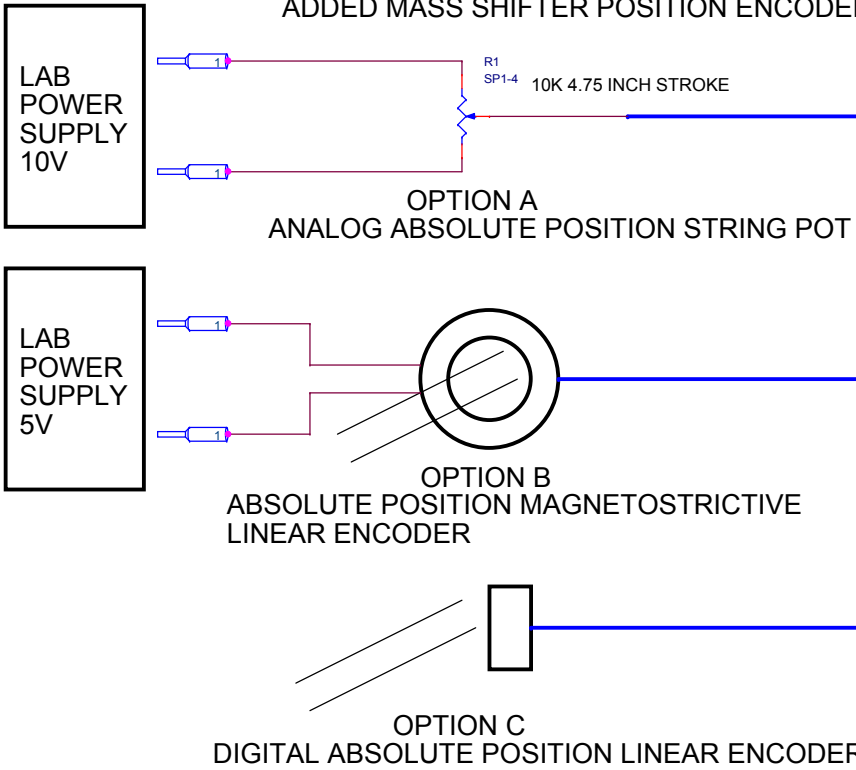
THRUSTER MOTOR



MASS SHIFTER MOTOR



ADDED MASS SHIFTER POSITION ENCODER



USB 2.0

USB 2.0

USB 2.0

HOST COMPUTER
RUNNING WINDOWS
AND PYTHON

MONTEREY BAY AQUARIUM RESEARCH INSTITUTE
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Title **LRAUV LAB DATA COLLECTION SYSTEM PHASE 1**

Size	Engineer: Mark Chaffey EMAIL: chma@mbari.org	Number	<Doc>	Rev	A
Customer:	Wednesday, March 21, 2018	Filename	<Filename>	Sheet	1 of 1