



Call 1-800-GO-VEXTA(468-3982) or 1-847-871-5931



- given information -

Table shape and dimensions

Table type = Round Table

Diameter D = 6 [in]

Width A = [in]

Depth B = [in]

Weight W = .5 [lb]

Thickness t = [in]

Material ρ = [oz/in³]

Drive shaft dimension

Shaft diameter D_2 = .25 [in]

Shaft weight W_2 = .2 [lb]

Shaft length L = [in]

Shaft material ρ_2 = [oz/in³]

Load shape and dimensions

Load type Rectangular pillar type

Diameter D_1 = [in]

Width A_1 = 1 [in]

Depth B_1 = 2 [in]

Distance from the table center to the load center r = 2 [in]

Number of loads n = 1 pc

Load weight $W_1 = \underline{\hspace{1cm}.5\hspace{1cm}} \text{ [lb]}$

Load height $h_1 = \underline{\hspace{1cm}} \text{ [in]}$

Load material $\rho_1 = \underline{\hspace{1cm}} \text{ [oz/in}^3\text{]}$

Table support

Friction coefficient between the table and the supporting mechanism $\mu = \underline{\hspace{1cm}0.05\hspace{1cm}}$

Distance from the table center to the supporting mechanism $l = \underline{\hspace{1cm}2\hspace{1cm}} \text{ [in]}$

System efficiency $\eta = \underline{\hspace{1cm}75\hspace{1cm}} \%$

Mechanism Condition

Mechanism Condition Horizontal operation

Other requirement(s)

Is it necessary to hold the load even after the power supply is turned off? $\rightarrow \underline{\hspace{1cm}NO\hspace{1cm}}$

Is it necessary to hold the load after the motor is stopped, but not necessary to hold after the power supply is turned off? $\rightarrow \underline{\hspace{1cm}NO\hspace{1cm}}$

Operating conditions

Fixed speed operation Operating speed $V_1 = \underline{\hspace{1cm}1\hspace{1cm}} \text{ [r/min]}$

Acceleration / deceleration time $t_1 = \underline{\hspace{1cm}10\hspace{1cm}} \text{ [s]}$

Stopping accuracy

Stopping accuracy $\pm \Delta\theta = \underline{\hspace{1cm}200\hspace{1cm}}^\circ$

$\pm \Delta l = \underline{\hspace{1cm}} \text{ [in]}$

Safety factor

Safety factor $S \cdot F = \underline{\hspace{1cm}1.5\hspace{1cm}}$

- calculated result -

Load Inertia

$$J_t = (1/8)(w \times 16) \times D^2$$

$$= (1/8)(.5 \times 16) \times 6^2 = 36 \text{ [oz-in}^2\text{]}$$

$$J_s = (1/8)(W_2 \times 16) \times D_2^2$$

$$= (1/8) \times (.2 \times 16) \times .25^2 = 2.5000\text{e-2 [oz-in}^2\text{]}$$

$$J_1 = (1/12)(W_1 \times 16) \times (A_1^2 + B_1^2 + 12 \times r^2) \times n$$

$$= (1/12)(.5 \times 16) \times (1^2 + 2^2 + 12 \times 2^2) \times 1 = 35.33 \text{ [oz-in}^2\text{]}$$

$$J_L = J_t + J_s + J_1$$

$$= (.36 + 2.5000\text{e-2} + 35.33) = 71.36 \text{ [oz-in}^2\text{]}$$

Required Speed

$$V_m = V$$

$$= 1 \text{ [r/min]}$$

Required Torque

$$T = (T_a + T_L)(\text{Safety Factor})$$

$$= (1.2099\text{e-4} + 0.1333) \times 1.5 = 0.2002 \text{ [lb-in]}$$

$$= 3.203 \text{ [oz-in]}$$

Acceleration Torque

$$T_a = (J_L / 386) (V_m / (9.55 \times t_1)) (1 / 16)$$

$$= (.71.36 / 386) \times (1 / (9.55 \times 10)) \times (1 / 16) = 1.2099\text{e-4 [lb-in]}$$

$$= 1.9358\text{e-3 [oz-in]}$$

Load Torque

$$W_T = W$$

$$= .5 = 0.5000 \text{ [lb]}$$

$$W_1 = w_1 \times n$$

$$= \underline{.5} \times \underline{1}$$

$$= \underline{0.5000} \text{ [lb]}$$

$$T_L = (W_T + W_I) \mu (1 / (\eta \times 0.01))$$

$$= (\underline{0.5000} + \underline{0.5000}) \times \underline{0.05} \times \underline{2} \times (1 / (\underline{75} \times 0.01))$$

$$= \underline{0.1333} \text{ [lb-in]}$$

$$= \underline{2.133} \text{ [oz-in]}$$

Required Stopping Accuracy

$$\Delta\theta = \Delta\theta$$

$$= \underline{200}$$

$$= \underline{200} \text{ [deg]}$$

Other requirement(s)

- end of the report -

