

```
#include "CCE2_hamilton_v1.spec"
```

Problem Description

```
title = TITLE
type  = surface
```

```
/* Weights are in Newtons */
```

Analysis Parameters

```
static-relaxation = 0.01
static-iterations = 1000
static-tolerance  = 0.001

relax-adapt-up     = 1.02
relax-adapt-down   = 1.1

static-outer-iterations = 1000

static-outer-relaxation = 0.98
static-outer-tolerance  = 0.01
static-initial-guess    = catenary
```

```
duration          = TF
ramp-time          = RAMPTIME
time-step          = DT
dynamic-relaxation = 0.95
dynamic-iterations = 500
dynamic-tolerance  = 1e-6
dynamic-rho        = -0.5
```

Environment

```
rho              = 1025
gravity          = 9.81
depth            = DEPTH
    bottom-elevation = 0
bottom-stiffness = 600
bottom-damping   = 20

x-current        = XCURRENT
x-wind           = XWIND

input-type = INPUT_TYPE
```

#ifdef WAVE_FOLLOWING

```
forcing-method = wave-follower
x-wave = (XWAVEAMP, XWAVEPERIOD, XWAVEDIR)
```

#endif

#ifdef VELOCITY_FORCING

```
forcing-method = velocity
z-input = (XWAVEAMP, XWAVEPERIOD, XWAVEDIR)
```

#endif

Buoys

```
atlas_buoy type = cylinder /*Based off of the TAO-C02 specs given by Taylor */
    m = 867
    d = 2
    h = 1
    buoyancy = 2542.4 /* kg */
    Cdn = 1.0    Cdt = 1.0
    Sw = 3.0    Cdw = 1.5 /* reduce area by 50% for ATLAS */
```

/* relative to 3-meter discus */

cce2_2_buoy type = cylinder

m = 1900

d = 2.3

h = 1

Cdn = 1.0

Cdt = 1.0

Cdw = 1.5

Sw = 2

/*Winded Surface Area, important for any surface probl

em (surface, deployment, etc.)*/

buoyancy = 4007 * 9.81

Anchors

clump

five_wheel_stack

Connectors

pivot

d = 0.01

/* to release moments - use segments mostly */

m = 0.01

wet = 0.01

Cdn = 0.0

length = 0.0

pivot2

d = 0.01

/* to release moments - use segments mostly */

m = 1.5

wet = 1.5 * 9.81

Cdn = 0.5

length = 0.2

Materials

Stretch_Hose

EA = 5e4

EI = 1000

GJ = 1.0

d = .078

Cdn = 0.5

Cdt = 0.5

wet = 9.8*3.94/2

m = 3.94 /*These are rough guesses */

type = nonlinear

T = 11675*e*e-25086*e*e*e+19235*e*e*e*e

Te = 2*11675*e-3*25086*e*e+4*19235*e*e*e

Tee = 2*11675-2*3*25086*e+3*4*19235*e*e

ESP_Assembly_ForCatenary

EA = 1e7

EI = 5e5

GJ = 1e5

m = 490/1.5

wet = 10/1.5

d = .762

Cdn = 0.5

Cdt = 0.5

/* Cat = .5

Can = 1.0 */

amt = 100/1.5

amn = 150/1.5

ESP_Assembly_ForTaut

EA = 1e7

EI = 5e5

GJ = 1e5

m = 730/1.5

wet = -1690/1.5

d = .762

Cdn = 0.5

Cdt = 0.5

/* Cat = .5

Can = 1.0 */

amt = 300/1.5

amn = 450/1.5

ESP_Can

EA = 1e7

EI = 5e5

GJ = 1e5

m = 235/0.85

wet = -1540/0.84

d = .762

Cdn = 0.5

Cdt = 0.5

Cat = .5

Can = 1.0

BatteryCase

EA = 1e+7

EI = 5e5

GJ = 1.0

m = 181.8/0.66

wet = 980/0.66

d = .91

Cdt = 0.5

Cdn = 0.5

Cat = .5

Can = 1.0

chain_5/8in EA = 9.2e+07 EI = 1e-4 GJ = 1e-4
m = 5 wet = 4.09 * 9.81
d = 0.0587 Cdt = 0.05 Cdn = 0.55
Cat = 0.1 Can = 1.0

chain_mr5/8in EA = 9.2e+07 EI = 1e-4 GJ = 1e-4
m = 5 wet = 4.35*9.81
d = 0.025 Cdt = 0.05 Cdn = 0.55
Cat = 0.1 Can = 1.0

adcp_frame EA = 1.0e8 EI = 4.508e+06 GJ = 2.25e+06
m = 25 wet = 245/1.4
d = 0.5 Cdt = 0.05 Cdn = 0.5
length = 1.4

nilspin_3/8in EA = 4.944e+06 EI = 1.0 GJ = 1.0
m = 0.412 wet = 3.04
d = 0.0127 Cdn = 1.5 Cdt = 0.005
Can = 1.0 Cat = 0.0

nylon_1in EA = 100084 EI = 0.01 GJ = 0.01
m = 0.214 wet = 0.2551
d = 0.0254 Cdn = 1.5 Cdt = 0.005
Can = 1.0 Cat = 0.0

depressor EA = 5.0e7 EI = 10000.0 GJ = 10000.0
m = 151.1820 wet = 1481.2577928
d = 0.290 Cdt = 0.01 Cdn = 1.0
Cmt = 1.26 Cmn = 2.0

single_release EA = 5.0e7 EI = 10000 GJ = 10000
m = 36 am=7.713 wet = 245
d = 0.5 Cdt = 1.0 Cdn = 1.0
Cat = 1.0 Can = 1.0
length = 1.0

nystron_1in EA = 748784 EI = 0.01 GJ = 0.01
m = 0.506 wet = 0.9614
d = 0.0254 Cdn = 1.5 Cdt = 0.005
Can = 1.0 Cat = 0.0

long_chain_3_4 EA = 5.0e7 EI = 10.0 GJ = 10.0
m = 6.6 wet = 56.3094
d = 0.066 Cdt = 0.006 Cdn = 0.5
Cmt = 1.1 Cmn = 2.0

short_chain_3_4 EA = 5.0e7 EI = 10.0 GJ = 10.0
m = 9.0 wet = 76.8123
d = 0.066 Cdt = 0.006 Cdn = 0.5
Cmt = 1.1 Cmn = 2.0

swivel_5T EA = 5.0e7 EI = 1000.0 GJ = 1000.0
m = 6.2/0.23 wet = 5.35/0.23 * 9.81
d = 0.1 Cdt = 1.2 Cdn = 1.2
length = 0.23

term_d EA = 5.0e7 EI = 1e-4 GJ = 1e-4
m = 12.694 wet = 107.922
d = 0.0805 Cdt = 0.05 Cdn = 0.55
Cat = 0.1 Can = 1.0
length = .26

```

chain_mr3/4in    EA = 9.2e+07    EI = 1e-4    GJ = 1e-4
                  m = 7.6        wet = 6.61*9.81
                  d = 0.03       Cdt = 0.05    Cdn = 0.55
                  Cat = 0.1      Can = 1.0

double_chain_mr3/4in    EA = 9.2e+07    EI = 1e-4    GJ = 1e-4
                        m = 7.6*2      wet = 6.61*9.81*2
                        d = 0.03*2     Cdt = 0.05*2    Cdn = 0.55*2
                        Cat = 0.1      Can = 1.0

sensor_cage       EA = 1.0e8    EI = 4.508e+06    GJ = 2.25e+06
                  m = 50/1.9        wet = 25/1.9*9.81
                  d = 0.5           Cdt = 0.05    Cdn = 0.5
                  /*length = 1.9*/

pig              EA = 5.0e7    EI = 10000.0    GJ = 10000.0
                m = 151.1820    wet = 100 * 9.81
                d = 0.290      Cdt = 0.01    Cdn = 1.0
                Cmt = 1.26    Cmn = 2.0

stud_chain_1in   EA = 9.2e+07    EI = 1e-4    GJ = 1e-4
                  m = 14.3827    wet = 12.51*9.81
                  d = 0.0905    Cdt = 0.05    Cdn = 0.55
                  Cat = 0.1      Can = 1.0

```

Layout

```

    terminal = {
        anchor = five_wheel_stack
    }

#ifdef CONFIG3 /*Taut mooring */
segment = {
    material = chain_mr3/4in
    length = 3
    nodes = (3, 1.0)
}

segment = {
    length = 85
    material = nilspin_3/8in
    nodes = (95, 1.0)
}

#else /* Chain Catenary Mooring (CONFIG1 or CONFIG2 or CONFIG4) */
segment = {
    material = chain_mr3/4in
    length = 90
    nodes = (90, 1.0)
}

connector = pivot2

segment = {
    length = 27.5
    material = stud_chain_1in
    nodes = (28, 1.0)
}

connector = pivot2

```

```
segment = {
    length = 20
    material = nystron_1in
    nodes = (20, 1.0)
}

connector = pivot2

segment = {
    length = 2
    material = chain_mr5/8in
    nodes = (6, 1.0)
}
#endif

connector = pivot2

segment = {
    material = single_release
    nodes = (3, 1.0)
}

#ifdef CONFIG3 /*Taut mooring */
connector = pivot2
segment = {
    length = 2
    material = chain_mr5/8in
    nodes = (3, 1.0)
}
#else /* Chain Catenary Mooring (CONFIG1 or CONFIG2 or CONFIG 4) */
connector = pivot2
segment = {
    length = 2
    material = chain_mr5/8in
    nodes = (3, 1.0)
}
#endif

connector = pivot2

segment = {
    length = 250
    material = nylon_1in
    nodes = (250, 1.0)
}

connector = pivot2

segment = {
    length = 270
    material = nilspin_3/8in
    nodes = (270, 1.0)
}

connector = pivot2

segment = {
    length = 110
    material = nilspin_3/8in
    nodes = (220, 1.0)
}
```

```
connector = pivot2
```

```
segment = {  
    length = 1.9  
    material = sensor_cage  
    nodes = (3, 1.0)  
}
```

```
segment = {  
    length = 23  
    material = nilspin_3/8in  
    nodes = (46, 1.0)  
}
```

```
connector = pivot2
```

```
segment = {  
    length = 1.9  
    material = sensor_cage  
    nodes = (3, 1.0)  
}
```

```
connector = pivot2
```

```
#ifdef CONFIG1  
    segment = {  
        length = 1.5  
        material = ESP_Assembly_ForCatenary  
        nodes = (4, 1.0)  
    }
```

```
    segment = {  
        length = 10  
        material = Stretch_Hose  
        nodes = (40, 1.0)  
    }
```

```
#endif
```

```
#ifdef CONFIG4  
    segment = {  
        length = 1.5  
        material = ESP_Assembly_ForTaut  
        nodes = (4, 1.0)  
    }
```

```
    segment = {  
        length = 10  
        material = Stretch_Hose  
        nodes = (40, 1.0)  
    }
```

```
#endif
```

```
#ifdef CONFIG2  
    segment = {  
        length = 1.5  
        material = ESP_Assembly_ForCatenary  
        nodes = (4, 1.0)  
    }
```

```
    segment = {  
        length = 15  
        material = EM_Chain  
        nodes = (30, 1.0)  
    }
```

```
#endif
```

```
#ifdef CONFIG3
```

```
    segment = {  
        length = 1.5  
        material = ESP_Assembly_ForTaut  
        nodes = (4, 1.0)  
    }
```

```
    segment = {  
        length = 8  
        material = Stretch_Hose  
        nodes = (32, 1.0)  
    }
```

```
#endif
```

```
    terminal = {  
        buoy = cce2_2_buoy  
    }
```

```
End
```