

```
#include "DelMar_hamilton_v1.spec"
```

Problem Description

```
title = TITLE
type  = surface
```

Analysis Parameters

```
static-relaxation = 0.1
static-iterations = 1000
static-tolerance  = 0.001

relax-adapt-up     = 1.02
relax-adapt-down   = 1.1

static-outer-iterations = 100

static-outer-relaxation = 0.98
static-outer-tolerance  = 0.01
static-initial-guess    = catenary

duration           = TF
ramp-time          = RAMPTIME
time-step          = DT
dynamic-relaxation = .95
dynamic-iterations = 1500
dynamic-tolerance  = 1e-6
dynamic-rho        = -0.5
```

Environment

```
rho           = 1025
gravity       = 9.81
depth        = DEPTH
bottom-stiffness = 600
bottom-damping  = 20
x-current     = XCURRENT
x-wind        = XWIND
```

```
input-type = INPUT_TYPE
```

#ifdef WAVE_FOLLOWING

```
forcing-method = wave-follower
x-wave = (XWAVEAMP, XWAVEPERIOD, XWAVEDIR)
#endif
```

#ifdef VELOCITY_FORCING

```
forcing-method = velocity
z-input = (XWAVEAMP, XWAVEPERIOD, XWAVEDIR)
#endif
```

Buoys

```
atlas_buoy  type = cylinder
            m = 245
            d = 2.3
            h = 1
            Cdn = 1.0   Cdt = 1.0
            Sw = 3.0    Cdw = 1.5 /* reduce area by 50% for ATLAS */
                                   /* relative to 3-meter discus */
geoce_buoy   type = cylinder
            m = 1475
            d = 2.3
            h = 1
```

```
Cdn = 1.0
Cdt = 1.0
buoyancy = 3400 * 9.81
```

```
del_mar_buoy    type = cylinder
m = 1500
d = 2.3
h = 1
Cdn = 1.0
Cdt = 1.0
/*buoyancy = 3403 * 9.81 */
```

f132_cage

```
type = sphere
m = 270
d = 2.1
Cdn = 0.47
Cdt = 0.47
buoyancy = 270
```

```
f145_cage       type = sphere
m = 380
d = 1.143
Cdn = 0.47
Cdt = 0.47
buoyancy = 308
```

```
f164_cage       type = sphere
m = 1300
d = 1.63
Cdn = 0.5
Cdt = 0.5
/* buoyancy = */
```

```
f164_cage_pilot type = sphere
m = 1300
d = 1.524
Cdn = 0.5
Cdt = 0.5
/* buoyancy = */
```

Anchors

```
five_wheel_stack
d = 0.8
Cdn = 1.0
Cdt = 1.0
/*wet = 4000*.454*9.81*/
wet = 2300*9.81
```

```
del_mar_anchor
d = 0.8
Cdn = 1.0
Cdt = 1.0
/*wet = 4000*.454*9.81*/
wet = 1250*9.81
```

Connectors

```
pivot          d = 0.3 /* to release moments - use segments mostly */
m = 1.5
wet = 1.5 * 9.81
```

Cdn = 0.5
length = 0.3
fl45 m = 380
d = 2.1
wet = -300 * 9.81
Cdn = 0.47

fl49
m = 580
d = 2.2
wet = -335 * 9.81
Cdn = 0.47

benthos_4m
m = 96
d = .5
wet = -88 * 9.81
Cdn = 0.47

length = 4
benthos_2m
m = 48
d = .5
wet = -44 * 9.81
Cdn = 0.47
length = 2

fl49_adcp m = 580
d = 2.4892
wet = -380 * 9.81
Cdn = 0.47
Cdt = 0.47

attachments

mc_im
m = 3.8
d = 0.075
length = .563
wet = 2.8 * 9.81
Cdn = 1.4
Cdt = .5

mcp_im
m = 3.8
d = 0.075
wet = 2.8 * 9.81
Cdn = 1.4
Cdt = .5
length = .563

icc
m = 2
d = .1
length = 0.2
wet = 1 * 9.81
Cdn = 1.4
Cdt = 1

sc_im
m = 10.7
d = 0.11
length = 0.8

```

      wet = 9.8 * 9.81
Cdn  = 1.4
      Cdt  = 1

```

Materials

```

Stretch_Hose EA = 5e4    EI = 1e4          GJ = 1.0
      d = .078      Cdn = 0.5      Cdt = 0.2
      wet = 9.8*3.94/2      m = 3.94 /*These are rough guesses */
type = nonlinear
T = 11675*e*e-25086*e*e*e+19235*e*e*e*e
Te = 2*11675*e-3*25086*e*e+4*19235*e*e*e
Tee = 2*11675-2*3*25086*e+3*4*19235*e*e

```

```

EM_Chain      EA = 1e+05      EI = 1000      GJ = 1e-4
      m = 3.5      wet = 1.*9.81
      d = 0.04      Cdt = 0.05      Cdn = 0.55
      Cat = 0.1      Can = 1.0

```

```

ESP_Assembly_ForCatenary EA = 1e7      EI = 5e5      GJ = 1e5
      m = 490/1.5      wet = 10/1.5
      d = .762      Cdn = 0.5      Cdt = 0.5
      /* Cat = .5      Can = 1.0 */
      amt = 100/1.5      amn = 150/1.5

```

```

ESP_Assembly_ForTaut EA = 1e7 EI = 5e5      GJ = 1e5
      m = 730/1.5      wet = -1690/1.5
      d = .762      Cdn = 0.5      Cdt = 0.5
      /* Cat = .5      Can = 1.0 */
      amt = 300/1.5      amn = 450/1.5

```

```

ESP_Can EA = 1e+7      EI = 5e6      GJ = 1.0
      d = .762      Cdn = 0.5      Cdt = 0.5
      wet = -1540/.84      m = 235/0.84
      /*wet = -400/.84      m = 235/0.84 */

```

```

BatteryCase EA = 1e+7      EI = 5e5      GJ = 1.0
      m = 181.8/0.66      wet = 980/0.66
      d = .91      Cdt = 0.5      Cdn = 0.5
      Cat = .5      Can = 1.0

```

```

float_chain_4m EA = 1.08e8      EI = 4.508e+06      GJ = 2.25e+06
      m = 96      am = 12      length = 4      wet = -88/4* 9.81
      d = 0.5      Cdt = 0.47      Cdn = 0.47

```

```

float_chain_2m EA = 1.08e8      EI = 4.508e+06      GJ = 2.25e+06
      m = 48      am = 6      length = 2      wet = -44/2* 9.81
      d = 0.5      Cdt = 0.47      Cdn = 0.47

```

```

float_chain_5m EA = 1.08e8      EI = 4.508e+06      GJ = 2.25e+06
      m = 48      am = 6      length = 2      wet = -112/5*9.81
      d = 0.5      Cdt = 0.47      Cdn = 0.47

```

```

chain_mr1/2in EA = 9.2e+07      EI = 20      GJ = 1e-4
      m = 3.5      wet = 3.04*9.81
      d = 0.02      Cdt = 0.05      Cdn = 0.55
      Cat = 0.1      Can = 1.0

```

```

chain_drop_1/2in EA = 9.2e+07      EI = 1e-4      GJ = 1e-4
      m = 7.8      wet = 6.8*9.81
      d = 0.04      length = 0.6      Cdt = 1.0

```

Cdn = 1.6

Cat = 0.1

Can = 1.0

chain_5/8in EA = 9.2e+07 EI = 1 GJ = 1e-4
 m = 6.070 wet = 51.7608
 d = 0.0587 Cdt = 0.05 Cdn = 0.55
 Cat = 0.1 Can = 1.0

adcp_frame EA = 1.0e8 EI = 4.508e+06 GJ = 2.25e+06
 m = 40/1.4 wet = 370/1.4
 d = 0.5 Cdt = 0.05 Cdn = 0.5
 length = 1.4

nilspin_3/8in EA = 4.944e+06 EI = 20.0 GJ = 1.0
 m = 0.446 wet = 3.109
 d = 0.0127 Cdn = 1.5 Cdt = 0.005
 Can = 1.0 Cat = 0.0

adcp_cage_up EA = 1.0e8 EI = 4.508e+06 GJ = 2.25e+06
 m = 100/1.9 wet = 45/2.2*9.81
 d = 0.18 Cdt = 0.9 Cdn = 1.3
 length = 2.2

adcp_cage_up_pilot EA = 1.0e8 EI = 4.508e+06 GJ = 2.25e+06
 m = 80/1.47 wet = 74/1.47*9.81
 d = 0.18 Cdt = 0.9 Cdn = 1.3
 length = 1.47

sensor_cage EA = 1.0e8 EI = 4.508e+06 GJ = 2.25e+06
 m = 50/1.9 wet = 25/1.9*9.81
 d = 0.5 Cdt = 0.05 Cdn = 0.5
 length = 1.9

sensor_cage_d_star EA = 1.0e8 EI = 4.508e+06 GJ = 2.25e+06
 m = 100/1.9 wet = 50/1.9*9.81
 d = 0.5 Cdt = 0.05 Cdn = 0.5
 length = 1.9

d_star EA = 1.0e8 EI = 4.508e+06 GJ = 2.25e+06
 m = 100/1.9 wet = 34.73/2.2*9.81
 d = 0.5 Cdt = 0.05 Cdn = 0.5
 length = 2.2

nilspin_3/16in EA = 4.944e+06 EI = 1.0 GJ = 1.0
 m = 0.106 wet = 0.0759*9.81
 d = 0.00635 Cdn = 1.2 Cdt = 0.005
 Can = 1.0 Cat = 0.0

nilspin_1/4in EA = 4.944e+06 EI = 1.0 GJ = 1.0
 m = 0.174 wet = 0.1314*9.81
 d = 0.00794 Cdn = 1.2 Cdt = 0.005
 Can = 1.0 Cat = 0.0

nylon_1in EA = 100084 EI = 0.01 GJ = 0.01
 m = 0.214 wet = 0.02648*9.81
 d = 0.020 Cdn = 1.2 Cdt = 0.005
 Can = 1.0 Cat = 0.0

dual_release EA = 5.0e7 EI = 10000 GJ = 10000
 m = 72/1.2 am=7.713/1.2 wet = 55/1.2*9.81
 d = 0.5 Cdt = 1.0 Cdn = 1.0
 Cat = 1.0 Can = 1.0
 length = 1.2

1/2

single_release EA = 5.0e7 EI = 10000 GJ = 10000
 m = 72/1.2/2 am=7.713/1.2/2 wet = 55/1.2*9.8
 d = 0.5 Cdt = 1.0 Cdn = 1.0
 Cat = 1.0 Can = 1.0
 length = 1.2

9.81

dual_release_pilot EA = 5.0e7 EI = 10000 GJ = 10000
 m = 72/1.2 am=7.713/1.2 wet = 154*.454/1.94*
 d = 0.5 Cdt = 1.0 Cdn = 1.0
 Cat = 1.0 Can = 1.0
 length = 1.94

depressor EA = 5.0e7 EI = 10000.0 GJ = 10000.0
 m = 520.0 wet = 889.64432
 d = 0.290 Cdt = 0.01 Cdn = 1.0
 Cmt = 1.26 Cmn = 2.0

del_mar_pig EA = 5.0e7 EI = 10000.0 GJ = 10000.0
 m = 100 wet = 100*9.81
 d = 0.290 Cdt = 0.01 Cdn = 1.0
 Cmt = 1.26 Cmn = 2.0

nystron_1in EA = 748784 EI = 0.01 GJ = 0.01
 m = 0.506 wet = 0.097957*9.81
 d = 0.026 Cdn = 1.2 Cdt = 0.005
 Can = 1.0 Cat = 0.0

long_chain_3_4 EA = 5.0e7 EI = 10.0 GJ = 10.0
 m = 6.35 wet = 5.74*9.81
 d = 0.066 Cdt = 0.006 Cdn = 0.5
 Cmt = 1.1 Cmn = 2.0

short_chain_3_4 EA = 5.0e7 EI = 10.0 GJ = 10.0
 m = 8.0 wet = 7.80*9.81
 d = 0.066 Cdt = 0.006 Cdn = 0.5
 Cmt = 1.1 Cmn = 2.0

swivel_3t EA = 5.0e7 EI = 1000.0 GJ = 1000.0
 m = 3.1 wet = 2.65*9.81
 d = 0.08 Cdt = 0.01 Cdn = 1.0
 Cmt = 1.18 Cmn = 2.0
 length = 0.5

swivel_5T EA = 5.0e7 EI = 1000.0 GJ = 1000.0
 m = 26.48/0.21 wet = 225.7/0.21
 d = 0.057 Cdt = 0.01 Cdn = 1.0
 Cmt = 1.18 Cmn = 2.0
 length = 0.21

```

term_d      EA = 5.0e7      EI = 1e-4      GJ = 1e-4
            m = 12.694
            d = 0.0805      Cdt = 0.05      wet = 107.922*9.81
            Cat = 0.1      Can = 1.0      Cdn = 0.55
            length = .26

chain_mr3/4in  EA = 9.2e+07      EI = 10      GJ = 1e-4
            m = 7.6
            d = 0.03      Cdt = 0.05      wet = 6.61*9.81
            Cat = 0.1      Can = 1.0      Cdn = 0.55

aquadopp_pilot EA = 1.0e8      EI = 4.508e+06      GJ = 2.25e+06
            m = 20/1
            d = 0.5      wet = 15.89/1*9.81
            length = 1      Cdt = 0.05      Cdn = 0.5

nylon_3/4in  EA = 56715      EI = 0.01      GJ = 0.01
            m = 0.2202      wet = 0.216
            d = 0.01905      Cdn = 1.5      Cdt = 0.005
            Can = 1.0      Cat = 0.0
            comment = "3/4 in nylon - Columbian Rope Corporation"

nilspin_5/16in EA = 3.434e+06      EI = 1.0      GJ = 1.0
            m = 0.3124      wet = 2.0867
            d = 0.0111      Cdn = 1.5      Cdt = 0.005
            Can = 1.0      Cat = 0.0
            comment = "Nilspin jacketed 5/16in wire rope (WRCA)"

```

Layout

```

terminal =
{
  anchor = del_mar_anchor
}

#ifdef CONFIG3 /*Taut mooring */
segment = {
  material = chain_mr3/4in
  length = 1
  nodes = (3, 1.0)
}

segment = {
  material = chain_mr3/4in
  length = 1
  nodes = (3, 1.0)
}

segment = {
  length = 4.5
  material = nilspin_3/8in
  nodes = (8, 1.0)
}

#else /* Chain Catenary Mooring (CONFIG 1 or CONFIG 2) */
segment = {
  material = chain_mr3/4in
  length = 24
  nodes = (48, 1.0)
}

segment =
{

```

```
length = 30
material = chain_5/8in
nodes = (60, 1.0)
}
connector = pivot

#ifdef CONFIG1
segment =
{
material = del_mar_pig
length = 1
nodes = (3, 1.0)
}
#endif
#ifdef CONFIG2
segment =
{
material = del_mar_pig
length = 2
nodes = (6, 1.0)
}
#endif

#endif

connector = pivot
segment =
{
material = swivel_5T
nodes = (2, 1.0)
}
connector = pivot

segment = {
length = 75
material = nilspin_3/8in
nodes = (75, 1.0)
/*attachments = icc : (2), mc_im : (3, 8, 13, 18, 23, 28, 38, 48, 58, 72), sc_im
: (33, 84)*/
}

connector = pivot
segment = {
length = 0.5
material = chain_mr3/4in
nodes = (3, 1.0)
}

#ifdef CONFIG1
segment = {
length = 1.5
material = ESP_Assembly_ForCatenary
nodes = (4, 1.0)
}

segment = {
length = 8.5
material = Stretch_Hose
nodes = (30, 1.0)
```

```
    }
#endif

#ifdef CONFIG2
    segment = {
        length = 1.5
        material = ESP_Assembly_ForCatenary
        nodes = (4, 1.0)
    }

    segment = {
        length = 13
        material = EM_Chain
        nodes = (30, 1.0)
    }

#endif

#ifdef CONFIG3
    segment = {
        length = 1.5
        material = ESP_Assembly_ForTaut
        nodes = (4, 1.0)
    }

    segment = {
        length = 9
        material = Stretch_Hose
        nodes = (32, 1.0)
    }

#endif

    terminal =
    {
        buoy = del_mar_buoy
    }

End
```

