

Ben Raanan

Week 30

- 300083 - DMO Support - LRAUV
- 600034 - Precision Control Technologies for ROVs and AUVs
- 708168 - DHS/LRAUV Under-Ice
- 901009 - CANON
- 901502 - Soundscape Research and Education
- 901513 - Targeted Sampling by Autonomous Underwater Vehicles
- 901910 - Plankton Taxonomic Groups from AUVs
- 902009 - AUV User Experience Design
- 902101 - LRAUV Technology Development and Fleet Operations
- 902102 - Multi-LRAUV Simulation Environment
- 902106 - Niobicon-Based AUV Docking Development
- 902204 - Scalable Marine Robotics Foundations
- DQ2032 - DOE Wave-Energy Control
- Overhead
- Out of Office

Week 29

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Week 20

- 300083 - DMO Support - LRAUV
 - Prep and support for Daphne and Pontus time-series deployments
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- 901513 - Targeted Sampling by Autonomous Underwater Vehicles
- 901910 - Plankton Taxonomic Groups from AUVs
- 902009 - AUV User Experience Design
 - 2023 abstract
- 902101 - LRAUV Technology Development and Fleet Operations
 - Supporting EcoHAB deployment in Santa Barbra
 - LRAUV video clip
 - Resolved network configuration issue on LRAUV backseat computers
- 902102 - Multi-LRAUV Simulation Environment
- 902106 - Niobicon-Based AUV Docking Development
- 902204 - Scalable Marine Robotics Foundations
 - Working on project update presentation
 - Testing 4D science data interpolation
 - Integrating simulation env with TethysDash
 - Integrating new battery simulation with LRAUV application
 - More work on DVL plugin
 - Intern project rampup

- DQ2032 - DOE Wave-Energy Control
- Overhead
 - SR committee
- Out of Office

Week 19

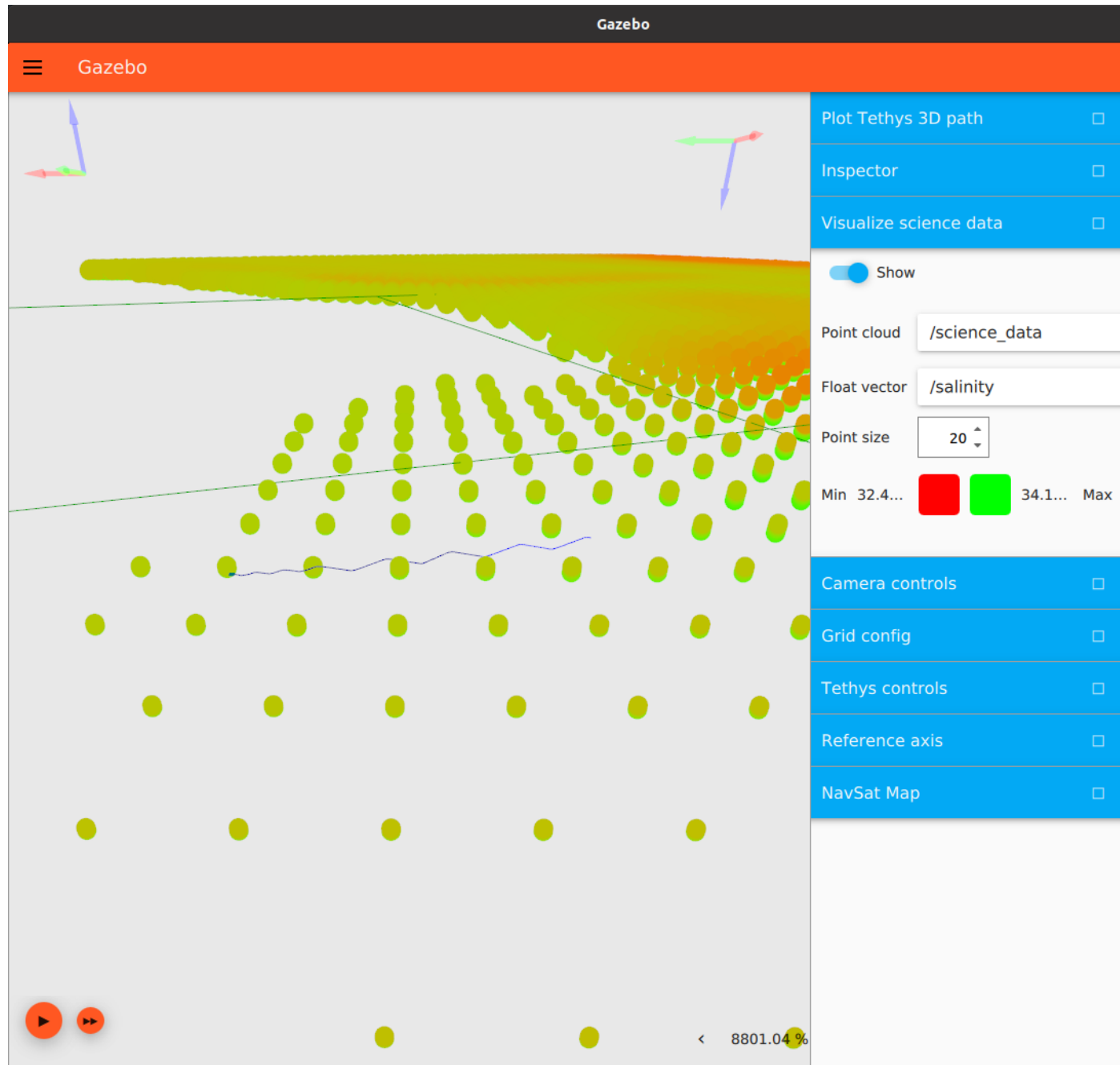
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- 902101 - LRAUV Technology Development and Fleet Operations
 - Prep for EcoHAB
- 902102 - Multi-LRAUV Simulation Environment
 - Integrating ROMs data from Santa Barbara to test EcoHAB scenarios ahead of the deployment
- 902106 - Niobicon-Based AUV Docking Development
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Week 18

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- 901910 - Plankton Taxonomic Groups from AUVs
- 902009 - AUV User Experience Design
- 902101 - LRAUV Technology Development and Fleet Operations
 - PR reviews
- 902102 - Multi-LRAUV Simulation Environment
 - Wrapping up data lookup/interp
 - [Acceptance testing — running multi-LRAUV targeted sampling tests with synthetic data](#)
 - Tethys (blue line): hover on chlorophyll max, trigger ESP water sample on a timer
 - Daphne (red line): acoustically track/circle Tethys while profiling the water column
 - Starting work on battery plugin
 - Starting work on DVL plugin
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Week 17

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- 901513 - Targeted Sampling by Autonomous Underwater Vehicles
- 901910 - Plankton Taxonomic Groups from AUVs
- 902009 - AUV User Experience Design
- 902101 - LRAUV Technology Development and Fleet Operations
- 902102 - Multi-LRAUV Simulation Environment
 - Acceptance tests with science data in the loop



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- Overhead

- Out of Office

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- Overhead
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 - 02/23-24
 - 04/4-7
 - 04/13-23

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 - 04/4-7
 - 04/13-23

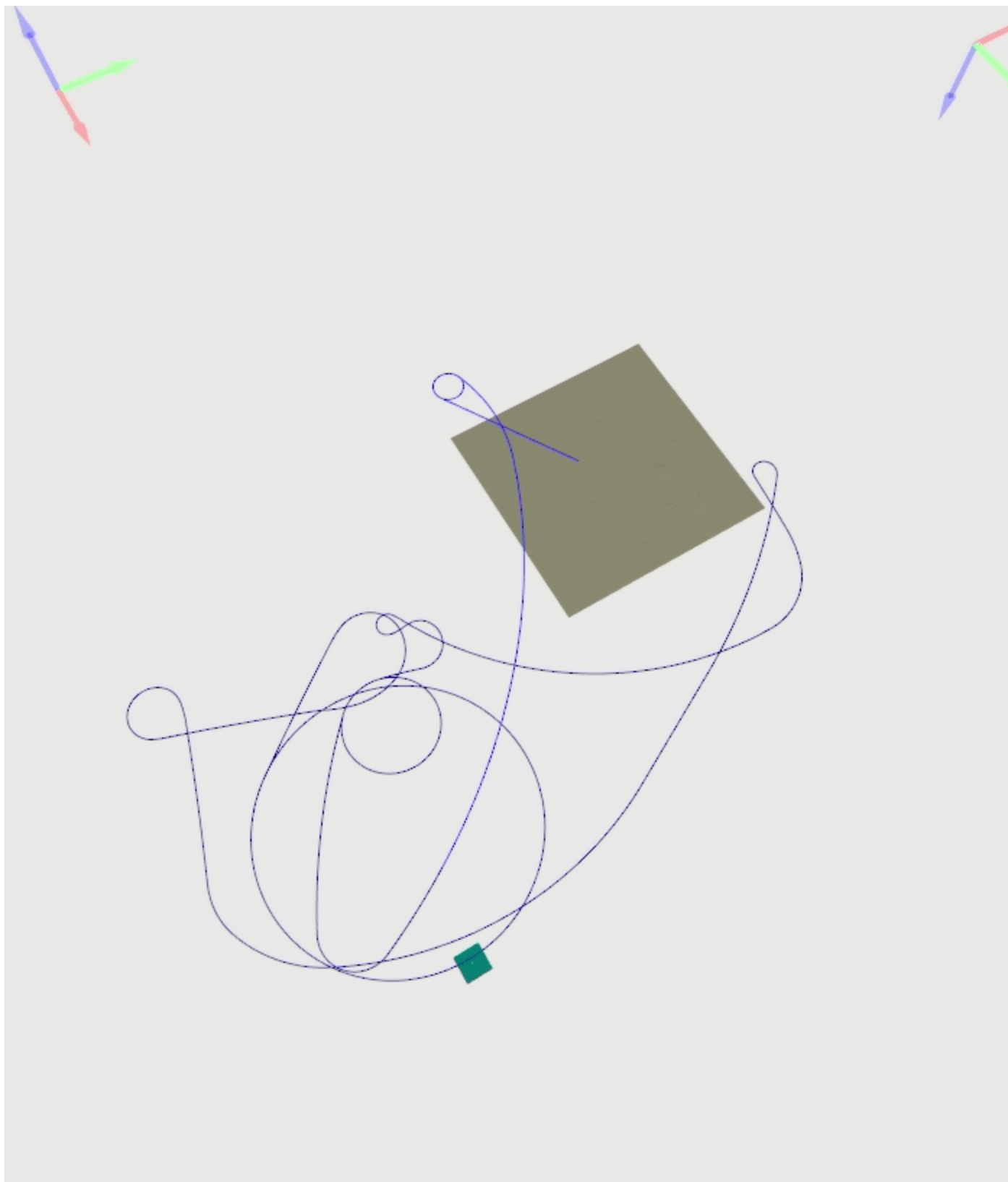
Week 14

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 - 02/23-24
 - 04/4-7
 - 04/13-23

Week 13

- 300083 - DMO Support - LRAUV
- 600034 - Precision Control Technologies for ROVs and AUVs
- 708168 - DHS/LRAUV Under-Ice
 - Docking development and analysis
- 901009 - CANON
- 901502 - Soundscape Research and Education
- 901513 - Targeted Sampling by Autonomous Underwater Vehicles
- 901910 - Plankton Taxonomic Groups from AUVs
- 902009 - AUV User Experience Design
- 902101 - LRAUV Technology Development and Fleet Operations
 - Tethys deployed for docking tests
 - Processing ROMs data from Santa Barbara for EcoHAB pre-deployment testing
- 902102 - Multi-LRAUV Simulation Environment
 - Added tiled DEM to the simulation environment



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- Acoustic tracking now working in the simulator
- Working to resolve issues with the science data interpolation
- 902106 - Niobicon-Based AUV Docking Development
- 902204 - Scalable Marine Robotics Foundations
- DQ2032 - DOE Wave-Energy Control
- Overhead
- Out of Office
 - 02/23-24
 - 04/4-7

- 04/13-23

Week 12

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 - 04/4-7
 - 04/13-23

Week 11

- 300083 - DMO Support - LRAUV
- 600034 - Precision Control Technologies for ROVs and AUVs
- 708168 - DHS/LRAUV Under-Ice
 - Recovered Tethys after docking sea-trials with the mock-dock. Ironed out some issues — docking success rate with the DAT is ~70%
- 901009 - CANON
- 901502 - Soundscape Research and Education
- 901513 - Targeted Sampling by Autonomous Underwater Vehicles
- 901910 - Plankton Taxonomic Groups from AUVs
- 902009 - AUV User Experience Design
- 902101 - LRAUV Technology Development and Fleet Operations
- 902102 - Multi-LRAUV Simulation Environment
 - Working on acceptance testing for the Q4
 - Test will include 2 vehicles
 - Vehicle 1 will simulate Chl patch tracking
 - Vehicle 2 will simulate acoustic tracking (track vehicle 1)
- 902106 - Niobicon-Based AUV Docking Development
- 902204 - Scalable Marine Robotics Foundations
- DQ2032 - DOE Wave-Energy Control
- Overhead
- Out of Office
 - 02/23-24
 - 04/4-7
 - 04/13-23

Week 10

- 300083 - DMO Support - LRAUV

- 600034 - Precision Control Technologies for ROVs and AUVs
- 708168 - DHS/LRAUV Under-Ice
 - Tethys deployed for docking tests. DAT noise has been an issue, but converging on a filtering approach that will allow line capture docking with reasonable success rates.
- 901009 - CANON
- 901502 - Soundscape Research and Education
- 901513 - Targeted Sampling by Autonomous Underwater Vehicles
- 901910 - Plankton Taxonomic Groups from AUVs
- 902009 - AUV User Experience Design
- 902101 - LRAUV Technology Development and Fleet Operations
 - Fixed additional issues with config set
- 902102 - Multi-LRAUV Simulation Environment
 - Updates in the lrauv-app to accommodate the new AHRS sensor model
 - Team is working on adding in digital elevation maps of Portuguese Ledge
 - Team is working on surface winds
 - Team is working on DVL plugin
 - Working on test plan for Q1
- 902106 - Niobicon-Based AUV Docking Development
- 902204 - Scalable Marine Robotics Foundations
- DQ2032 - DOE Wave-Energy Control
- Overhead
- Out of Office
 - 02/23-24
 - 04/4-7
 - 04/13-23

Week 9

- 300083 - DMO Support - LRAUV
- 600034 - Precision Control Technologies for ROVs and AUVs
- 708168 - DHS/LRAUV Under-Ice
 - Tethys deployed for docking testing (operations and data analysis)
- 901009 - CANON
- 901502 - Soundscape Research and Education
- 901513 - Targeted Sampling by Autonomous Underwater Vehicles
- 901910 - Plankton Taxonomic Groups from AUVs
- 902009 - AUV User Experience Design
- 902101 - LRAUV Technology Development and Fleet Operations
 - Fixed altitude following behavior (testing offshore)
 - Fixed configuration set bug
 - Fixed mission manager bug
 - Fixed minor bug in the acoustic tracking behavior
- 902102 - Multi-LRAUV Simulation Environment
 - Wrapping up surface buoyancy gradient
 - Added science data interpolation unit tests
 - Integrating new AHRS sensor model with LRAUV app
 - Starting work on adding digital elevation maps support
 - Started work on DVL plugin
- 902106 - Niobicon-Based AUV Docking Development
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Week 8

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- 901009 - CANON
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- 901513 - Targeted Sampling by Autonomous Underwater Vehicles
 - PR review
- 901910 - Plankton Taxonomic Groups from AUVs
- 902009 - AUV User Experience Design
- 902101 - LRAUV Technology Development and Fleet Operations
 - Docking sea trials with new proportional navigation guidance code
 - Resolved config set issue
 - Resolved mission manger issue
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- 902102 - Multi-LRAUV Simulation Environment
 - Integrated new acommms sim interface
 - Working on surface dynamics plug-ins
 - Devising Q1 test plan
- 902106 - Niobicon-Based AUV Docking Development
- 902204 - Scalable Marine Robotics Foundations
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- Overhead
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 - 04/13-23

Week 7

- 300083 - DMO Support - LRAUV
- 600034 - Precision Control Technologies for ROVs and AUVs
 - Tethys sea trial at Portuguese Ledge with TRN running on the backseat
- 708168 - DHS/LRAUV Under-Ice
 - Meetings and support for WHOI team
- 901009 - CANON
- 901502 - Soundscape Research and Education
- 901513 - Targeted Sampling by Autonomous Underwater Vehicles
 - Pull request review and sea trail prep
- 901910 - Plankton Taxonomic Groups from AUVs
- 902009 - AUV User Experience Design
- 902101 - LRAUV Technology Development and Fleet Operations
 - Major rehaul of terminal guidance stack using velocity based proportional navigation guidance law
 - Added single-pole IIR filter and median filter classes and integrated into the acoustic tracking stack
- 902102 - Multi-LRAUV Simulation Environment
 - Export control stuff

- Testing new acommms module
- Wrapping up new AHRS sensor model unit tests
- Wrapping up surface dynamics simulation
- Starting work on DVL sensor plugin
- Starting work on surface wind plugin
- Updating virtualization layer to use Rocker
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- 901513 - Targeted Sampling by Autonomous Underwater Vehicles
- 901910 - Plankton Taxonomic Groups from AUVs
- 902009 - AUV User Experience Design
 - Met with the SliceBread team for design review
- 902101 - LRAUV Technology Development and Fleet Operations
 - Terminal homing improvements — Resolved vehicle→navigation frame projection issue. Adding median and single pole IIR low-pass filtering on dock nav-frame projection and bearing rate calculation.
- 902102 - Multi-LRAUV Simulation Environment
 - Working on new acommms sim module, AHRS sensor model, surface simulation
- 902106 - Niobicon-Based AUV Docking Development
- 902204 - Scalable Marine Robotics Foundations
- DQ2032 - DOE Wave-Energy Control
 - Met with the team at Open Robotics for project kickoff
- Overhead
- Out of Office
 - 02/23-24
 - 04/4-7
 - 04/27-05/5

Week 5

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Week 2

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