

Tom O'Reilly Sorted By Project

300082 - DMO Support - Wave Glider

901101 - Seafloor Mapping

901112 - Monterey Bay Time Series

901513 - Targeted Sampling by AUVs

901902 - Unoccupied Aerial Vehicles for Science, Operations and Outreach

- (Week 4)
- Teams conducted coordinated surveys with our Trinity UAV and LRAUV last week off Terrace Point, UC Santa Cruz. Objective is to determine whether UAV and LRAUV can detect or measure any near-surface chemical/biological/physical features in common, using UAV's color and multispectral camera payloads and LRAUV's Piscivore and other sensors. These tests help us assess the UAV's potential role as "scout" for phenomena that can be examined in detail by surface/underwater vehicles. (Week 4)

902101 - LRAUV Technology Development

Out of Office

Overhead