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function [Q] = rr_action_bellman(alpha,beta,gamma,Rsearch,Rwait)
% RR_ACTION_BELLMAN - Seeks an iterative solution to the optimal Bellman equations for
the action-value function.
%
% Inputs:
%
% State Transition Probabilities:
%
% alpha = the probability that after searching with a "high" energy level we end with a
"high"
% beta = the probability that after searching with a "low" energy level we end with a
"low"
% gamma = the learning rate
%
% Recieved Rewards (Rsearch > Rwait):
%
% Rsearch = the reward given to searching
% Rwait = the reward given to waiting (Rwait <= Rsearch)
%
% See ePage 226-227 for the Bellman equation for the optimal state-value function  $Q^*(s)$ 
and
% the book solutions for the Bellman equation for the optimal action-value function
 $Q^*(s,a)$ .
%
% Written by:
% --
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%
% Please send comments and especially bug reports to the
% above email address.
%
%-----

if( nargin==0 )
    % State Transition Probabilities:
    %
    % the probability that after searching with a "high" energy level we end with a "high"
    alpha = 0.8;
    % the probability that after searching with a "low" energy level we end with a "low"
    beta = 0.2;
    % the learning rate:
    gamma = 0.9;

    % Recieved Rewards (Rsearch > Rwait):
    %
    Rsearch = 2.0; % <- the reward given to searching
    Rwait = 1.0; % <- the reward given to waiting
end

% Initialize our action-value function:
% state\action: search wait recharge
% high N.A.
% low
Q = zeros(2,3);
% some convience variables denoting states and actions:
h = 1; l = 2;
s = 1; w = 2; rc = 3;

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% some parameters for convergence:
%
MAX_N_ITERS = 100; iterCnt = 0;
CONV_TOL     = 1e-3; delta = 1e10;

while( (delta > CONV_TOL) && (iterCnt <= MAX_N_ITERS) )
    delta = 0;
    % update action states in the following order:
    %
    q = Q(h,s);
    Q(h,s) = Rsearch + alpha*gamma*max( [ Q(h,s), Q(h,w) ] ) + (1-alpha)*gamma*max( [
Q(l,s), Q(l,w), Q(l,rc) ] );
    delta = max( [ delta, abs( q-Q(h,s) ) ] );

    q = Q(h,w);
    Q(h,w) = Rwait + gamma*max( [ Q(h,s), Q(h,w) ] );
    delta = max( [ delta, abs( q-Q(h,w) ) ] );

    q = Q(l,s);
    Q(l,s) = (1-beta)*(-3 + gamma*max( [ Q(h,s), Q(h,w) ] ) ) + beta*( Rsearch + gamma*max(
[ Q(l,s), Q(l,w), Q(l,rc) ] ) );
    delta = max( [ delta, abs( q-Q(l,s) ) ] );

    q = Q(l,w);
    Q(l,w) = Rwait + gamma*max( [ Q(l,s), Q(l,w), Q(l,rc) ] );
    delta = max( [ delta, abs( q-Q(l,w) ) ] );

    q = Q(l,rc);
    Q(l,rc) = gamma*max( [ Q(h,s), Q(h,w) ] );
    delta = max( [ delta, abs( q-Q(l,rc) ) ] );

    %Q, delta
    iterCnt=iterCnt+1;
end

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